# MC9S08PL4

# MC9S08PL4 Series Data Sheet

#### Supports: MC9S08PL4 Key features

- 8-Bit S08 central processor unit (CPU)
  - Up to 20 MHz bus at 2.7 V to 5.5 V across temperature range of -40 °C to 85 °C
  - Supporting up to 40 interrupt/reset sources
  - Supporting up to four-level nested interrupt
  - On-chip memory
  - Up to 4 KB flash read/program/erase over full operating voltage and temperature
  - Up to 128 byte EEPROM; 2-byte erase sector; program and erase while executing flash
  - Up to 512 byte random-access memory (RAM)
  - Flash and RAM access protection
- · Power-saving modes
  - One low-power stop mode; reduced power wait mode
  - Peripheral clock enable register can disable clocks to unused modules, reducing currents; allows clocks to remain enabled to specific peripherals in stop3 mode
- Clocks
  - Oscillator (XOSC) loop-controlled Pierce oscillator; crystal or ceramic resonator range of 31.25 kHz to 39.0625 kHz or 4 MHz to 20 MHz
  - Internal clock source (ICS) containing a frequencylocked-loop (FLL) controlled by internal or external reference; precision trimming of internal reference allowing 1% deviation across temperature range of 0 °C to 70 °C and 2% deviation across whole operating temperature range; up to 20 MHz
- System protection
  - Watchdog with independent clock source
  - Low-voltage detection with reset or interrupt; selectable trip points
  - Illegal opcode detection with reset
  - Illegal address detection with reset

- Development support
  - Single-wire background debug interface
  - Breakpoint capability to allow three breakpoints setting during in-circuit debugging
  - On-chip in-circuit emulator (ICE) debug module containing two comparators and nine trigger modes
- Peripherals
  - ACMP one analog comparator with both positive and negative inputs; separately selectable interrupt on rising and falling comparator output; filtering
  - ADC 8-channel, 10-bit resolution; 2.5 µs conversion time; data buffers with optional watermark; automatic compare function; internal bandgap reference channel; operation in stop mode; optional hardware trigger
  - FTM two 2-channel flex timer modulators modules; 16-bit counter; each channel can be configured for input capture, output compare, edgeor center-aligned PWM mode
  - RTC 16-bit real timer counter (RTC)
  - SCI one serial communication interface (SCI/ UART) modules optional 13-bit break; full duplex non-return to zero (NRZ); LIN extension support
- Input/Output
  - Up to 18 GPIOs including one output-only pin
  - One 8-bit keyboard interrupt module (KBI)
- Package options
  - 20-pin TSSOP
  - 16-pin TSSOP
  - 8-pin SOIC

NXP reserves the right to change the production detail specifications as may be required to permit improvements in the design of its products.



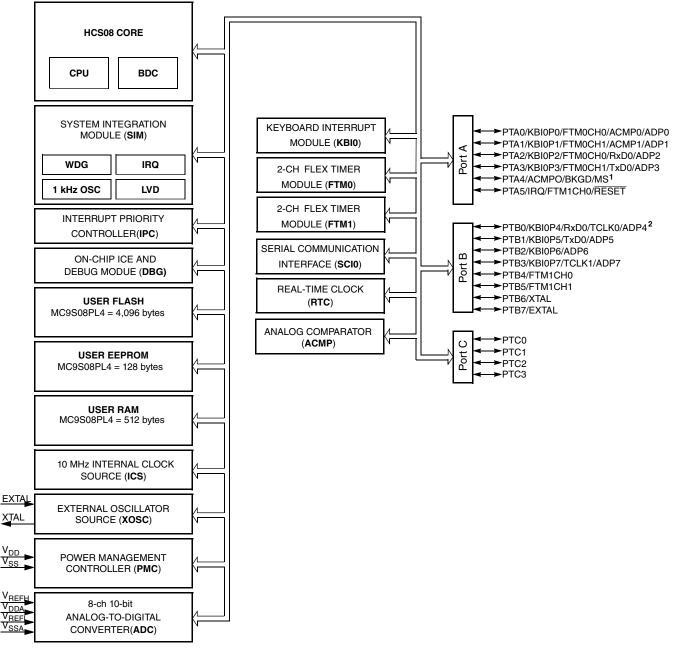
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# 1 MCU block diagram

The block diagram below shows the structure of the MCUs.



1. PTA4/ACMPO/BKGD/MS is an output-only pin when used as port pin.

2. PTB0 operates as true-open drain when working as output.

Figure 1. MCU block diagram

# 2 Orderable part numbers

The following table summarizes the part numbers of the devices covered by this document.

| Part Number          |          | MC9S08PL4 |         |
|----------------------|----------|-----------|---------|
|                      | СТЈ      | CTG       | CSC     |
| Max. frequency (MHz) | 20       | 20        | 20      |
| Flash memory (KB)    | 4        | 4         | 4       |
| RAM (KB)             | 0.512    | 0.512     | 0.512   |
| EEPROM (B)           | 128      | 128       | 128     |
| 10-bit ADC           | 8ch      | 8ch       | 4ch     |
| ACMP                 | 1        | 1         | 1       |
| 16-bit FlexTimer     | 2ch+2ch  | 2ch+2ch   | 2ch+1ch |
| RTC                  | Yes      | Yes       | Yes     |
| SCI (LIN Capable)    | 1        | 1         | 1       |
| Watchdog             | Yes      | Yes       | Yes     |
| CRC                  | -        | -         | -       |
| KBI pins             | 8        | 8         | 4       |
| GPIO                 | 18       | 14        | 6       |
| Package              | 20-TSSOP | 16-TSSOP  | 8-SOIC  |

Table 1. Ordering information

# 3 Part identification

### 3.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

### 3.2 Format

Part numbers for this device have the following format:

MC 9 S08 PL AA B CC

# 3.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

| Field | Description                      | Values  |
|-------|----------------------------------|---|
| MC    | Qualification status             | MC = fully qualified, general market flow                                     |
| 9     | Memory                           | • 9 = flash based   |
| S08   | Core                             | • S08 = 8-bit CPU   |
| PL    | Device family                    | • PL  |
| AA    | Approximate flash size in KB     | • 4 = 4 KB  |
| В     | Operating temperature range (°C) | • C = -40 to 85   |
| СС    | Package designator               | <ul> <li>TJ = 20-TSSOP</li> <li>TG = 16-TSSOP</li> <li>SC = 8-SOIC</li> </ul> |

### 3.4 Example

This is an example part number:

MC9S08PL4CTJ

# 4 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding, the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

#### Table 2. Parameter Classifications

| Р | Those parameters are guaranteed during production testing on each individual device.   |
|---|--|
| С | Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.  |
| Т | Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category. |
| D | Those parameters are derived mainly from simulations.  |

### NOTE

The classification is shown in the column labeled "C" in the parameter tables where appropriate.

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# 5 Ratings

# 5.1 Thermal handling ratings

| Symbol           | Description                                    | Min. | Max. | Unit | Notes |
|------------------|--|------|------|------|-------|
| T <sub>STG</sub> | Storage temperature                            | -55  | 150  | °C   | 1     |
| T <sub>SDR</sub> | T <sub>SDR</sub> Solder temperature, lead-free |      | 260  | °C   | 2     |

1. Determined according to JEDEC Standard JESD22-A103, High Temperature Storage Life.

2. Determined according to IPC/JEDEC Standard J-STD-020, Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices.

# 5.2 Moisture handling ratings

| Symbol | Description                | Min. | Max. | Unit | Notes |
|--------|----------------------------|------|------|------|-------|
| MSL    | Moisture sensitivity level | —    | 3    | _    | 1     |

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

# 5.3 ESD handling ratings

| Symbol           | Description   | Min.  | Max.  | Unit | Notes |
|------------------|---|-------|-------|------|-------|
| V <sub>HBM</sub> | Electrostatic discharge voltage, human body model     | -6000 | +6000 | V    | 1     |
| V <sub>CDM</sub> | Electrostatic discharge voltage, charged-device model | -500  | +500  | V    | 2     |
| I <sub>LAT</sub> | Latch-up current at ambient temperature of 85         | -100  | +100  | mA   |       |

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.

2. Determined according to JEDEC Standard JESD22-C101, Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components.

### 5.4 Voltage and current operating ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in below table may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this document.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either  $V_{SS}$  or  $V_{DD}$ ) or the programmable pullup resistor associated with the pin is enabled.

| Symbol   | Description  | Min.                  | Max.                  | Unit |
|--|--|-----------------------|-----------------------|------|
| V <sub>DD</sub>  | Supply voltage   | -0.3                  | 6.0                   | V    |
| I <sub>DD</sub>  | Maximum current into V <sub>DD</sub>                                       | _                     | 120                   | mA   |
| V <sub>DIO</sub>   | Digital input voltage (except RESET, EXTAL, XTAL, or true open drain pin ) | -0.3                  | V <sub>DD</sub> + 0.3 | V    |
|  | Digital input voltage (true open drain pin )                               | -0.3                  | 6                     | V    |
| V <sub>AIO</sub>   | Analog <sup>1</sup> , RESET, EXTAL, and XTAL input voltage                 | -0.3                  | V <sub>DD</sub> + 0.3 | V    |
| I <sub>D</sub> Instantaneous maximum current single pin limit (applies to all port pins) |  | -25                   | 25                    | mA   |
| V <sub>DDA</sub>   | Analog supply voltage  | V <sub>DD</sub> – 0.3 | V <sub>DD</sub> + 0.3 | V    |

1. All digital I/O pins, except open-drain pin , are internally clamped to  $V_{SS}$  and  $V_{DD}$ . is only clamped to  $V_{SS}$ .

# 6 General

# 6.1 Nonswitching electrical specifications

### 6.1.1 DC characteristics

This section includes information about power supply requirements and I/O pin characteristics.

| Symbol           | С |                        | Descriptions                              |                                     | Min                   | Typical <sup>1</sup> | Мах  | Unit |
|------------------|---|------------------------|---|-------------------------------------|-----------------------|----------------------|------|------|
| —                | _ | Oper                   | rating voltage                            | —                                   | 2.7                   | —                    | 5.5  | V    |
| V <sub>OH</sub>  | С | Output high<br>voltage | All I/O pins, standard-<br>drive strength | 5 V, I <sub>load</sub> =<br>-5 mA   | V <sub>DD</sub> - 0.8 |                      |      | V    |
|                  | С |                        |   | 3 V, I <sub>load</sub> =<br>-2.5 mA | V <sub>DD</sub> - 0.8 | —                    | —    | V    |
| I <sub>OHT</sub> | D | Output high            | Max total I <sub>OH</sub> for all         | 5 V                                 | —                     | —                    | -100 | mA   |
|                  |   | current                | ports                                     | 3 V                                 | —                     | _                    | -50  |      |
| V <sub>OL</sub>  | С | Output low<br>voltage  | All I/O pins, standard-<br>drive strength | 5 V, I <sub>load</sub> = 5<br>mA    |                       |                      | 0.8  | V    |

Table 3. DC characteristics

Table continues on the next page...

| Symbol                       | С |  | Descriptions  |                                    | Min                  | Typical <sup>1</sup> | Max                  | Unit |
|------------------------------|---|--|---|------------------------------------|----------------------|----------------------|----------------------|------|
|                              | С |  |   | 3 V, I <sub>load</sub> =<br>2.5 mA | _                    | _                    | 0.8                  | V    |
| I <sub>OLT</sub>             | D | Output low   | Max total I <sub>OL</sub> for all                                     | 5 V                                | _                    | _                    | 100                  | mA   |
|                              |   | current  | ports   | 3 V                                | _                    | _                    | 50                   |      |
| V <sub>IH</sub>              | Р | Input high   | All digital inputs  | V <sub>DD</sub> >4.5V              | $0.70 \times V_{DD}$ | _                    | -                    | V    |
|                              | С | voltage  |   | V <sub>DD</sub> >2.7V              | $0.75 \times V_{DD}$ | _                    | _                    |      |
| VIL                          | Р | Input low  | All digital inputs  | V <sub>DD</sub> >4.5V              | _                    | _                    | $0.30 \times V_{DD}$ | V    |
|                              | С | voltage  |   | V <sub>DD</sub> >2.7V              | _                    | _                    | $0.35 \times V_{DD}$ | 1    |
| V <sub>hys</sub>             | С | Input<br>hysteresis  | All digital inputs  | _                                  | $0.06 \times V_{DD}$ | _                    | —                    | mV   |
| <sub>In</sub>                | Ρ | Input leakage current  | All input only pins<br>(per pin)                                      | $V_{IN} = V_{DD}$ or<br>$V_{SS}$   |                      | 0.1                  | 1                    | μA   |
| II <sub>OZ</sub> I           | Ρ | Hi-Z (off-<br>state) leakage<br>current                      | All input/output (per<br>pin)   | $V_{IN} = V_{DD}$ or $V_{SS}$      | _                    | 0.1                  | 1                    | μA   |
| I <sub>OZTOT</sub>           | С | Total leakage<br>combined for<br>all inputs and<br>Hi-Z pins | All input only and I/O  | $V_{IN} = V_{DD}$ or<br>$V_{SS}$   | —                    | _                    | 2                    | μA   |
| R <sub>PU</sub>              | Ρ | Pullup<br>resistors  | All digital inputs,<br>when enabled (all I/O<br>pins other than PTB0) | _                                  | 30.0                 | —                    | 50.0                 | kΩ   |
| R <sub>PU</sub> <sup>2</sup> | Ρ | Pullup<br>resistors  | PTB0 pin  | _                                  | 30.0                 | _                    | 60.0                 | kΩ   |
| I <sub>IC</sub>              | D | DC injection   | Single pin limit  | $V_{\rm IN} < V_{\rm SS},$         | -0.2                 | _                    | 2                    | mA   |
|                              |   | current <sup>3, 4, 5</sup>                                   | Total MCU limit,<br>includes sum of all<br>stressed pins              | V <sub>IN</sub> > V <sub>DD</sub>  | -5                   | —                    | 25                   |      |
| C <sub>In</sub>              | С | Input cap  | bacitance, all pins   | —                                  | —                    |                      | 7                    | pF   |
| V <sub>RAM</sub>             | С | RAM re   | etention voltage  | _                                  | 2.0                  |                      | _                    | V    |

#### Table 3. DC characteristics (continued)

1. Typical values are measured at 25  $^\circ\text{C}.$  Characterized, not tested.

- 2. The specified resistor value is the actual value internal to the device. The pullup value may appear higher when measured externally on the pin.
- 3. All functional non-supply pins, except for PTB0, are internally clamped to  $V_{SS}$  and  $V_{DD}$ .
- 4. Input must be current-limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the large one.
- 5. Power supply must maintain regulation within operating V<sub>DD</sub> range during instantaneous and operating maximum current conditions. If the positive injection current (V<sub>In</sub> > V<sub>DD</sub>) is higher than I<sub>DD</sub>, the injection current may flow out of V<sub>DD</sub> and could result in external power supply going out of regulation. Ensure that external V<sub>DD</sub> load will shunt current higher than maximum injection current when the MCU is not consuming power, such as no system clock is present, or clock rate is very low (which would reduce overall power consumption).

| Table 4. | LVD and | POR S | pecification |
|----------|---------|-------|--------------|
|----------|---------|-------|--------------|

| Symbol           | С | Description                        | Min | Тур  | Max | Unit |
|------------------|---|------------------------------------|-----|------|-----|------|
| V <sub>POR</sub> | D | POR re-arm voltage <sup>1, 2</sup> | 1.5 | 1.75 | 2.0 | V    |

Table continues on the next page...

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| Symbol              | С | Description   | Min                    | Тур  | Max  | Unit |
|---------------------|---|---|------------------------|------|------|------|
| V <sub>LVDH</sub>   | С | Falling low-voltage d<br>threshold - high range<br>= $1)^3$ |                        | 4.3  | 4.4  | V    |
| V <sub>LVW1H</sub>  | С | voltage (LVW)   | falling 4.3<br>( = 00) | 4.4  | 4.5  | V    |
| V <sub>LVW2H</sub>  | С | warning<br>threshold -<br>high range                        |                        | 4.5  | 4.6  | V    |
| V <sub>LVW3H</sub>  | С | Level 3<br>(LVW)  |                        | 4.6  | 4.7  | V    |
| V <sub>LVW4H</sub>  | С | Level 4<br>(LVWV  |                        | 4.7  | 4.8  | V    |
| V <sub>HYSH</sub>   | С | High range low-volt<br>detect/warning hyste                 |                        | 100  | —    | mV   |
| V <sub>LVDL</sub>   | С | Falling low-voltage d<br>threshold - low range (I<br>0)     |                        | 2.61 | 2.66 | V    |
| V <sub>LVDW1L</sub> | С | Falling low-Level 1<br>voltage (LVWV                        |                        | 2.7  | 2.78 | V    |
| V <sub>LVDW2L</sub> | С | warning<br>threshold -<br>low range                         |                        | 2.8  | 2.88 | V    |
| V <sub>LVDW3L</sub> | С | Level 3<br>(LVW)  |                        | 2.9  | 2.98 | V    |
| V <sub>LVDW4L</sub> | С | Level 4<br>(LVWV  |                        | 3.0  | 3.08 | V    |
| V <sub>HYSDL</sub>  | С | Low range low-voltage<br>hysteresis                         | detect —               | 40   | -    | mV   |
| V <sub>HYSWL</sub>  | С | Low range low-volta<br>warning hysteres                     |                        | 80   | -    | mV   |
| V <sub>BG</sub>     | Р | Buffered bandgap ou   | tput <sup>4</sup> 1.14 | 1.16 | 1.18 | V    |

Table 4. LVD and POR Specification (continued)

1. Maximum is highest voltage that POR is guaranteed.

2. POR ramp time must be longer than 20us/V to get a stable startup.

3. Rising thresholds are falling threshold + hysteresis.

4. Voltage factory trimmed at  $V_{DD}$  = 5.0 V, Temp = 25  $^\circ C$ 

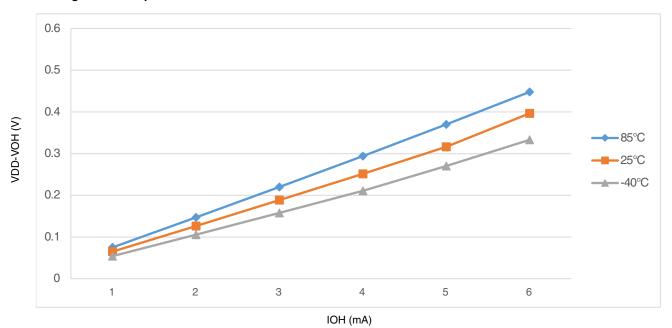


Figure 2. Typical I<sub>OH</sub> Vs.  $V_{DD}$ - $V_{OH}$  (standard drive strength) ( $V_{DD}$  = 5 V)

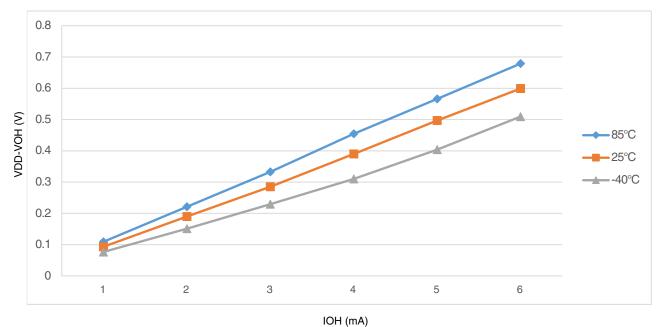


Figure 3. Typical I<sub>OH</sub> Vs.  $V_{DD}$ - $V_{OH}$  (standard drive strength) ( $V_{DD}$  = 3 V)

Nonswitching electrical specifications

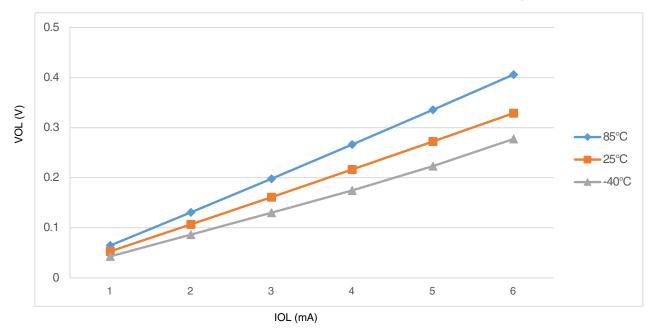


Figure 4. Typical I<sub>OL</sub> Vs. V<sub>OL</sub> (standard drive strength) (V<sub>DD</sub> = 5 V)

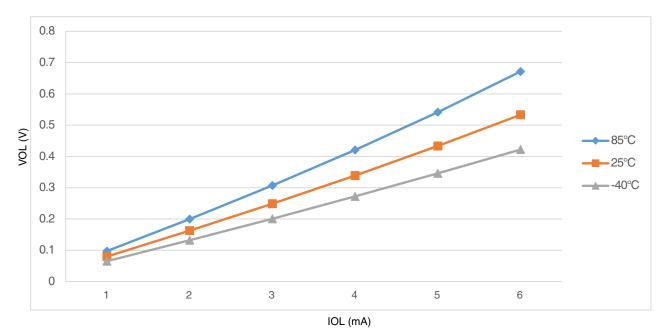


Figure 5. Typical I<sub>OL</sub> Vs. V<sub>OL</sub> (standard drive strength) ( $V_{DD}$  = 3 V)

### 6.1.2 Supply current characteristics

This section includes information about power supply current in various operating modes.

| Num | С | Parameter  | Symbol            | Bus Freq | V <sub>DD</sub> (V) | Typical <sup>1</sup> | Мах  | Unit |
|-----|---|--|-------------------|----------|---------------------|----------------------|------|------|
| 1   | С | Run supply current FEI mode,                                 | RI <sub>DD</sub>  | 20 MHz   | 5                   | 5.43                 | _    | mA   |
|     | С | all modules on; run from flash                               |                   | 10 MHz   |                     | 3.46                 | _    |      |
|     |   |  |                   | 1 MHz    |                     | 1.71                 |      |      |
|     | С |  |                   | 20 MHz   | 3                   | 5.35                 |      |      |
|     | С |  |                   | 10 MHz   |                     | 3.45                 | —    |      |
|     |   |  |                   | 1 MHz    |                     | 1.69                 | _    |      |
| 2   | С | Run supply current FEI mode,                                 | RI <sub>DD</sub>  | 20 MHz   | 5                   | 4.51                 | —    | mA   |
|     | С | all modules off and gated; run<br>from flash                 |                   | 10 MHz   |                     | 3.01                 | —    |      |
|     |   | nom nasn   |                   | 1 MHz    |                     | 1.68                 | _    |      |
|     | С |  |                   | 20 MHz   | 3                   | 4.47                 | _    |      |
|     | С |  |                   | 10 MHz   |                     | 2.99                 | —    |      |
|     |   |  |                   | 1 MHz    |                     | 1.65                 |      |      |
| 3   | Р | Run supply current FBE                                       | RI <sub>DD</sub>  | 20 MHz   | 5                   | 5.31                 | 7.41 | mA   |
|     | С | mode, all modules on; run<br>from RAM                        |                   | 10 MHz   |                     | 3.17                 | _    |      |
|     |   |  |                   | 1 MHz    |                     | 1.25                 |      |      |
|     | С |  |                   | 20 MHz   | 3                   | 5.29                 |      |      |
|     | С |  |                   | 10 MHz   |                     | 3.17                 | _    |      |
|     |   |  |                   | 1 MHz    |                     | 1.24                 |      |      |
| 4   | Р | Run supply current FBE                                       | RI <sub>DD</sub>  | 20 MHz   | 5                   | 4.39                 | 6.59 | mA   |
|     | С | mode, all modules off and gated; run from RAM                |                   | 10 MHz   |                     | 2.71                 | _    |      |
|     |   | gated, full from than  |                   | 1 MHz    |                     | 1.21                 |      |      |
|     | С |  |                   | 20 MHz   | 3                   | 4.39                 | _    |      |
|     | С |  |                   | 10 MHz   |                     | 2.71                 |      |      |
|     |   |  |                   | 1 MHz    |                     | 1.20                 |      |      |
| 5   | С | Wait mode current FEI mode,                                  | WI <sub>DD</sub>  | 20 MHz   | 5                   | 3.62                 | _    | mA   |
|     | С | all modules on   |                   | 10 MHz   |                     | 2.27                 |      |      |
|     |   |  |                   | 1 MHz    |                     | 1.11                 |      |      |
|     | С |  |                   | 20 MHz   | 3                   | 3.61                 |      |      |
|     |   |  |                   | 10 MHz   |                     | 2.31                 |      |      |
|     |   |  |                   | 1 MHz    |                     | 1.10                 | _    | 1    |
| 6   | С | Stop3 mode supply current                                    | S3I <sub>DD</sub> |          | 5                   | 1.5                  | _    | μA   |
|     | С | no clocks active (except 1<br>kHz LPO clock) <sup>2, 3</sup> |                   |          | 3                   | 0.85                 | _    |      |
| 7   | С | ADC adder to stop3   |                   |          | 5                   | 96.0                 | _    | μA   |
|     | С | ADLPC = 1  | _                 | —        | 3                   | 88.3                 | _    |      |

Table 5. Supply current characteristics in operating temperature range

Table continues on the next page...

|     |   |                     |        |          |                     |                      |     | -    |
|-----|---|---------------------|--------|----------|---------------------|----------------------|-----|------|
| Num | С | Parameter           | Symbol | Bus Freq | V <sub>DD</sub> (V) | Typical <sup>1</sup> | Max | Unit |
|     |   | ADLSMP = 1          |        |          |                     |                      |     |      |
|     |   | ADCO = 1            |        |          |                     |                      |     |      |
|     |   | MODE = 10B          |        |          |                     |                      |     |      |
|     |   | ADICLK = 11B        |        |          |                     |                      |     |      |
| 8   | С | LVD adder to stop34 | _      | —        | 5                   | 129                  | —   | μA   |
|     | С |                     |        |          | 3                   | 126                  | —   | ]    |

Table 5. Supply current characteristics in operating temperature range (continued)

1. Data in Typical column was characterized at 5.0 V, 25  $^\circ C$  or is typical recommended value.

2. RTC adder cause <1 µA I<sub>DD</sub> increase typically, RTC clock source is 1 kHz LPO clock.

3. ACMP adder cause <10  $\mu$ A I<sub>DD</sub> increase typically.

4. LVD is periodically woken up from stop3 by 5% duty cycle. The period is equal to or less than 2 ms.

### 6.1.3 EMC performance

Electromagnetic compatibility (EMC) performance is highly dependent on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult NXP applications notes such as AN2321, AN1050, AN1263, AN2764, and AN1259 for advice and guidance specifically targeted at optimizing EMC performance.

### 6.2 Switching specifications

### 6.2.1 Control timing

Table 6. Control timing

| Num | С | Rating   |                                | Symbol              | Min                       | Typical <sup>1</sup> | Max  | Unit |
|-----|---|--|--------------------------------|---------------------|---------------------------|----------------------|------|------|
| 1   | Р | Bus frequency (t <sub>cyc</sub> = 1/f <sub>Bus</sub> )   |                                | f <sub>Bus</sub>    | DC                        | —                    | 20   | MHz  |
| 2   | Р | Internal low power oscillator  | frequency                      | f <sub>LPO</sub>    | 0.67                      | 1.0                  | 1.25 | KHz  |
| 3   | D | External reset pulse width <sup>2</sup>  |                                | t <sub>extrst</sub> | 1.5 ×<br>t <sub>cyc</sub> | _                    | _    | ns   |
| 4   | D | Reset low drive  |                                | t <sub>rstdrv</sub> | 34 × t <sub>cyc</sub>     |                      |      | ns   |
| 5   | D | BKGD/MS setup time after i<br>debug force reset to enter u   |                                | t <sub>MSSU</sub>   | 500                       | _                    | _    | ns   |
| 6   | D | BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes <sup>3</sup> |                                | t <sub>MSH</sub>    | 100                       | _                    | —    | ns   |
| 7   | D | IRQ pulse width  | Asynchronous path <sup>2</sup> | t <sub>ILIH</sub>   | 100                       | _                    | _    | ns   |

Table continues on the next page...

#### Switching specifications

| Num | С | Rating   |                                   | Symbol            | Min                 | Typical <sup>1</sup> | Max | Unit |
|-----|---|--|-----------------------------------|-------------------|---------------------|----------------------|-----|------|
|     | D |  | Synchronous path <sup>4</sup>     | t <sub>IHIL</sub> | $1.5 	imes t_{cyc}$ | —                    | —   | ns   |
| 8   | D | Keyboard interrupt pulse<br>width                      | Asynchronous<br>path <sup>2</sup> | t <sub>ILIH</sub> | 100                 | _                    |     | ns   |
|     | D |  | Synchronous path                  | t <sub>IHIL</sub> | $1.5 	imes t_{cyc}$ | _                    | —   | ns   |
| 9   | С | Port rise and fall time -                              | _                                 | t <sub>Rise</sub> | —                   | 10.2                 | —   | ns   |
|     | С | standard drive strength<br>(load = 50 pF) <sup>5</sup> |                                   | t <sub>Fall</sub> |                     | 9.5                  | —   | ns   |

 Table 6.
 Control timing (continued)

- 1. Typical values are based on characterization data at  $V_{DD}$  = 5.0 V, 25 °C unless otherwise stated.
- 2. This is the shortest pulse that is guaranteed to be recognized as a reset pin request.
- 3. To enter BDM mode following a POR, BKGD/MS must be held low during the powerup and for a hold time of t<sub>MSH</sub> after V<sub>DD</sub> rises above V<sub>LVD</sub>.
- 4. This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized.
- 5. Timing is shown with respect to 20%  $V_{DD}$  and 80%  $V_{DD}$  levels in operating temperature range.

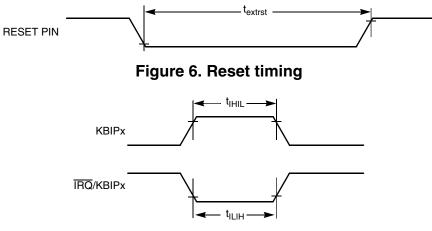
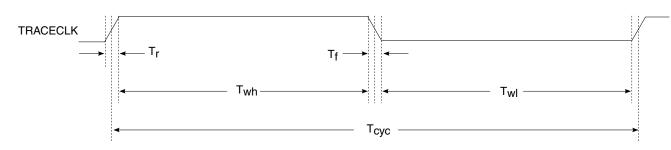


Figure 7. IRQ/KBIPx timing

#### 6.2.2 Debug trace timing specifications Table 7. Debug trace operating behaviors

| Symbol           | Description              | Min.      | Max.      | Unit |
|------------------|--------------------------|-----------|-----------|------|
| t <sub>cyc</sub> | Clock period             | Frequency | dependent | MHz  |
| t <sub>wl</sub>  | Low pulse width          | 2         | —         | ns   |
| t <sub>wh</sub>  | High pulse width         | 2         | _         | ns   |
| t <sub>r</sub>   | Clock and data rise time | _         | 3         | ns   |
| t <sub>f</sub>   | Clock and data fall time | _         | 3         | ns   |
| t <sub>s</sub>   | Data setup               | 3         | —         | ns   |
| t <sub>h</sub>   | Data hold                | 2         | —         | ns   |

#### Switching specifications





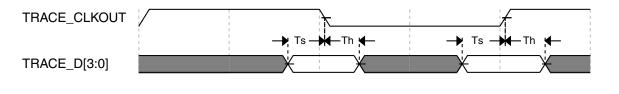


Figure 9. Trace data specifications

### 6.2.3 FTM module timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

| No. | С | Function                     | Symbol            | Min | Max                 | Unit             |
|-----|---|------------------------------|-------------------|-----|---------------------|------------------|
| 1   | D | External clock<br>frequency  | f <sub>TCLK</sub> | 0   | f <sub>Bus</sub> /4 | Hz               |
| 2   | D | External clock<br>period     | t <sub>TCLK</sub> | 4   | _                   | t <sub>cyc</sub> |
| 3   | D | External clock<br>high time  | t <sub>clkh</sub> | 1.5 | _                   | t <sub>cyc</sub> |
| 4   | D | External clock<br>low time   | t <sub>clkl</sub> | 1.5 | _                   | t <sub>cyc</sub> |
| 5   | D | Input capture<br>pulse width | t <sub>ICPW</sub> | 1.5 |                     | t <sub>cyc</sub> |

Table 8.FTM input timing

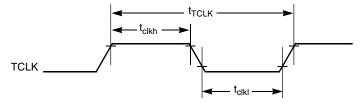


Figure 10. Timer external clock

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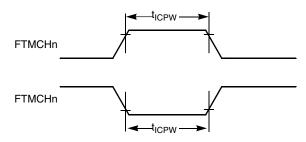


Figure 11. Timer input capture pulse

# 6.3 Thermal specifications

### 6.3.1 Thermal operating requirements

Table 9. Thermal operating requirements

| Symbol         | Description              | Min. | Max. | Unit |
|----------------|--------------------------|------|------|------|
| TJ             | Die junction temperature | -40  | 105  | °C   |
| T <sub>A</sub> | Ambient temperature      | -40  | 85   | °C   |

#### NOTE

Maximum  $T_A$  can be exceeded only if the user ensures that  $T_J$  does not exceed the maximum. The simplest method to determine  $T_J$  is:  $T_J = T_A + R_{\theta JA} \times chip$  power dissipation.

### 6.3.2 Thermal characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take  $P_{I/O}$  into account in power calculations, determine the difference between actual pin voltage and  $V_{SS}$  or  $V_{DD}$  and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and  $V_{SS}$  or  $V_{DD}$  will be very small.

| Rating                                 | Symbol | Value | Unit |  |
|--|--------|-------|------|--|
| Thermal resistance single-layer board  |        |       |      |  |
| 20-pin TSSOP R <sub>0JA</sub> 115 °C/W |        |       |      |  |

| Table 10. | Thermal | characteristics |
|-----------|---------|-----------------|
|-----------|---------|-----------------|

Table continues on the next page ...

| Rating       | Symbol           | Value                           | Unit |
|--------------|------------------|---------------------------------|------|
| 16-pin TSSOP | R <sub>θJA</sub> | 130                             | °C/W |
| 8-pin SOIC   | R <sub>θJA</sub> | 150                             | °C/W |
|              | Ther             | mal resistance four-layer board |      |
| 20-pin TSSOP | R <sub>θJA</sub> | 76                              | °C/W |
| 16-pin TSSOP | R <sub>θJA</sub> | 87                              | °C/W |
| 8-pin SOIC   | R <sub>θJA</sub> | 87                              | °C/W |

#### Table 10. Thermal characteristics (continued)

# 7 Peripheral operating requirements and behaviors

### 7.1 External oscillator (XOSC) and ICS characteristics

#### Table 11. XOSC and ICS specifications in operating temperature range

| Num | С | c                                   | haracteristic   | Symbol          | Min   | Typical <sup>1</sup>  | Max     | Unit |
|-----|---|-------------------------------------|---|-----------------|-------|-----------------------|---------|------|
| 1   | С | Oscillator                          | Low range (RANGE = 0)   | f <sub>lo</sub> | 31.25 | 32.768                | 39.0625 | kHz  |
|     | С | crystal or<br>resonator             | High range (RANGE = 1)<br>FEE or FBE mode <sup>2</sup>        | f <sub>hi</sub> | 4     | —                     | 20      | MHz  |
|     | С |                                     | High range (RANGE = 1),<br>high gain (HGO = 1),<br>FBELP mode | f <sub>hi</sub> | 4     | —                     | 20      | MHz  |
|     | C |                                     | High range (RANGE = 1),<br>low power (HGO = 0),<br>FBELP mode | f <sub>hi</sub> | 4     | —                     | 20      | MHz  |
| 2   | D | Lo                                  | bad capacitors  | C1, C2          |       | See Note <sup>3</sup> |         |      |
| 3   | D | Feedback<br>resistor                | Low Frequency, Low-Power<br>Mode <sup>4</sup>                 | R <sub>F</sub>  | _     |                       | _       | ΜΩ   |
|     |   |                                     | Low Frequency, High-Gain<br>Mode                              |                 | _     | 10                    | _       | ΜΩ   |
|     |   |                                     | High Frequency, Low-<br>Power Mode                            |                 | _     | 1                     | _       | ΜΩ   |
|     |   |                                     | High Frequency, High-Gain<br>Mode                             |                 | _     | 1                     | _       | MΩ   |
| 4   | D | Series resistor -                   | Low-Power Mode <sup>4</sup>                                   | R <sub>S</sub>  | _     | _                     | _       | kΩ   |
|     |   | Low Frequency                       | High-Gain Mode  |                 | _     | 200                   | _       | kΩ   |
| 5   | D | Series resistor -<br>High Frequency | Low-Power Mode <sup>4</sup>                                   | R <sub>S</sub>  | _     | _                     | —       | kΩ   |
|     | D | Series resistor -                   | 4 MHz   |                 | _     | 0                     | _       | kΩ   |
|     | D | High<br>Frequency,                  | 8 MHz   |                 | _     | 0                     | —       | kΩ   |
|     | D | High-Gain Mode                      | 16 MHz  |                 |       | 0                     | _       | kΩ   |

Table continues on the next page ...

#### Peripheral operating requirements and behaviors

| Num | С  | c   | haracteristic  | Symbol               | Min     | Typical <sup>1</sup> | Мах  | Unit              |
|-----|--|---|--|----------------------|---------|----------------------|------|-------------------|
| 6   | С  | Crystal start-up                                      | Low range, low power   | t <sub>CSTL</sub>    | _       | 1000                 |      | ms                |
|     | С  | time Low range<br>= 32.768 kHz                        | Low range, high power  |                      | —       | 800                  | _    | ms                |
|     | С  | crystal; High   | High range, low power  | t <sub>CSTH</sub>    | _       | 3                    | _    | ms                |
|     | С  | range = 20 MHz<br>crystal <sup>5</sup> , <sup>6</sup> | High range, high power   |                      | —       | 1.5                  | —    | ms                |
| 7   | Т  | Internal re   | t <sub>IRST</sub>  | _                    | 20      | 50                   | μs   |                   |
| 8   | D  | Square wave   | FEE or FBE mode <sup>2</sup>                                   | f <sub>extal</sub>   | 0.03125 | _                    | 5    | MHz               |
|     | D  | input clock<br>frequency                              | FBELP mode   |                      | 0       | _                    | 20   | MHz               |
| 9   | Ρ  | Average internal reference frequency -<br>trimmed     |  | f <sub>int_t</sub>   | _       | 31.25                | _    | kHz               |
| 10  | Р  | DCO output fi   | requency range - trimmed                                       | f <sub>dco_t</sub>   | 16      | —                    | 20   | MHz               |
| 11  | Р  | Total deviation<br>of DCO output                      | Over full voltage and temperature range                        | $\Delta f_{dco_t}$   | _       |                      | ±2.0 | %f <sub>dco</sub> |
|     | C from trimmed<br>frequency <sup>5</sup> |   | Over fixed voltage and<br>temperature range of 0 to<br>70 °C   |                      |         |                      | ±1.0 |                   |
| 12  | С  | FLL a   | cquisition time <sup>5</sup> , <sup>7</sup>                    | t <sub>Acquire</sub> | _       | —                    | 2    | ms                |
| 13  | С  |   | tter of DCO output clock<br>d over 2 ms interval) <sup>8</sup> | C <sub>Jitter</sub>  | —       | 0.02                 | 0.2  | %f <sub>dco</sub> |

#### Table 11. XOSC and ICS specifications in operating temperature range (continued)

- 1. Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.
- 2. When ICS is configured for FEE or FBE mode, input clock source must be divisible using RDIV to within the range of 31.25 kHz to 39.0625 kHz.
- 3. See crystal or resonator manufacturer's recommendation.
- 4. Load capacitors ( $C_1$ , $C_2$ ), feedback resistor ( $R_F$ ) and series resistor ( $R_S$ ) are incorporated internally when RANGE = HGO = 0.
- 5. This parameter is characterized and not tested on each device.
- 6. Proper PC board layout procedures must be followed to achieve specifications.
- 7. This specification applies to any time the FLL reference source or reference divider is changed, trim value changed, or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
- Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f<sub>Bus</sub>. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V<sub>DD</sub> and V<sub>SS</sub> and variation in crystal oscillator frequency increase the C<sub>Jitter</sub> percentage for a given interval.

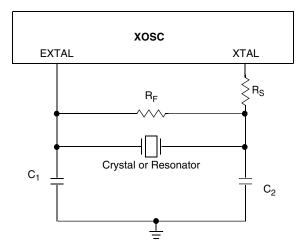


Figure 12. Typical crystal or resonator circuit

# 7.2 NVM specifications

This section provides details about program/erase times and program/erase endurance for the flash and EEPROM memories.

| С | Characteristic  | Symbol                  | Min  | Typical | Мах  | Unit   |
|---|---|-------------------------|------|---------|------|--------|
| D | Supply voltage for program/erase across the operating temperature range   | V <sub>prog/erase</sub> | 2.7  |         | 5.5  | V      |
| D | Supply voltage for read operation   | V <sub>Read</sub>       | 2.7  | —       | 5.5  | V      |
| D | NVM Bus frequency   | f <sub>NVMBUS</sub>     | 1    |         | 20   | MHz    |
| D | NVM operating frequency   | f <sub>NVMOP</sub>      | 0.8  | 1.0     | 1.05 | MHz    |
| С | FLASH Program/erase endurance ${\rm T_L}$ to ${\rm T_H}$ in the operating temperature range   | N <sub>FLPE</sub>       | 10 k | 100 k   |      | Cycles |
| С | $\begin{array}{c} \mbox{EEPROM Program/erase endurance } T_L \\ \mbox{to } T_H \mbox{ in the operating temperature} \\ \mbox{ range} \end{array}$ | N <sub>FLPE</sub>       | 50 k | 500 k   | _    | Cycles |
| С | Data retention at an average junction<br>temperature of T <sub>Javg</sub> = 85°C after up to<br>10,000 program/erase cycles                       | t <sub>D_ret</sub>      | 15   | 100     | _    | years  |

Table 12. Flash clock characteristics

All timing parameters are a function of the bus clock frequency,  $F_{NVMBUS}$ . All program and erase times are also a function of the NVM operating frequency,  $f_{NVMOP}$ .

Each command timing is given by:

 $t_{command} = f_{NVMOP} \text{ cycle} \times 1/f_{NVMOP} + f_{NVMBUS} \text{ cycle} \times 1/f_{NVMBUS}$ 

Peripheral operating requirements and behaviors

| С | Characteristic              | Symbol               | f <sub>NVMOP</sub> cycle | f <sub>NVMBUS</sub> cycle |
|---|-----------------------------|----------------------|--------------------------|---------------------------|
| D | Erase Verify All Blocks     | t <sub>VFYALL</sub>  | —                        | 1850                      |
| D | Erase Verify Flash Block    | t <sub>RD1BLK</sub>  | _                        | 1559                      |
| D | Erase Verify EEPROM Block   | t <sub>RD1BLK</sub>  | —                        | 682                       |
| D | Erase Verify Flash Section  | t <sub>RD1SEC</sub>  | _                        | 494                       |
| D | Erase Verify EEPROM Section | t <sub>DRD1SEC</sub> | —                        | 555                       |
| D | Read Once                   | t <sub>RDONCE</sub>  |                          | 450                       |
| D | Program Flash (2 word)      | t <sub>PGM2</sub>    | 68                       | 1407                      |
| D | Program Flash (4 word)      | t <sub>PGM4</sub>    | 122                      | 2138                      |
| D | Program Once                | t <sub>PGMONCE</sub> | 122                      | 2090                      |
| D | Program EEPROM (1 Byte)     | t <sub>DPGM1</sub>   | 47                       | 1371                      |
| D | Program EEPROM (2 Byte)     | t <sub>DPGM2</sub>   | 94                       | 2120                      |
| D | Program EEPROM (3 Byte)     | t <sub>DPGM3</sub>   | 141                      | 2869                      |
| D | Program EEPROM (4 Byte)     | t <sub>DPGM4</sub>   | 188                      | 3618                      |
| D | Erase All Blocks            | t <sub>ERSALL</sub>  | 100066                   | 2255                      |
| D | Erase Flash Block           | t <sub>ERSBLK</sub>  | 100060                   | 1882                      |
| D | Erase Flash Sector          | t <sub>ERSPG</sub>   | 20015                    | 878                       |
| D | Erase EEPROM Sector         | t <sub>DERSPG</sub>  | 5015                     | 756                       |
| D | Unsecure Flash              | t <sub>UNSECU</sub>  | 100066                   | 2242                      |
| D | Verify Backdoor Access Key  | tVFYKEY              | —                        | 464                       |
| D | Set User Margin Level       | t <sub>MLOADU</sub>  | _                        | 413                       |

#### Table 13. Flash timing characteristics

Program and erase operations do not require any special power sources other than the normal  $V_{DD}$  supply. For more detailed information about program/erase operations, see the Memory section.

# 7.3 Analog

### 7.3.1 ADC characteristics

| Characteri<br>stic | Conditions   | Symb              | Min  | Typ <sup>1</sup> | Max  | Unit | Comment |
|--------------------|--|-------------------|------|------------------|------|------|---------|
| Supply             | Absolute   | V <sub>DDA</sub>  | 2.7  | —                | 5.5  | V    | —       |
| voltage            | Delta to V <sub>DD</sub> (V <sub>DD</sub> -V <sub>DDAD</sub> ) | $\Delta V_{DDA}$  | -100 | 0                | +100 | mV   |         |
| Ground<br>voltage  | Delta to $V_{SS} (V_{SS} - V_{SSA})^2$                         | ΔV <sub>SSA</sub> | -100 | 0                | +100 | mV   |         |

Table 14. 5 V 10-bit ADC operating conditions

Table continues on the next page...

| Characteri<br>stic               | Conditions  | Symb              | Min               | Typ <sup>1</sup> | Max               | Unit | Comment            |
|----------------------------------|---|-------------------|-------------------|------------------|-------------------|------|--------------------|
| Input<br>voltage                 |   | V <sub>ADIN</sub> | V <sub>REFL</sub> | —                | V <sub>REFH</sub> | V    |                    |
| Input<br>capacitance             |   | C <sub>ADIN</sub> | —                 | 4.5              | 5.5               | pF   |                    |
| Input<br>resistance              |   | R <sub>ADIN</sub> | —                 | 3                | 5                 | kΩ   | -                  |
| Analog<br>source<br>resistance   | <ul> <li>10-bit mode</li> <li>f<sub>ADCK</sub> &gt; 4 MHz</li> <li>f<sub>ADCK</sub> &lt; 4 MHz</li> </ul> | R <sub>AS</sub>   | _                 | _                | 5<br>10           | kΩ   | External to<br>MCU |
|                                  | 8-bit mode<br>(all valid f <sub>ADCK</sub> )  |                   |                   |                  | 10                | -    |                    |
| ADC                              | High speed (ADLPC=0)  | f <sub>ADCK</sub> | 0.4               | _                | 8.0               | MHz  | _                  |
| conversion<br>clock<br>frequency | Low power (ADLPC=1)   |                   | 0.4               | _                | 4.0               |      |                    |

 Table 14. 5 V 10-bit ADC operating conditions (continued)

1. Typical values assume V<sub>DDA</sub> = 5.0 V, Temp = 25°C, f<sub>ADCK</sub>=1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2. DC potential difference.

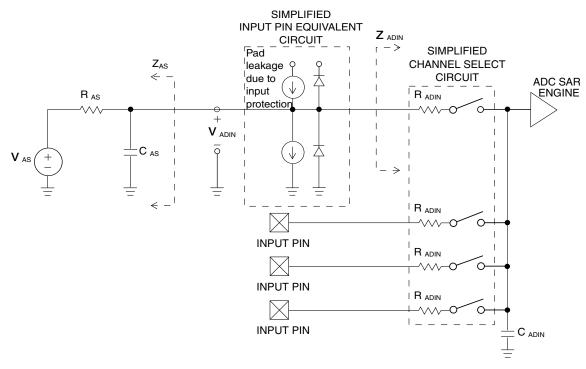


Figure 13. ADC input impedance equivalency diagram

| Table 15. | 10-bit ADC | Characteristics | (V <sub>REFH</sub> = | $V_{DDA}$ , | $V_{REFL} = $ | V <sub>SSA</sub> ) |
|-----------|------------|-----------------|----------------------|-------------|---------------|--------------------|
|-----------|------------|-----------------|----------------------|-------------|---------------|--------------------|

| Characteristic                   | Conditions | С | Symb             | Min | Typ <sup>1</sup> | Мах | Unit |  |
|----------------------------------|------------|---|------------------|-----|------------------|-----|------|--|
| Supply current                   |            | Т | I <sub>DDA</sub> | —   | 133              | —   | μA   |  |
| Table continues on the payt page |            |   |                  |     |                  |     |      |  |

Table continues on the next page...

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#### Peripheral operating requirements and behaviors

# Table 15. 10-bit ADC Characteristics ( $V_{REFH} = V_{DDA}$ , $V_{REFL} = V_{SSA}$ ) (continued)

| Characteristic                       | Conditions                   | С | Symb               | Min  | Typ <sup>1</sup>                  | Max   | Unit             |
|--------------------------------------|------------------------------|---|--------------------|------|-----------------------------------|-------|------------------|
| ADLPC = 1                            |                              |   |                    |      |                                   |       |                  |
| ADLSMP = 1                           |                              |   |                    |      |                                   |       |                  |
| ADCO = 1                             |                              |   |                    |      |                                   |       |                  |
| Supply current                       |                              | Т | I <sub>DDA</sub>   | _    | 218                               |       | μA               |
| ADLPC = 1                            |                              |   |                    |      |                                   |       |                  |
| ADLSMP = 0                           |                              |   |                    |      |                                   |       |                  |
| ADCO = 1                             |                              |   |                    |      |                                   |       |                  |
| Supply current                       |                              | Т | I <sub>DDA</sub>   | _    | 327                               | _     | μA               |
| ADLPC = 0                            |                              |   |                    |      |                                   |       |                  |
| ADLSMP = 1                           |                              |   |                    |      |                                   |       |                  |
| ADCO = 1                             |                              |   |                    |      |                                   |       |                  |
| Supply current                       |                              | Т | I <sub>DDAD</sub>  | _    | 582                               | 990   | μA               |
| ADLPC = 0                            |                              |   |                    |      |                                   |       |                  |
| ADLSMP = 0                           |                              |   |                    |      |                                   |       |                  |
| ADCO = 1                             |                              |   |                    |      |                                   |       |                  |
| Supply current                       | Stop, reset, module off      | Т | I <sub>DDA</sub>   | _    | 0.011                             | 1     | μA               |
| ADC asynchronous<br>clock source     | High speed (ADLPC<br>= 0)    | Р | f <sub>ADACK</sub> | 2    | 3.3                               | 5     | MHz              |
|                                      | Low power (ADLPC<br>= 1)     |   |                    | 1.25 | 2                                 | 3.3   | -                |
| Conversion time<br>(including sample | Short sample<br>(ADLSMP = 0) | Т | t <sub>ADC</sub>   | _    | 20                                | _     | ADCK<br>cycles   |
| time)                                | Long sample<br>(ADLSMP = 1)  |   |                    | _    | 40                                | —     |                  |
| Sample time                          | Short sample<br>(ADLSMP = 0) | Т | t <sub>ADS</sub>   | —    | 3.5                               | _     | ADCK<br>cycles   |
|                                      | Long sample<br>(ADLSMP = 1)  |   |                    | _    | 23.5                              | _     | 1                |
| Total unadjusted                     | 10-bit mode                  | Р | E <sub>TUE</sub>   | _    | ±1.5                              | ±2.0  | LSB <sup>3</sup> |
| Error <sup>2</sup>                   | 8-bit mode                   | Р |                    |      | ±0.7                              | ±1.0  |                  |
| Differential Non-                    | 10-bit mode <sup>4</sup>     | Р | DNL                | _    | ±0.25                             | ±0.5  | LSB <sup>3</sup> |
| Linearity                            | 8-bit mode <sup>4</sup>      | Р |                    | —    | ±0.15                             | ±0.25 | 1                |
| Integral Non-Linearity               | 10-bit mode                  | Т | INL                | —    | ±0.3                              | ±0.5  | LSB <sup>3</sup> |
|                                      | 8-bit mode                   | Т |                    | _    | ±0.15                             | ±0.25 |                  |
| Zero-scale error <sup>5</sup>        | 10-bit mode                  | Р | E <sub>ZS</sub>    | —    | ±0.25                             | ±1.0  | LSB <sup>3</sup> |
|                                      | 8-bit mode                   | Р |                    | —    | ±0.65                             | ±1.0  | ]                |
| Full-scale error <sup>6</sup>        | 10-bit mode                  | Т | E <sub>FS</sub>    | —    | ±0.5                              | ±1.0  | LSB <sup>3</sup> |
|                                      | 8-bit mode                   | Т |                    | —    | ±0.5                              | ±1.0  | ]                |
| Quantization error                   | ≤10 bit modes                | D | EQ                 | _    | _                                 | ±0.5  | LSB <sup>3</sup> |
| Input leakage error <sup>7</sup>     | all modes                    | D | E <sub>IL</sub>    |      | I <sub>In</sub> * R <sub>AS</sub> |       | mV               |

Table continues on the next page...

Table 15.10-bit ADC Characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)

| Characteristic      | Conditions  | С | Symb                | Min | Typ <sup>1</sup> | Мах | Unit  |
|---------------------|-------------|---|---------------------|-----|------------------|-----|-------|
| Temp sensor slope   | -40°C– 25°C | D | m                   | —   | 3.266            | —   | mV/°C |
|                     | 25°C– 85°C  |   |                     |     | 3.638            | —   |       |
| Temp sensor voltage | 25°C        | D | V <sub>TEMP25</sub> |     | 1.396            |     | V     |

1. Typical values assume V<sub>DDA</sub> = 5.0 V, Temp = 25°C, f<sub>ADCK</sub>=1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2. Includes quantization.

3. 1 LSB =  $(V_{REFH} - V_{REFL})/2^N$ 

4. Monotonicity and no-missing-codes guaranteed in 10-bit and 8-bit modes

5. V<sub>ADIN</sub> = V<sub>SSA</sub>

6.  $V_{ADIN} = V_{DDA}$ 

7. I<sub>In</sub> = leakage current (refer to DC characteristics)

#### 7.3.2 Analog comparator (ACMP) electricals Table 16. Comparator electrical specifications

| С | Characteristic                        | Symbol              | Min                   | Typical | Max              | Unit |
|---|---------------------------------------|---------------------|-----------------------|---------|------------------|------|
| D | Supply voltage                        | V <sub>DDA</sub>    | 2.7                   | —       | 5.5              | V    |
| Т | Supply current (Operation mode)       | I <sub>DDA</sub>    | _                     | 10      | 20               | μA   |
| D | Analog input voltage                  | V <sub>AIN</sub>    | V <sub>SS</sub> - 0.3 | —       | V <sub>DDA</sub> | V    |
| Р | Analog input offset voltage           | V <sub>AIO</sub>    |                       | _       | 40               | mV   |
| С | Analog comparator hysteresis (HYST=0) | V <sub>H</sub>      |                       | 15      | 20               | mV   |
| С | Analog comparator hysteresis (HYST=1) | V <sub>H</sub>      | _                     | 20      | 30               | mV   |
| Т | Supply current (Off mode)             | I <sub>DDAOFF</sub> |                       | 60      |                  | nA   |
| С | Propagation Delay                     | t <sub>D</sub>      |                       | 0.4     | 1                | μs   |

### 8 Dimensions

### 8.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to nxp.com and perform a keyword search for the drawing's document number:

| If you want the drawing for this package | Then use this document number |
|--|-------------------------------|
| 8-pin SOIC                               | 98ASB42564B                   |
| 16-pin TSSOP                             | 98ASH70247A                   |

Table continues on the next page ...

| Pinout                                   |                               |
|--|-------------------------------|
| If you want the drawing for this package | Then use this document number |
| 20-pin TSSOP                             | 98ASH70169A                   |

# 9 Pinout

# 9.1 Signal multiplexing and pin assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

| Pin Number |          | Lowest Priority <> Highest |                   |        |         |       |                 |
|------------|----------|----------------------------|-------------------|--------|---------|-------|-----------------|
| 20-TSSOP   | 16-TSSOP | 8-SOIC                     | Port Pin          | Alt 1  | Alt 2   | Alt 3 | Alt 4           |
| 1          | 1        | 1                          | PTA5              | IRQ    | FTM1CH0 | _     | RESET           |
| 2          | 2        | 2                          | PTA4              | —      | ACMPO   | BKGD  | MS              |
| 3          | 3        | 3                          | _                 | —      | —       | —     | V <sub>DD</sub> |
| 4          | 4        | 4                          | _                 | —      | —       |       | V <sub>SS</sub> |
| 5          | 5        | —                          | PTB7              | —      | _       | —     | EXTAL           |
| 6          | 6        | —                          | PTB6              | —      | —       | —     | XTAL            |
| 7          | 7        | —                          | PTB5              | —      | FTM1CH1 |       | —               |
| 8          | 8        | —                          | PTB4              | —      | FTM1CH0 | —     | —               |
| 9          | —        | —                          | PTC3              | —      | —       | —     | —               |
| 10         | _        | —                          | PTC2              | —      | —       | —     | —               |
| 11         | —        | —                          | PTC1              | —      | —       | —     | —               |
| 12         | —        | —                          | PTC0              | —      | —       | —     | —               |
| 13         | 9        | —                          | PTB3              | KBI0P7 | —       | TCLK1 | ADP7            |
| 14         | 10       | —                          | PTB2              | KBI0P6 | —       | —     | ADP6            |
| 15         | 11       | —                          | PTB1              | KBI0P5 | TxD0    | —     | ADP5            |
| 16         | 12       | —                          | PTB0 <sup>1</sup> | KBI0P4 | RxD0    | TCLK0 | ADP4            |
| 17         | 13       | 5                          | PTA3              | KBI0P3 | FTM0CH1 | TxD0  | ADP3            |
| 18         | 14       | 6                          | PTA2              | KBI0P2 | FTM0CH0 | RxD0  | ADP2            |
| 19         | 15       | 7                          | PTA1              | KBI0P1 | FTM0CH1 | ACMP1 | ADP1            |
| 20         | 16       | 8                          | PTA0              | KBI0P0 | FTM0CH0 | ACMP0 | ADP0            |

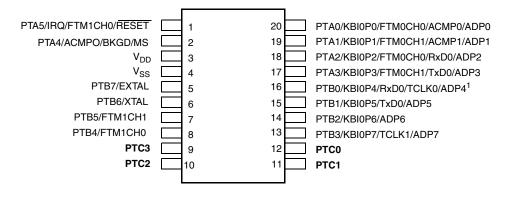
Table 17. Pin availability by package pin-count

1. This is a true open-drain pin when operated as output.

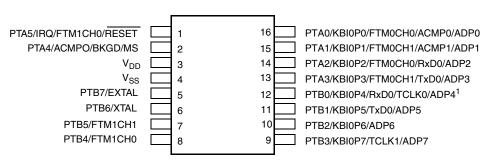
#### Note

When an alternative function is first enabled, it is possible to get a spurious edge to the module. User software must clear any associated flags before interrupts are enabled. The table above illustrates the priority if multiple modules are enabled. The highest priority module will have control over the pin. Selecting a higher priority pin function with a lower priority function already enabled can cause spurious edges to the lower priority module. Disable all modules that share a pin before enabling another module.

#### 9.2 Device pin assignment



Pins in **bold** are not available on less pin-count packages. 1. True open drain pins



#### Figure 14. 20-pin TSSOP package

Pins in **bold** are not available on less pin-count packages. 1. True open drain pins



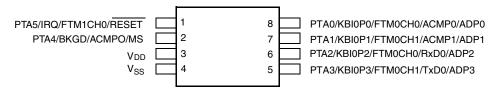


Figure 16. 8-pin SOIC packages

# 10 Revision history

The following table provides a revision history for this document.

| Rev. No. | Date    | Substantial Changes   |
|----------|---------|---|
| 0        | 03/2018 | Initial Created   |
| 1        | 04/2018 | Completed all the TBDs and added 20-pin TSSOP and 16-pin TSSOP packages.  |
| 2        | 01/2019 | <ul> <li>Added ACMP module and related information across the whole book.</li> <li>Added Thermal operating requirements.</li> <li>Updated the S3I<sub>DD</sub> in Supply current characteristics</li> </ul> |
| 3        | 08/2019 | <ul> <li>Added MCU block diagram.</li> <li>Updated flash characteristics in the NVM specifications.</li> </ul>  |

| Table | 18. | Revision | historv |
|-------|-----|----------|---------|
|       |     |          |         |

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