

DDR2 SDRAM SODIMM

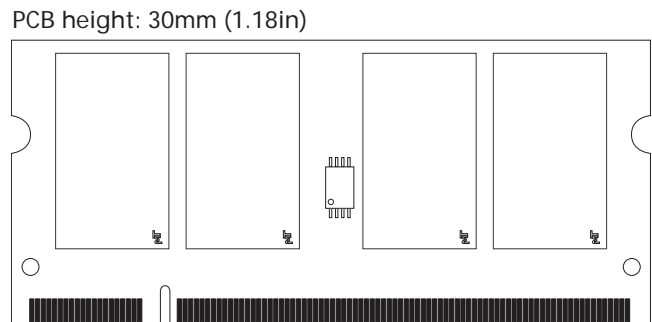
MT4HTF1664H – 128MB¹
 MT4HTF3264H – 256MB
 MT4HTF6464H – 512MB

For component data sheets, refer to Micron's Web site: www.micron.com

Features

- 200-pin, small-outline dual in-line memory module (SODIMM)
- Fast data transfer rates: PC2-3200, PC2-4200, PC2-5300, or PC2-6400
- 128MB (16 Meg x 64), 256MB (32 Meg x 64), and 512MB (64 Meg x 64)
- $V_{DD} = V_{DDQ} = +1.8V$
- $V_{DDSPD} = +1.7V$ to $+3.6V$
- JEDEC-standard 1.8V I/O (SSTL_18-compatible)
- Differential data strobe (DQS, DQS#) option
- 4n-bit prefetch architecture
- Single rank
- Multiple internal device banks for concurrent operation
- Programmable CAS latency (CL)
- Posted CAS additive latency (AL)
- WRITE latency = READ latency - 1 t_{CK}
- Programmable burst lengths (BL): 4 or 8
- Adjustable data-output drive strength
- 64ms, 8192-cycle refresh
- On-die termination (ODT)
- Serial presence-detect (SPD) with EEPROM
- Gold edge contacts

Figure 1: 200-Pin SODIMM (MO-224 R/C C)



Options

- Operating temperature²
 - Commercial ($0^{\circ}C \leq T_A \leq +70^{\circ}C$)
 - Industrial ($-40^{\circ}C \leq T_A \leq +85^{\circ}C$)
- Package
 - 200-pin DIMM (Pb-free)
- Frequency/CAS latency
 - 2.5ns @ CL = 5 (DDR2-800)
 - 2.5ns @ CL = 6 (DDR2-800)
 - 3.0ns @ CL = 5 (DDR2-667)
 - 3.75ns @ CL = 4 (DDR2-533)³
 - 5.0ns @ CL = 3 (DDR2-400)³

Marking

– Commercial ($0^{\circ}C \leq T_A \leq +70^{\circ}C$)	None
– Industrial ($-40^{\circ}C \leq T_A \leq +85^{\circ}C$)	I
– 200-pin DIMM (Pb-free)	Y
– 2.5ns @ CL = 5 (DDR2-800)	-80E
– 2.5ns @ CL = 6 (DDR2-800)	-800
– 3.0ns @ CL = 5 (DDR2-667)	-667
– 3.75ns @ CL = 4 (DDR2-533) ³	-53E
– 5.0ns @ CL = 3 (DDR2-400) ³	-40E

Notes: 1. End of life.

2. Contact Micron for industrial temperature module offerings.

3. Not recommended for new designs.

Table 1: Key Timing Parameters

Speed Grade	Industry Nomenclature	Data Rate (MT/s)				t _{RCD} (ns)	t _{RP} (ns)	t _{RC} (ns)
		CL = 6	CL = 5	CL = 4	CL = 3			
-80E	PC2-6400	–	800	533	–	12.5	12.5	55
-800	PC2-6400	800	667	533	–	15	15	55
-667	PC2-5300	–	667	533	400	15	15	55
-53E	PC2-4200	–	–	533	400	15	15	55
-40E	PC2-3200	–	–	400	400	15	15	55



Table 2: Addressing

Parameter	128MB	256MB	512MB
Refresh count	8K	8K	8K
Row address	8K A[12:0]	8K A[12:0]	8K A[12:0]
Device bank address	4 (BA0, BA1)	4 (BA0, BA1)	8 (BA0–BA2)
Device configuration	256Mb (16 Meg x 16)	512Mb (32 Meg x 16)	1Gb (64 Meg x 16)
Column address	512 A[8:0]	1K A[9:0]	1K A[9:0]
Module rank address	1 (S0#)	1 (S0#)	1 (S0#)

Table 3: Part Numbers and Timing Parameters – 128MB Modules

Base device: MT47H16M16,¹ 256Mb DDR2 SDRAM

Part Number ²	Module Density	Configuration	Module Bandwidth	Memory Clock/Data Rate	Clock Cycles (CL- ^t RCD- ^t RP)
MT4HTF1664HY-667__	128MB	16 Meg x 64	5.3 GB/s	3.0ns/667 MT/s	5-5-5
MT4HTF1664HY-53E__	128MB	16 Meg x 64	4.3 GB/s	3.75ns/533 MT/s	4-4-4
MT4HTF1664HY-40E__	128MB	16 Meg x 64	3.2 GB/s	5.0ns/400 MT/s	3-3-3

Table 4: Part Numbers and Timing Parameters – 256MB Modules

Base device: MT47H32M16,¹ 512Mb DDR2 SDRAM

Part Number ²	Module Density	Configuration	Module Bandwidth	Memory Clock/Data Rate	Clock Cycles (CL- ^t RCD- ^t RP)
MT4HTF3264H(I)Y-80E__	256MB	32 Meg x 64	6.4 GB/s	2.5ns/800 MT/s	5-5-5
MT4HTF3264H(I)Y-800__	256MB	32 Meg x 64	6.4 GB/s	2.5ns/800 MT/s	6-6-6
MT4HTF3264H(I)Y-667__	256MB	32 Meg x 64	5.3 GB/s	3.0ns/667 MT/s	5-5-5
MT4HTF3264H(I)Y-53E__	256MB	32 Meg x 64	4.3 GB/s	3.75ns/533 MT/s	4-4-4
MT4HTF3264H(I)Y-40E__	256MB	32 Meg x 64	3.2 GB/s	5.0ns/400 MT/s	3-3-3

Table 5: Part Numbers and Timing Parameters – 512MB Modules

Base device: MT47H64M16,¹ 1Gb DDR2 SDRAM

Part Number ²	Module Density	Configuration	Module Bandwidth	Memory Clock/Data Rate	Clock Cycles (CL- ^t RCD- ^t RP)
MT4HTF6464H(I)Y-80E__	512MB	64 Meg x 64	6.4 GB/s	2.5ns/800 MT/s	5-5-5
MT4HTF6464H(I)Y-800__	512MB	64 Meg x 64	6.4 GB/s	2.5ns/800 MT/s	6-6-6
MT4HTF6464H(I)Y-667__	512MB	64 Meg x 64	5.3 GB/s	3.0ns/667 MT/s	5-5-5
MT4HTF6464H(I)Y-53E__	512MB	64 Meg x 64	4.3 GB/s	3.75ns/533 MT/s	4-4-4
MT4HTF6464H(I)Y-40E__	512MB	64 Meg x 64	3.2 GB/s	5.0ns/400 MT/s	3-3-3

- Notes: 1. Data sheets for the base devices can be found on Micron's Web site.
 2. All part numbers end with a two-place code (not shown) that designates component and PCB revisions. Consult factory for current revision codes. Example: MT4HTF6464HY-667D3.



Pin Assignments and Descriptions

Table 6: Pin Assignments

200-Pin DDR2 SODIMM Front								200-Pin DDR2 SODIMM Back							
Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol		
1	V _{REF}	51	DQS2	101	A1	151	DQ42	2	V _{SS}	52	DM2	102	A0		
3	V _{SS}	53	V _{SS}	103	V _{DD}	153	DQ43	4	DQ4	54	V _{SS}	104	V _{DD}		
5	DQ0	55	DQ18	105	A10	155	V _{SS}	6	DQ5	56	DQ22	106	BA1		
7	DQ1	57	DQ19	107	BA0	157	DQ48	8	V _{SS}	58	DQ23	108	RAS#		
9	V _{SS}	59	V _{SS}	109	WE#	159	DQ49	10	DM0	60	V _{SS}	110	S0#		
11	DQS0#	61	DQ24	111	V _{DD}	161	V _{SS}	12	V _{SS}	62	DQ28	112	V _{DD}		
13	DQS0	63	DQ25	113	CAS#	163	NC	14	DQ6	64	DQ29	114	ODT0		
15	V _{SS}	65	V _{SS}	115	NC	165	V _{SS}	16	DQ7	66	V _{SS}	116	NC		
17	DQ2	67	DM3	117	V _{DD}	167	DQS6#	18	V _{SS}	68	DQS3#	118	V _{DD}		
19	DQ3	69	NC	119	NC	169	DQS6	20	DQ12	70	DQS3	120	NC		
21	V _{SS}	71	V _{SS}	121	V _{SS}	171	V _{SS}	22	DQ13	72	V _{SS}	122	V _{SS}		
23	DQ8	73	DQ26	123	DQ32	173	DQ50	24	V _{SS}	74	DQ30	124	DQ36		
25	DQ9	75	DQ27	125	DQ33	175	DQ51	26	DM1	76	DQ31	126	DQ37		
27	V _{SS}	77	V _{SS}	127	V _{SS}	177	V _{SS}	28	V _{SS}	78	V _{SS}	128	V _{SS}		
29	DQS1#	79	CKE0	129	DQS4#	179	DQ56	30	CK0	80	NC	130	DM4		
31	DQS1	81	V _{DD}	131	DQS4	181	DQ57	32	CK0#	82	V _{DD}	132	V _{SS}		
33	V _{SS}	83	NC	133	V _{SS}	183	V _{SS}	34	V _{SS}	84	NC	134	DQ38		
35	DQ10	85 ¹	NC/BA2	135	DQ34	185	DM7	36	DQ14	86	NC	136	DQ39		
37	DQ11	87	V _{DD}	137	DQ35	187	V _{SS}	38	DQ15	88	V _{DD}	138	V _{SS}		
39	V _{SS}	89	A12	139	V _{SS}	189	DQ58	40	V _{SS}	90	A11	140	DQ44		
41	V _{SS}	91	A9	141	DQ40	191	DQ59	42	V _{SS}	92	A7	142	DQ45		
43	DQ16	93	A8	143	DQ41	193	V _{SS}	44	DQ20	94	A6	144	V _{SS}		
45	DQ17	95	V _{DD}	145	V _{SS}	195	SDA	46	DQ21	96	V _{DD}	146	DQS5#		
47	V _{SS}	97	A5	147	DM5	197	SCL	48	V _{SS}	98	A4	148	DQS5		
49	DQS2#	99	A3	149	V _{SS}	199	V _{DDSPD}	50	NC	100	A2	150	V _{SS}		
												200	SA1		

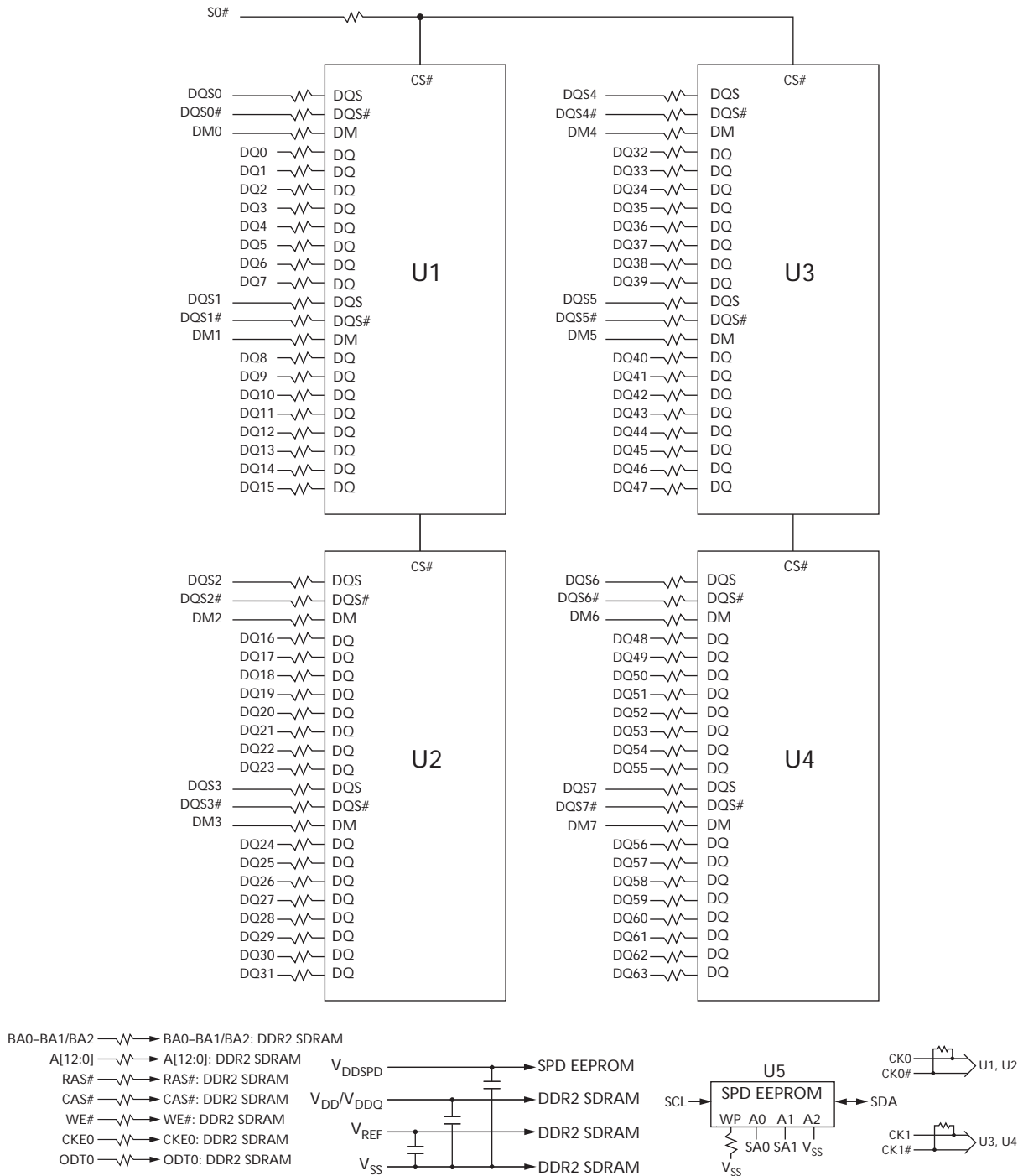
Notes: 1. Pin 85 is NC for 128MB and 256MB or BA2 for 512MB.

Table 7: Pin Descriptions

Symbol	Type	Description
A0–A12	Input	Address inputs: Provide the row address for ACTIVE commands, and the column address and auto precharge bit (A10) for READ/WRITE commands, to select one location out of the memory array in the respective bank. A10 sampled during a PRECHARGE command determines whether the PRECHARGE applies to one device bank (A10 LOW, device bank selected by BA0–BA1/BA2) or all device banks (A10 HIGH). The address inputs also provide the op-code during a LOAD MODE command.
BA0–BA2	Input	Bank address inputs: BA0–BA2 define the device bank to which an ACTIVE, READ, WRITE, or PRECHARGE command is being applied. BA0–BA2 define which mode register (MR, EMR, EMR2, and EMR3) is loaded during the LOAD MODE command. BA0, BA1 (128MB, 256MB) and BA0–BA2 (512MB).
CK0, CK0# CK1, CK1#	Input	Clock: CK and CK# are differential clock inputs. All control, command, and address input signals are sampled on the crossing of the positive edge of CK and the negative edge of CK#. Output data (DQ, DQS, and DQS#) is referenced to the crossings of CK and CK#.
CKE0	Input	Clock enable: CKE enables (registered HIGH) and disables (registered LOW) internal circuitry and clocks on the DDR2 SDRAM.
DM0–DM7	Input	Input data mask: DM is an input mask signal for write data. Input data is masked when DM is sampled HIGH, along with the input data, during a write access. DM is sampled on both edges of the DQS. Although the DM pins are input-only, the DM loading is designed to match that of the DQ and DQS pins.
ODT0	Input	On-die termination: ODT enables (registered HIGH) and disables (registered LOW) termination resistance internal to the DDR2 SDRAM. When enabled in normal operation, ODT is only applied to the following pins: DQ, DQS, DQS#, DM, and CB. The ODT input will be ignored if disabled via the LOAD MODE command.
RAS#, CAS#, WE#	Input	Command inputs: RAS#, CAS#, and WE# (along with S#) define the command being entered.
S0#	Input	Chip select: S# enables (registered LOW) and disables (registered HIGH) the command decoder.
SA0–SA1	Input	Serial address inputs: These pins are used to configure the SPD EEPROM address range on the I ² C bus.
SCL	Input	Serial clock for SPD EEPROM: SCL is used to synchronize communication to and from the SPD EEPROM.
DQ0–DQ63	I/O	Data input/output: Bidirectional data bus.
DQS0–DQS7, DQS0#–DQS7#	I/O	Data strobe: DQS# is only used when differential data strobe mode is enabled via the LOAD MODE command. Output with read data. Edge-aligned with read data. Input with write data for source-synchronous operation. Center-aligned with write data.
SDA	I/O	Serial data: SDA is a bidirectional pin used to transfer addresses and data into and out of the SPD EEPROM on the module on the I ² C bus.
V _{DD}	Supply	Power supply: +1.8V ±0.1V. The component V _{DD} and V _{DDQ} are connected to the module V _{DD} .
V _{DDSPD}	Supply	SPD EEPROM positive power supply: +1.7V to +3.6V.
V _{REF}	Supply	SSTL_18 reference voltage (V _{DD/2}).
V _{SS}	Supply	Ground.
NC	–	No connect: These pins are not connected on the module.

Functional Block Diagram

Figure 2: Functional Block Diagram



General Description

The MT4HTF1664H, MT4HTF3264H, and MT4HTF6464H DDR2 SDRAM modules are high-speed, CMOS dynamic random access 128MB, 256MB, and 512MB memory modules organized in a x64 configuration. These modules use 256Mb and 512Mb DDR2 SDRAM devices with four internal banks or a 1Gb DDR2 SDRAM device with eight internal banks.

DDR2 SDRAM modules use double data rate architecture to achieve high-speed operation. The double data rate architecture is essentially a $4n$ -prefetch architecture with an interface designed to transfer two data words per clock cycle at the I/O pins. A single read or write access for the DDR2 SDRAM module effectively consists of a single $4n$ -bit-wide, one-clock-cycle data transfer at the internal DRAM core and four corresponding n -bit-wide, one-half-clock-cycle data transfers at the I/O pins.

A bidirectional data strobe (DQS, DQS#) is transmitted externally, along with data, for use in data capture at the receiver. DQS is a strobe transmitted by the DDR2 SDRAM device during READs and by the memory controller during WRITEs. DQS is edge-aligned with data for READs and center-aligned with data for WRITEs.

DDR2 SDRAM modules operate from a differential clock (CK and CK#); the crossing of CK going HIGH and CK# going LOW will be referred to as the positive edge of CK. Clock, control, command, and address signals are registered at every positive edge of CK. Input data is registered on both edges of DQS, and output data is referenced to both edges of DQS, as well as to both edges of CK.

Serial Presence-Detect Operation

DDR2 SDRAM modules incorporate serial presence-detect. The SPD data is stored in a 256-byte EEPROM. The first 128 bytes are programmed by Micron to identify the module type and various SDRAM organizations and timing parameters. The remaining 128 bytes of storage are available for use by the customer. System READ/WRITE operations between the master (system logic) and the slave EEPROM device occur via a standard I²C bus using the DIMM's SCL (clock) and SDA (data) signals, together with SA[1:0], which provide four unique DIMM/EEPROM addresses. Write protect (WP) is connected to V_{SS}, permanently disabling hardware write protect.

Electrical Specifications

Stresses greater than those listed in Table 8 may cause permanent damage to the module. This is a stress rating only, and functional operation of the module at these or any other conditions outside those indicated in each device's data sheet is not implied. Exposure to absolute maximum rating conditions for extended periods may adversely affect reliability.

Table 8: Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Units	
V_{DD}/V_{DDQ}	V_{DD}/V_{DDQ} supply voltage relative to V_{SS}	-0.5	+2.3	V	
V_{IN}, V_{OUT}	Voltage on any pin relative to V_{SS}	-0.5	+2.3	V	
I_L	Input leakage current; Any input $0V \leq V_{IN} \leq V_{DD}$; V_{REF} input $0V \leq V_{IN} \leq 0.95V$ (All other pins not under test = 0V)	Address inputs, RAS#, CAS#, WE#, S#, CKE, ODT, BA	-20	+20	μA
		CK, CK#	-10	+10	
		DM	-5	+5	
I_{OZ}	Output leakage current; $0V \leq V_{OUT} \leq V_{DDQ}$; DQ and ODT are disabled	DQ, DQS, DQS#	-5	+5	μA
I_{VREF}	V_{REF} leakage current; V_{REF} = valid V_{REF} level		-8	+8	μA
T_A	Module ambient operating temperature	Commercial	0	+70	$^{\circ}C$
		Industrial	-40	+85	$^{\circ}C$
T_C^1	DDR2 SDRAM component case operating temperature ²	Commercial	0	+85	$^{\circ}C$
		Industrial	-40	+95	$^{\circ}C$

- Notes: 1. The refresh rate is required to double when $85^{\circ}C < T_C \leq 95^{\circ}C$.
2. For further information, refer to technical note [TN-00-08: "Thermal Applications,"](#) available on Micron's Web site.



DRAM Operating Conditions

Recommended AC operating conditions are given in the DDR2 component data sheets. Component specifications are available on Micron's Web site. Module speed grades correlate with component speed grades, as shown in Table 9.

Table 9: Module and Component Speed Grades
DDR2 components may exceed the listed module speed grades

Module Speed Grade	Component Speed Grade
-80E	-25E
-800	-25
-667	-3
-53E	-37E
-40E	-5E

Design Considerations

Simulations

Micron memory modules are designed to optimize signal integrity through carefully designed terminations, controlled board impedances, routing topologies, trace length matching, and decoupling. However, good signal integrity starts at the system level. Micron encourages designers to simulate the signal characteristics of the system's memory bus to ensure adequate signal integrity of the entire memory system.

Power

Operating voltages are specified at the DRAM, not at the edge connector of the module. Designers must account for any system voltage drops at anticipated power levels to ensure the required supply voltage is maintained.

I_{DD} Specifications

Table 10: DDR2 I_{DD} Specifications and Conditions – 128MB

Values are for the MT47H16M16 DDR2 SDRAM only and are computed from values specified in the 256Mb (16 Meg x 16) component data sheet

Parameter/Condition	Symbol	-667	-53E	-40E	Units	
Operating one bank active-precharge current: $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD0}	360	320	300	mA	
Operating one bank active-read-precharge current: I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data pattern is the same as I _{DD4W}	I _{DD1}	400	360	340	mA	
Precharge power-down current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I _{DD2P}	20	20	20	mA	
Precharge quiet standby current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, S# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating	I _{DD2Q}	200	140	100	mA	
Precharge standby current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, S# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD2N}	160	140	120	mA	
Active power-down current: All device banks open; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	Fast PDN exit MR[12] = 0	I _{DD3Pf}	120	100	80	mA
	Slow PDN exit MR[12] = 1	I _{DD3Ps}	24	24	24	mA
Active standby current: All device banks open; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD3N}	220	160	120	mA	
Operating burst write current: All device banks open; Continuous burst writes; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD4W}	860	720	560	mA	
Operating burst read current: All device banks open; Continuous burst reads; I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD4R}	760	640	480	mA	
Burst refresh current: $t_{CK} = t_{CK}(I_{DD})$; REFRESH command at every $t_{RFC}(I_{DD})$ interval; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD5}	720	680	660	mA	
Self refresh current: CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating	I _{DD6}	20	20	20	mA	
Operating bank interleave read current: All device banks interleaving reads; I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = $t_{RCD}(I_{DD}) - 1 \times t_{CK}(I_{DD})$; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RRD} = t_{RRD}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching	I _{DD7}	1040	960	920	mA	

Table 11: DDR2 I_{DD} Specifications and Conditions – 256MB

Values are for the MT47H32M16 DDR2 SDRAM only and are computed from values specified in the 512Mb (32 Meg x 16) component data sheet

Parameter/Condition	Symbol	-80E/ -800	-667	-53E	-40E	Units	
Operating one bank active-precharge current: $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD0}	540	480	440	440	mA	
Operating one bank active-read-precharge current: I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data pattern is the same as I _{DD4W}	I _{DD1}	660	600	540	520	mA	
Precharge power-down current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I _{DD2P}	28	28	28	28	mA	
Precharge quiet standby current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, S# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating	I _{DD2Q}	260	260	220	180	mA	
Precharge standby current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, S# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD2N}	280	280	240	200	mA	
Active power-down current: All device banks open; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	Fast PDN exit MR[12] = 0	I _{DD3Pf}	160	140	120	100	mA
	Slow PDN exit MR[12] = 1	I _{DD3Ps}	48	48	48	48	mA
Active standby current: All device banks open; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD3N}	300	280	240	200	mA	
Operating burst write current: All device banks open; Continuous burst writes; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD4W}	1180	1000	820	640	mA	
Operating burst read current: All device banks open; Continuous burst reads; I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD4R}	1100	940	780	620	mA	
Burst refresh current: $t_{CK} = t_{CK}(I_{DD})$; REFRESH command at every $t_{RFC}(I_{DD})$ interval; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD5}	920	740	700	680	mA	
Self refresh current: CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating	I _{DD6}	28	28	28	28	mA	
Operating bank interleave read current: All device banks interleaving reads; I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = $t_{RCD}(I_{DD}) - 1 \times t_{CK}(I_{DD})$; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RRD} = t_{RRD}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching	I _{DD7}	1480	1400	1360	1360	mA	

Table 12: DDR2 I_{DD} Specifications and Conditions (Die Revision A) – 512MB

Values are for the MT47H64M16 DDR2 SDRAM only and are computed from values specified in the 1Gb (64 Meg x 16) component data sheet

Parameter/Condition	Symbol	-667	-53E	-40E	Units	
Operating one bank active-precharge current: $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD0}	540	440	440	mA	
Operating one bank active-read-precharge current: I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data pattern is the same as I _{DD4W}	I _{DD1}	520	480	460	mA	
Precharge power-down current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I _{DD2P}	28	28	28	mA	
Precharge quiet standby current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, S# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating	I _{DD2Q}	260	180	160	mA	
Precharge standby current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, S# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD2N}	280	200	160	mA	
Active power-down current: All device banks open; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	Fast PDN exit MR[12] = 0	I _{DD3Pf}	160	140	140	mA
	Slow PDN exit MR[12] = 1	I _{DD3Ps}	72	72	72	mA
Active standby current: All device banks open; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD3N}	300	240	220	mA	
Operating burst write current: All device banks open; Continuous burst writes; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD4W}	840	720	640	mA	
Operating burst read current: All device banks open; Continuous burst reads; I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD4R}	880	720	640	mA	
Burst refresh current: $t_{CK} = t_{CK}(I_{DD})$; REFRESH command at every $t_{RFC}(I_{DD})$ interval; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD5}	1080	1000	960	mA	
Self refresh current: CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating	I _{DD6}	28	28	28	mA	
Operating bank interleave read current: All device banks interleaving reads; I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = $t_{RCD}(I_{DD}) - 1 \times t_{CK}(I_{DD})$; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RRD} = t_{RRD}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching	I _{DD7}	1400	1360	1320	mA	

Table 13: DDR2 I_{DD} Specifications and Conditions (Die Revision E) – 512MB

Values are for the MT47H64M16 DDR2 SDRAM only and are computed from values specified in the 1Gb (64 Meg x 16) component data sheet

Parameter/Condition	Symbol	-80E/ -800	-667	-53E	-40E	Units	
Operating one bank active-precharge current: $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD0}	600	540	440	440	mA	
Operating one bank active-read-precharge current: I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RAS} = t_{RAS\ MIN}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data pattern is the same as I _{DD4W}	I _{DD1}	700	520	480	460	mA	
Precharge power-down current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I _{DD2P}	28	28	28	28	mA	
Precharge quiet standby current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, S# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating	I _{DD2Q}	300	260	180	160	mA	
Precharge standby current: All device banks idle; $t_{CK} = t_{CK}(I_{DD})$; CKE is HIGH, S# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD2N}	320	280	200	160	mA	
Active power-down current: All device banks open; $t_{CK} = t_{CK}(I_{DD})$; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	Fast PDN exit MR[12] = 0	I _{DD3P}	160	160	140	140	mA
	Slow PDN exit MR[12] = 1	I _{DD3Ps}	40	40	40	56	mA
Active standby current: All device banks open; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD3N}	340	300	240	220	mA	
Operating burst write current: All device banks open; Continuous burst writes; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD4W}	1260	800	720	640	mA	
Operating burst read current: All device banks open; Continuous burst reads; I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = 0; $t_{CK} = t_{CK}(I_{DD})$, $t_{RAS} = t_{RAS\ MAX}(I_{DD})$, $t_{RP} = t_{RP}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I _{DD4R}	1280	880	720	640	mA	
Burst refresh current: $t_{CK} = t_{CK}(I_{DD})$; REFRESH command at every $t_{RFC}(I_{DD})$ interval; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I _{DD5}	1120	1080	1000	960	mA	
Self refresh current: CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating	I _{DD6}	28	28	28	28	mA	
Operating bank interleave read current: All device banks interleaving reads; I _{OUT} = 0mA; BL = 4, CL = CL(I _{DD}), AL = $t_{RCD}(I_{DD}) - 1 \times t_{CK}(I_{DD})$; $t_{CK} = t_{CK}(I_{DD})$, $t_{RC} = t_{RC}(I_{DD})$, $t_{RRD} = t_{RRD}(I_{DD})$, $t_{RCD} = t_{RCD}(I_{DD})$; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching	I _{DD7}	1760	1400	1320	1320	mA	

Serial Presence-Detect

Table 14: Serial Presence-Detect EEPROM DC Operating Conditions

Parameter/Condition	Symbol	Min	Max	Units
Supply voltage	V_{DDSPD}	1.7	3.6	V
Input high voltage: Logic 1; All inputs	V_{IH}	$V_{DDSPD} \times 0.7$	$V_{DDSPD} + 0.5$	V
Input low voltage: Logic 0; All inputs	V_{IL}	-0.6	$V_{DDSPD} \times 0.3$	V
Output low voltage: $I_{OUT} = 3mA$	V_{OL}	-	0.4	V
Input leakage current: $V_{IN} = GND$ to V_{DD}	I_{LI}	0.10	3.0	μA
Output leakage current: $V_{OUT} = GND$ to V_{DD}	I_{LO}	0.05	3.0	μA
Standby current	I_{SB}	1.6	4.0	μA
Power supply current, READ: SCL clock frequency = 100 kHz	I_{CCR}	0.4	1.0	mA
Power supply current, WRITE: SCL clock frequency = 100 kHz	I_{CCW}	2.0	3.0	mA

Table 15: Serial Presence-Detect EEPROM AC Operating Conditions

Parameter/Condition	Symbol	Min	Max	Units	Notes
SCL LOW to SDA data-out valid	t_{AA}	0.2	0.9	μs	1
Time the bus must be free before a new transition can start	t_{BUF}	1.3	-	μs	
Data-out hold time	t_{DH}	200	-	ns	
SDA fall time	t_F	-	300	ns	2
SDA rise time	t_R	-	300	ns	2
Data-in hold time	$t_{HD:DAT}$	0	-	μs	
Start condition hold time	$t_{H:STA}$	0.6	-	μs	
Clock HIGH period	t_{HIGH}	0.6	-	μs	
Noise suppression time constant at SCL, SDA inputs	t_I	-	50	ns	
Clock LOW period	t_{LOW}	1.3	-	μs	
SCL clock frequency	f_{SCL}	-	400	kHz	
Data-in setup time	$t_{SU:DAT}$	100	-	ns	
Start condition setup time	$t_{SU:STA}$	0.6	-	μs	3
Stop condition setup time	$t_{SU:STO}$	0.6	-	μs	
WRITE cycle time	t_{WRC}	-	10	ms	4

- Notes: 1. To avoid spurious start and stop conditions, a minimum delay is placed between SCL = 1 and the falling or rising edge of SDA.
2. This parameter is sampled.
3. For a restart condition or following a WRITE cycle.
4. The SPD EEPROM WRITE cycle time (t_{WRC}) is the time from a valid stop condition of a write sequence to the end of the EEPROM internal ERASE/PROGRAM cycle. During the WRITE cycle, the EEPROM bus interface circuit is disabled, SDA remains HIGH due to pull-up resistance, and the EEPROM does not respond to its slave address.

Serial Presence-Detect Data

For the latest serial presence-detect data, refer to Micron's SPD page:
www.micron.com/SPD.

