

### 5.7 kV RMS/1.5 kV RMS, Quad-Channel LVDS 2.5 Gigabit Isolator

#### **FEATURES**

- ▶ 5.7 kV rms and 1.5 kV rms LVDS isolators
- ▶ Complies with TIA/EIA-644-A LVDS signal levels
- ▶ Quad-channel configuration
- Any data rate up to 2.5 Gbps switching with low jitter
  - ▶ 10 Gbps total bandwidth across four channels
  - ▶ 2.15 ns typical propagation delay
  - ▶ Typical jitter: 0.82 ps rms random, 40 ps total peak
- ▶ Lower power 1.8 V supplies
- ▶ ±8 kV IEC 61000-4-2 ESD protection across isolation barrier
- ▶ High common-mode transient immunity: 100 kV/µs typical
- ▶ Safety and regulatory approvals (28-lead SOIC W FP package)
  - ▶ UL (pending): 5700 V rms for 1 minute per UL 1577
  - ▶ CSA Component Acceptance Notice 5A (pending)
  - VDE certificate of conformity (pending)
    - ▶ DIN V VDE V 0884-11 (VDE V 0884-11):2017-01
    - V<sub>IORM</sub> = 849 V<sub>PEAK</sub> (working voltage)
- ▶ Enable or disable refresh (low speed output correctness check)
- ▶ Operating temperature range: -40°C to +125°C
- ▶ 28-lead, wide-body, finer pitch SOIC\_W\_FP package with 8.3 mm creepage and clearance or 6 mm × 6 mm LFCSP package with 1.27 mm creepage and clearance

### **APPLICATIONS**

- Isolated video and imaging data
- ▶ Analog front-end isolation
- Data plane isolation
- Isolated high speed clock and data links
- Multi-gigabit serialization/deserialization (SERDES)
- ▶ Board-to-board optical replacement (for example, short reach fiber)

### **FUNCTIONAL BLOCK DIAGRAM**

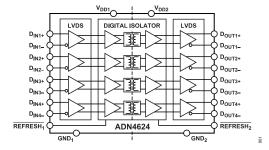


Figure 1.

### **GENERAL DESCRIPTION**

The ADN4624<sup>1</sup> is a quad-channel, signal isolated, low voltage differential signaling (LVDS) buffer that operates at up to 2.5 Gbps with very low jitter. The device integrates Analog Devices, Inc., iCoupler® technology, enhanced for high speed operation to provide drop-in galvanic isolation of LVDS signal chains. AC coupling and/or level shifting to the LVDS receivers and from the LVDS drivers allows isolation of other high speed signals such as current mode logic (CML).

The ADN4624 includes a refresh mechanism to monitor the input and output states and ensure they remain the same in the absence of data transitions (for example, at power-on).

For lower power consumption and high speed operation with low jitter, the LVDS and isolator circuits rely on 1.8 V supplies. The ADN4624 is fully specified over a wide industrial temperature range and is available in a 28-lead, wide-body, finer pitch SOIC\_W\_FP package with 8.3 mm creepage and clearance (for 5.7 kV rms or 8 kV<sub>PEAK</sub> surge and impulse voltages and reinforced insulation at ac mains voltages) or 6 mm × 6 mm LFCSP package with 1.27 mm creepage and clearance (for basic/functional isolation).

<sup>&</sup>lt;sup>1</sup> Protected by U.S. Patents 5,952,849; 6,873,065; 6,903,578; and 7,075,329. Other patents are pending.

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### **SPECIFICATIONS**

For all minimum and maximum specifications,  $V_{DD1} = V_{DD2} = 1.7 \text{ V}$  to 1.9 V and  $T_A = -40^{\circ}\text{C}$  to +125°C, unless otherwise noted. For all typical specifications,  $V_{DD1} = V_{DD2} = 1.8 \text{ V}$  and  $T_A = 25^{\circ}\text{C}$ . For all specifications,  $\overline{\text{REFRESH}_1} = \text{GND}_1$  and  $\overline{\text{REFRESH}_2} = \text{GND}_2$ , unless otherwise noted.

Table 1.

Parameter	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments
INPUTS (RECEIVERS)						
Input Threshold						See Figure 30 and Table 2
High	$V_{TH}$			100	mV	
Low	V <sub>TL</sub>	-100			mV	
Differential Input Voltage	V <sub>ID</sub>	100			mV	See Figure 30 and Table 2
Input Common-Mode Voltage	V <sub>IC</sub>	0.5 V <sub>ID</sub>		2.4 - 0.5 V <sub>ID</sub>	V	See Figure 30 and Table 2
Input Current, High and Low	I <sub>IH</sub> , I <sub>IL</sub>	<b>-</b> 5		+5	μA	$D_{INx\pm}$ = 2.4 V or 0 V, other input = 1.2 V, $V_{DDx}$ = 1.8 V or 0 V
Differential Input Capacitance <sup>1</sup>	C <sub>INx±</sub>		1.7		pF	$D_{INx\pm} = 0.4 \sin(30 \times 10^6 \pi t) \text{ V} + 0.5 \text{ V}$ , other input = 1.2 V <sup>2</sup>
LOGIC INPUTS						$V_{DDx} = V_{DD1}$ for $\overline{REFRESH_1}$ , $V_{DDx} = V_{DD2}$ for $\overline{REFRESH_2}$
Input High Voltage	V <sub>INH</sub>	0.65 V <sub>DDx</sub>			V	
Input Low Voltage	V <sub>INL</sub>			$0.35  V_{DDx}$	V	
Input Current High	I <sub>INH</sub>			1	μA	$\overline{REFRESH_X} = V_{DDX}$
				25	μA	$\overline{REFRESH_X} = 1.9 \text{ V}, V_{DDX} = 0 \text{ V}$
Input Current Low	I <sub>INL</sub>			16	μA	REFRESH <sub>x</sub> = 0 V
OUTPUTS (DRIVERS)						
Differential Output Voltage	V <sub>OD</sub>	250	310	450	mV	See Figure 28 and Figure 29, load resistance ( $R_L$ ) = 100 $\Omega$
V <sub>OD</sub> Magnitude Change	$\Delta  V_{OD} $			50	mV	See Figure 28 and Figure 29, $R_L$ = 100 $\Omega$
Offset Voltage	Vos	1.125	1.17	1.375	V	See Figure 28, $R_L$ = 100 $\Omega$
V <sub>OS</sub> Magnitude Change	ΔV <sub>OS</sub>			50	mV	See Figure 28, $R_L$ = 100 $\Omega$
V <sub>OS</sub> , Peak to Peak <sup>1</sup>	V <sub>OS(PP)</sub>			150	mV	See Figure 28, $R_L$ = 100 $\Omega$
Output Short-Circuit Current	Ios			-20	mA	D <sub>OUTx±</sub> = 0 V
				12	mA	V <sub>OD</sub>   = 0 V
Differential Output Capacitance <sup>1</sup>	C <sub>OUTx±</sub>		5		pF	$D_{OUTx\pm}$ = 0.4 sin(30 × 10 <sup>6</sup> $\pi$ t) V + 0.5 V, other input = 1.2 V, $V_{DD1}$ or $V_{DD2}$ = 0 V
POWER SUPPLY						
Supply Current Side 1	I <sub>DD1</sub>		140	175	mA	Frequency (f) = 1.25 GHz
Supply Current Side 2	I <sub>DD2</sub>					
			115	140	mA	$f$ = 1.25 GHz, $R_L$ = 100 $Ω$
			95	135	mA	f = 1.25 GHz, $R_L$ = 100 $Ω$ , $\overline{REFRESH_2}$ = $V_{DD2}$
COMMON-MODE TRANSIENT IMMUNITY <sup>3</sup>	CM	40	100		kV/µs	Common-mode voltage (V <sub>CM</sub> ) = 1000 V, transient magnitude = 800 V

<sup>&</sup>lt;sup>1</sup> These specifications are guaranteed by design and characterization.

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<sup>&</sup>lt;sup>2</sup> t denotes time.

 $<sup>^3</sup>$  |CM| is the maximum common-mode voltage slew rate that can be sustained while maintaining any  $D_{OUTx+}$  or  $D_{OUTx-}$  pin in the same state as the corresponding  $D_{INx+}$  or  $D_{INx-}$  pin (no change in output) or producing the expected transition on any  $D_{OUTx+}$  or  $D_{OUTx-}$  pin if the applied common-mode transient edge is coincident with a data transition on the corresponding  $D_{INx+}$  or  $D_{INx-}$  pin. The common-mode voltage slew rates apply to both rising and falling common-mode voltage edges.

### **SPECIFICATIONS**

### RECEIVER INPUT THRESHOLD TEST VOLTAGES

Table 2. Test Voltages for Receiver Operation

Applie	ed Voltages			
D <sub>INx+</sub> (V)	D <sub>INx</sub> - (V)	Input Voltage, Differential, V <sub>ID</sub> (V)	Input Voltage, Common-Mode, V <sub>IC</sub> (V)	Driver Output, Differential V <sub>OD</sub> (mV)
1.25	1.15	0.1	1.2	>250
.15	1.25	-0.1	+1.2	<-250
.4	2.3	0.1	2.35	>250
2.3	2.4	-0.1	+2.35	<-250
.1	0	0.1	0.05	>250
	0.1	-0.1	+0.05	<-250
.5	0.9	0.6	1.2	>250
.9	1.5	-0.6	+1.2	<-250
.4	1.8	0.6	2.1	>250
.8	2.4	-0.6	+2.1	<-250
.6	0	0.6	0.3	>250
1	0.6	-0.6	+0.3	<-250

### **TIMING SPECIFICATIONS**

For all minimum and maximum specifications,  $V_{DD1} = V_{DD2} = 1.7 \text{ V}$  to 1.9 V and  $T_A = -40 ^{\circ}\text{C}$  to  $+125 ^{\circ}\text{C}$ , unless otherwise noted. For all typical specifications,  $V_{DD1} = V_{DD2} = 1.8 \text{ V}$  and  $T_A = 25 ^{\circ}\text{C}$ . For all specifications,  $\overline{\text{REFRESH}}_1 = V_{DD1}$  and  $\overline{\text{REFRESH}}_2 = V_{DD2}$ , unless otherwise noted.

Table 3.

Parameter	Symbol	Min	Тур	Max <sup>1</sup>	Unit	Test Conditions/Comments
PROPAGATION DELAY	t <sub>PLH</sub> , t <sub>PHL</sub>		2.15	2.8	ns	See Figure 31, from any D <sub>INX+</sub> and D <sub>INX-</sub> to D <sub>OUTX+</sub> and D <sub>OUTX-</sub>
SKEW						See Figure 31, across all D <sub>OUTx+</sub> and D <sub>OUTx-</sub>
Duty Cycle <sup>2</sup>	t <sub>SK(D)</sub>		2	16	ps	
Channel to Channel <sup>3</sup>	t <sub>SK(CH)</sub>		38	92	ps	SOIC_W_FP package
			29	67	ps	LFCSP package
Part to Part <sup>4</sup>	t <sub>SK(PP)</sub>		150	300	ps	
JITTER <sup>5</sup>						See Figure 31, for any D <sub>OUTx+</sub> and D <sub>OUTx-</sub>
Random Jitter, RMS <sup>6</sup> (1σ)	t <sub>RJ(RMS)</sub>		0.82	1.44	ps rms	1.25 GHz clock input
Deterministic Jitter, Peak to Peak <sup>6, 7</sup>	t <sub>DJ(PP)</sub>		28	54	ps	2.5 Gbps, 2 <sup>23</sup> – 1 pseudorandom bit stream (PRBS)
Total Jitter, Peak to Peak, at Bit Error Rate (BER) 1 × 10 <sup>-12</sup>	t <sub>TJ(PP)</sub>		40	70	ps	1.25 GHz/2.5 Gbps, 2 <sup>23</sup> – 1 PRBS <sup>8</sup>
With Crosstalk			50		ps	1.25 GHz/2.5 Gbps, 2 <sup>23</sup> – 1 PRBS all channels <sup>8</sup>
With Crosstalk and Refresh			55		ps	1.25 GHz/2.5 Gbps, $2^{23}$ – 1 PRBS all channels, $\overline{\text{REFRESH}_1}$ = GND <sub>1</sub> , $\overline{\text{REFRESH}_2}$ = GND <sub>2</sub> <sup>8</sup>
Additive Phase Jitter	t <sub>ADDJ</sub>					
SOIC_W_FP Package			225		fs rms	100 Hz to 100 kHz, output frequency (f <sub>OUT</sub> ) = 10 MHz <sup>9</sup>
			270		fs rms	100 Hz to 100 kHz, $f_{OUT}$ = 10 MHz, $\overline{REFRESH_1}$ = $GND_1$ , $\overline{REFRESH_2}$ = $GND_2^9$
			85		fs rms	12 kHz to 20 MHz, f <sub>OUT</sub> = 1.25 GHz <sup>10</sup>
			200		fs rms	12 kHz to 20 MHz, $f_{OUT}$ = 1.25 GHz, $\overline{REFRESH_1}$ = $GND_1$ , $\overline{REFRESH_2}$ = $GND_2^{10}$
LFCSP Package			152		fs rms	100 Hz to 100 kHz, output frequency (f <sub>OUT</sub> ) = 10 MHz <sup>9</sup>
			182		fs rms	100 Hz to 100 kHz, $f_{OUT} = 10$ MHz, $\overline{REFRESH_1} = GND_1$ , $\overline{REFRESH_2} = GND_2^9$
			152		fs rms	12 kHz to 20 MHz, f <sub>OUT</sub> = 1.25 GHz <sup>10</sup>
			348		fs rms	12 kHz to 20 MHz, $f_{OUT}$ = 1.25 GHz, $\overline{REFRESH_1}$ = $GND_1$ , $\overline{REFRESH_2}$ = $GND_2^{10}$

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Table 3.

Parameter	Symbol	Min	Тур	Max <sup>1</sup>	Unit	Test Conditions/Comments
RISE AND FALL TIME	t <sub>R</sub> , t <sub>F</sub>			180	ps	See Figure 31, 1.25 GHz clock input, any $D_{OUTx+}$ and $D_{OUTx-}$ , 20% to 80%, $R_L$ = 100 $\Omega$ , load capacitance ( $C_L$ ) = 5 pF
MAXIMUM DATA RATE		2.5			Gbps	

<sup>&</sup>lt;sup>1</sup> These specifications are guaranteed by design and characterization.

- Duty cycle or pulse skew is the magnitude of the maximum difference between t<sub>PLH</sub> and t<sub>PHL</sub> for any Channel x of a device (where x = 1, 2, 3, or 4), that is, |t<sub>PLHx</sub> t<sub>PHLx</sub>|.
- 3 Channel to channel or output skew is the difference between the largest and smallest values of t<sub>PLHx</sub> within a device or the difference between the largest and smallest values of t<sub>PHx</sub> within a device, whichever of the two is greater.
- <sup>4</sup> Part to part output skew is the difference between the largest and smallest values of t<sub>PLHx</sub> across multiple devices or the difference between the largest and smallest values of t<sub>PLHx</sub> across multiple devices, whichever of the two is greater.
- <sup>5</sup> Jitter parameters are guaranteed by design and characterization. Values do not include stimulus jitter. V<sub>ID</sub> = 400 mV p-p, V<sub>IC</sub> = 1.2 V, and t<sub>R</sub> / t<sub>F</sub> < 0.05 ns (20% to 80%).
- <sup>6</sup> This specification is measured over a population of ~3,000,000 edges.
- Peak-to-peak jitter specifications include jitter due to pulse skew (t<sub>SK(D)</sub>).
- <sup>8</sup> Using the following formula:  $t_{TJ(PP)} = 14 \times t_{RJ(RMS)} + t_{DJ(PP)}$ .
- 9 With input phase jitter of 340 fs rms subtracted.
- <sup>10</sup> With input phase jitter of 155 fs rms subtracted.

#### **INSULATION AND SAFETY RELATED SPECIFICATIONS**

For additional information, see www.analog.com/icouplersafety.

Table 4. RN-28-1 Wide Body with Finer Pitch [SOIC W FP] Package

Parameter	Symbol	Value	Unit	Test Conditions/Comments
Rated Dielectric Insulation Voltage		5.7	kV rms	1 minute duration
Minimum External Air Gap (Clearance)	L (I01)	8.3	mm min	Measured from input terminals to output terminals, shortest distance through air
Minimum External Tracking (Creepage)	L (102)	8.3	mm min	Measured from input terminals to output terminals, shortest distance path along body
Minimum Clearance in the Plane of the Printed Circuit Board (PCB Clearance)	L (PCB)	8.1	mm min	Measured from input terminals to output terminals, shortest distance through air, line of sight, in the PCB mounting plane
Minimum Internal Gap (Internal Clearance)		25.5	µm min	Insulation distance through insulation
Tracking Resistance (Comparative Tracking Index)	CTI	>600	V	Tested in accordance to IEC 60112
Material Group		1		Material Group per IEC 60664-1

Table 5. CP-32-32 Lead Frame Chip Scale Package [LFCSP]

Parameter	Symbol	Value	Unit	Test Conditions/Comments
Rated Dielectric Insulation Voltage		1.5	kV rms	1 minute duration
Minimum External Air Gap (Clearance)	L (I01)	1.27	mm min	Measured from input terminals to output terminals, shortest distance through air
Minimum External Tracking (Creepage)	L (102)	1.27	mm min	Measured from input terminals to output terminals, shortest distance path along body
Minimum Clearance in the Plane of the Printed Circuit Board (PCB Clearance)	L (PCB)	1.27	mm min	Measured from input terminals to output terminals, shortest distance through air, line of sight, in the PCB mounting plane
Minimum Internal Gap (Internal Clearance)		25.5	µm min	Insulation distance through insulation
Tracking Resistance (Comparative Tracking Index)	CTI	>600	V	Tested in accordance to IEC 60112
Material Group		1		Material Group per IEC 60664-1

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#### **SPECIFICATIONS**

#### PACKAGE CHARACTERISTICS

Table 6. RN-28-1 Wide Body with Finer Pitch [SOIC\_W\_FP] Package and CP-32-32 Lead Frame Chip Scale Package [LFCSP]

Parameter	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments
Resistance (Input to Output) <sup>1</sup>	R <sub>I-O</sub>		10 <sup>13</sup>		Ω	Voltage (input to output) (V <sub>I-O</sub> ) = 500 V dc
Capacitance (Input to Output) <sup>1</sup>	C <sub>I-O</sub>		2.2		pF	Frequency = 1 MHz
Input Capacitance <sup>2</sup>	CI		3.4		pF	

<sup>1</sup> The device is considered a 2-terminal device: Pin 1 through Pin 14 are shorted together (Pin 1 through Pin 16 for LFCSP), and Pin 15 through Pin 28 are shorted together (Pin 17 through Pin 32 for LFCSP).

#### REGULATORY INFORMATION

See Table 14 and the Insulation Lifetime section for details regarding the recommended maximum working voltages for specific cross-isolation waveforms and insulation levels.

Table 7. RN-28-1 Wide Body with Finer Pitch [SOIC W FP] Package

Regulatory Agency	Standard Certification/Approval	File
UL (Pending)	To be recognized under UL 1577 Component Recognition Program <sup>1</sup>	E214100
	Single protection, 5700 V rms isolation voltage	
CSA (Pending) <sup>2</sup>	To be approved under CSA Component Acceptance Notice 5A	205078
	CSA 62368-1-19, EN 62368-1:2020 and IEC 62368-1:2018 third edition	
	Basic insulation at 830 V rms	
	Reinforced insulation at 415 V rms	
	CSA 61010-1-12+A1 and IEC 61010-1 third edition	
	Basic insulation at 600 V rms	
	Reinforced insulation at 300 V rms	
	CSA 60601-1:14 and IEC60601-1 third edition+A1	
	2 means of patient protection (MOPP) for 261 V rms	
VDE (Pending)	To be certified according to DIN V VDE V 0884-11 (VDE V 0884-11):2017-01 <sup>3</sup>	2471900-4880-0001
	Reinforced insulation, V <sub>IORM</sub> = 849 V <sub>PEAK</sub> , V <sub>IOSM</sub> = 8000 V <sub>PEAK</sub>	
CQC (Pending)	To be certified according to GB4943.1-2011 per CQC11-471543-2015	Pending
	Basic insulation at 820 V rms (1159 V <sub>PEAK</sub> )	
	Reinforced insulation at 410 V rms (578 V <sub>PEAK</sub> )	

<sup>&</sup>lt;sup>1</sup> In accordance with UL 1577, each ADN4624 is proof tested by applying an insulation test voltage ≥6840 V rms for 1 sec.

Table 8. CP-32-32 Lead Frame Chip Scale Package [LFCSP]

Regulatory Agency	Standard Certification/Approval	File
UL (Pending)	To be recognized under UL 1577 Component Recognition Program <sup>1</sup>	E214100
	Single protection, 1500 V rms isolation voltage	
CSA (Pending)	To be approved under CSA Component Acceptance Notice 5A	205078
VDE (Pending)	To be certified according to DIN V VDE V 0884-11 (VDE V 0884-11):2017-01 <sup>2</sup>	2471900-4880-0001
	Reinforced insulation, V <sub>IORM</sub> = 560 V <sub>PEAK</sub> , V <sub>IOSM</sub> = 8000 V <sub>PEAK</sub>	
CQC (Pending)	To be certified according to GB4943.1-2011 per CQC11-471543-2015	Pending

<sup>&</sup>lt;sup>1</sup> In accordance with UL 1577, each ADN4624 is proof tested by applying an insulation test voltage ≥1800 V rms for 1 sec.

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<sup>&</sup>lt;sup>2</sup> Input capacitance is from any input data pin to ground.

<sup>&</sup>lt;sup>2</sup> Working voltages are quoted for Pollution Degree 2, Material Group III. ADN4624 case material has been evaluated by CSA as Material Group I.

In accordance with DIN V VDE V 0884-11, each ADN4624 is proof tested by applying an insulation test voltage ≥1592 V<sub>PEAK</sub> for 1 sec (partial discharge detection limit = 5 pC).

In accordance with DIN V VDE V 0884-11, each ADN4624 is proof tested by applying an insulation test voltage ≥1050 V<sub>PEAK</sub> for 1 sec (partial discharge detection limit = 5 pC).

### **SPECIFICATIONS**

### DIN V VDE V 0884-11 (VDE V 0884-11) INSULATION CHARACTERISTICS (PENDING)

This isolator is suitable for reinforced electrical isolation only within the safety limit data. Protective circuits ensure the maintenance of the safety data.

Table 9. RN-28-1 Wide Body with Finer Pitch [SOIC W FP] Package

Description	Test Conditions/Comments <sup>1</sup>	Symbol	Characteristic	Unit
Installation Classification per DIN VDE 0110				
For Rated Mains Voltage ≤ 150 V rms			I to IV	
For Rated Mains Voltage ≤ 300 V rms			I to IV	
For Rated Mains Voltage ≤ 600 V rms			I to IV	
Climatic Classification			40/125/21	
Pollution Degree per DIN VDE 0110, Table 1			2	
Maximum Working Insulation Voltage		V <sub>IORM</sub>	849	V <sub>PEAK</sub>
nput to Output Test Voltage, Method B1	$V_{IORM} \times 1.875 = V_{PD (M)}$ , 100% production test, $t_{INI} = t_M = 1$ sec, partial discharge < 5 pC	V <sub>PD (m)</sub>	1592	V <sub>PEAK</sub>
nput to Output Test Voltage, Method A		V <sub>PD (m)</sub>		
After Environmental Tests Subgroup 1	$V_{IORM} \times 1.5 = V_{PD (M)}$ , $t_{INI} = 60$ sec, $t_{M} = 10$ sec, partial discharge < 5 pC		1274	V <sub>PEAK</sub>
After Input or Safety Test Subgroup 2 and Subgroup 3	$V_{IORM} \times 1.2 = V_{PD (M)}$ , $t_{INI} = 60$ sec, $t_M = 10$ sec, partial discharge < 5 pC		1019	V <sub>PEAK</sub>
lighest Allowable Overvoltage		V <sub>IOTM</sub>	8000	$V_{PEAK}$
Surge Isolation Voltage				
Basic	V <sub>PEAK</sub> = 16 kV, 1.2 μs rise time, 50 μs, 50% fall time	V <sub>IOSM</sub>	16,000	$V_{PEAK}$
Reinforced	V <sub>PEAK</sub> = 16 kV, 1.2 μs rise time, 50 μs, 50% fall time	V <sub>IOSM</sub>	10000	V <sub>PEAK</sub>
Safety Limiting Values	Maximum value allowed in the event of a failure (see Figure 3)			
Maximum Junction Temperature		T <sub>S</sub>	150	°C
Total Power Dissipation at 25°C		Ps	2.74	W
nsulation Resistance at T <sub>S</sub>	V <sub>IO</sub> = 500 V	R <sub>S</sub>	>10 <sup>9</sup>	Ω

 $<sup>^{1}~</sup>$  For information about  $t_{\text{M}},\,t_{\text{INI}},$  and  $V_{\text{IO}},$  see DIN V VDE V 0884-11.

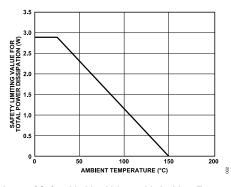


Figure 2. Thermal Derating Curve, Dependence of Safety Limiting Values with Ambient Temperature per DIN V VDE V 0884-11, SOIC\_W\_FP

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Table 10. CP-32-32 Lead Frame Chip Scale Package [LFCSP]

Description	Test Conditions/Comments <sup>1</sup>	Symbol	Characteristic	Unit
Installation Classification per DIN VDE 0110				
For Rated Mains Voltage ≤ 150 V rms			I to III	
For Rated Mains Voltage ≤ 300 V rms			I to II	
For Rated Mains Voltage ≤ 400 V rms			1	
Climatic Classification			40/125/21	
Pollution Degree per DIN VDE 0110, Table 1			2	
Maximum Working Insulation Voltage		V <sub>IORM</sub>	560	$V_{PEAK}$
Input to Output Test Voltage, Method B1	$V_{IORM} \times 1.875 = V_{PD~(M)}$ , 100% production test, $t_{INI} = t_M = 1$ sec, partial discharge < 5 pC	V <sub>PD (m)</sub>	1050	V <sub>PEAK</sub>
Input to Output Test Voltage, Method A		V <sub>PD (m)</sub>		
After Environmental Tests Subgroup 1	$V_{IORM} \times 1.5 = V_{PD (M)}$ , $t_{INI} = 60$ sec, $t_M = 10$ sec, partial discharge < 5 pC		840	V <sub>PEAK</sub>
After Input or Safety Test Subgroup 2 and Subgroup 3	$V_{IORM} \times 1.2 = V_{PD (M)}$ , $t_{INI} = 60$ sec, $t_M = 10$ sec, partial discharge < 5 pC		672	V <sub>PEAK</sub>
Highest Allowable Overvoltage		V <sub>IOTM</sub>	2500	V <sub>PEAK</sub>
Surge Isolation Voltage				
Basic	V <sub>PEAK</sub> = 16 kV, 1.2 μs rise time, 50 μs, 50% fall time	V <sub>IOSM</sub>	16,000	V <sub>PEAK</sub>
Reinforced	$V_{PEAK}$ = 16 kV, 1.2 µs rise time, 50 µs, 50% fall time	V <sub>IOSM</sub>	10000	V <sub>PEAK</sub>
Safety Limiting Values	Maximum value allowed in the event of a failure (see Figure 3)			
Maximum Junction Temperature		T <sub>S</sub>	150	°C
Total Power Dissipation at 25°C		P <sub>S</sub>	4.12	W
Insulation Resistance at T <sub>S</sub>	V <sub>IO</sub> = 500 V	R <sub>S</sub>	>109	Ω

 $<sup>^{1}~</sup>$  For information about  $t_{\text{M}},\,t_{\text{INI}},$  and  $V_{\text{IO}},$  see DIN V VDE V 0884-11.

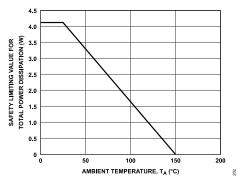


Figure 3. Thermal Derating Curve, Dependence of Safety Limiting Values with Ambient Temperature per DIN V VDE V 0884-11, LFCSP

### **RECOMMENDED OPERATING CONDITIONS**

Table 11.

Parameter	Symbol	Rating
Operating Temperature	T <sub>A</sub>	-40°C to +125°C
Supply Voltages	V <sub>DD1</sub> , V <sub>DD2</sub>	1.7 V to 1.9 V

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### **ABSOLUTE MAXIMUM RATINGS**

Table 12.

Parameter	Rating
V <sub>DD1</sub> to GND <sub>1</sub> /V <sub>DD2</sub> to GND <sub>2</sub>	-0.3 V to +2 V
Input Voltage REFRESH <sub>1</sub> to GND <sub>1</sub> /REFRESH <sub>2</sub> to GND <sub>2</sub>	-0.3 V to +2 V
Input Voltage ( $D_{INX^+}$ , $D_{INX^-}$ ) to $GND_x$ on the Same Side	-0.3 V to +4 V
Output Voltage ( $D_{OUTx+}$ , $D_{OUTx-}$ ) to $GND_x$ on the Same Side	-0.3 V to +2 V
Short-Circuit Duration ( $D_{OUTx+}, D_{OUTx-}$ ) to $GND_x$ on the Same Side	Continuous
Operating Temperature Range	-40°C to +125°C
Storage Temperature Range	-65°C to +150°C
Junction Temperature (T <sub>J</sub> Maximum)	150°C
Power Dissipation	$(T_J \text{ maximum} - T_A)/\theta_{JA}$

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

Table 13. Maximum Continuous Working Voltage<sup>1</sup>, RN-28-1 Wide Body with Finer Pitch ISOIC W FPI Package

Parameter	Rating	Constraint
AC Voltage		
Bipolar Waveform		
Basic Insulation	650 V rms	Basic insulation rating per IEC60747-17. Accumulative failure rate over lifetime (FROL) ≤ 1000 ppm at 20 years.
Reinforced Insulation	600 V rms	Reinforced insulation rating per IEC60747-17. Accumulative FROL ≤ 1 ppm at 26 years.
Unipolar Waveform		
Basic Insulation	1782 V <sub>PEAK</sub>	Rating limited by AC bipolar waveform accumulative FROL ≤ 1000 ppm at 20 years.
Reinforced Insulation	1330 V <sub>PEAK</sub>	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.
DC Voltage		
Basic Insulation	1660 V dc	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.
Reinforced Insulation	830 V dc	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.

Maximum continuous working voltage refers to the continuous voltage magnitude imposed across the isolation barrier in a Pollution Degree 2 environment. See the Insulation Lifetime section for more details.

Table 14. Maximum Continuous Working Voltage<sup>1</sup>, CP-32-32 Lead Frame Chip Scale Package [LFCSP]

Parameter	Rating	Constraint
AC Voltage		
Bipolar Waveform		
Basic Insulation	253 V rms	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.
Reinforced Insulation	63 V rms	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.
Unipolar Waveform		
Basic Insulation	413 V <sub>PEAK</sub>	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.
Reinforced Insulation	102 V <sub>PEAK</sub>	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.
DC Voltage		
Basic Insulation	253 V dc	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.
Reinforced Insulation	63 V dc	Rating limited by package creepage per IEC 60664-1 in Pollution Degree 2 environment.

<sup>1</sup> Maximum continuous working voltage refers to the continuous voltage magnitude imposed across the isolation barrier in a Pollution Degree 2 environment. See the Insulation Lifetime section for more details.

#### THERMAL RESISTANCE

Thermal performance is directly linked to PCB design and operation environment. Close attention to PCB thermal design is required.

 $\theta_{\text{JA}}$  is the natural convection junction to ambient thermal resistance measured in a one cubic foot sealed enclosure.

Table 15. Thermal Resistance

Package Type <sup>1</sup>	$\theta_{JA}$	Unit
RN-28-1	43.45	°C/W
CP-32-32	30.3	°C/W

Test Condition 1: thermal impedance simulated with 4-layer standard JEDEC PCB.

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### **ABSOLUTE MAXIMUM RATINGS**

### **ELECTROSTATIC DISCHARGE (ESD) RATINGS**

The following ESD information is provided for handling of ESD-sensitive devices in an ESD protected area only.

Human body model (HBM) per ANSI/ESDA/JEDEC JS-001.

International electrotechnical commission (IEC) electromagnetic compatibility: Part 4-2 (IEC) per IEC 61000-4-2.

### **ESD Ratings for ADN4624**

#### Table 16. ADN4624, 28-Lead SOIC W FP

ESD Model	Withstand Threshold (V)	Class
HBM <sup>1</sup>	±4000	3A
IEC <sup>2</sup>	±8000 (contact discharge)	Level 4

<sup>&</sup>lt;sup>1</sup> All pins to respective GNDx, 1.5 k $\Omega$ , 100 pF.

### Table 17. ADN4624, 32-Lead LFCSP

ESD Model	Withstand Threshold (V)	Class
HBM <sup>1</sup>	±4000	3A
IEC <sup>2</sup>	±2000 (contact discharge)	Level 1

 $<sup>^{1}~</sup>$  All pins to respective GNDx, 1.5 k $\Omega,$  100 pF.

#### **ESD CAUTION**



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

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<sup>&</sup>lt;sup>2</sup> LVDS pins to isolated GNDx across isolation barrier.

<sup>&</sup>lt;sup>2</sup> LVDS pins to isolated GNDx across isolation barrier.

### PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

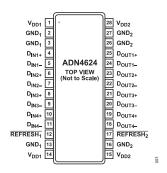


Figure 4. Pin Configuration, SOIC\_W\_FP

### Table 18. SOIC W FP Pin Function Descriptions

Pin No.	Mnemonic	Description
1, 14	V <sub>DD1</sub>	1.8 V Power Supply for Side 1. Connect both pins externally and bypass to GND <sub>1</sub> with 0.1 μF capacitors.
2, 3, 13	GND <sub>1</sub>	Ground, Side 1.
4	D <sub>IN1+</sub>	Noninverted Differential Input 1.
5	D <sub>IN1-</sub>	Inverted Differential Input 1.
6	D <sub>IN2+</sub>	Noninverted Differential Input 2.
7	D <sub>IN2</sub> -	Inverted Differential Input 2.
8	D <sub>IN3+</sub>	Noninverted Differential Input 3.
9	D <sub>IN3</sub> -	Inverted Differential Input 3.
10	D <sub>IN4+</sub>	Noninverted Differential Input 4.
11	D <sub>IN4-</sub>	Inverted Differential Input 4.
12	REFRESH₁	Active Low Enable for Side 1 Refresh Function. Short to GND <sub>1</sub> for normal operation with refresh enabled, or short to V <sub>DD1</sub> for lower power, lower jitter, and quieter operation with refresh disabled.
15, 28	$V_{DD2}$	1.8 V Power Supply for Side 2. Connect both pins externally and bypass to GND <sub>2</sub> with 0.1 μF capacitors.
16, 26, 27	GND <sub>2</sub>	Ground, Side 2.
17	REFRESH <sub>2</sub>	Active Low Enable for Side 1 Refresh Function. Short to GND <sub>2</sub> for normal operation with refresh enabled, or short to V <sub>DD2</sub> for lower power, lower jitter, and quieter operation with refresh disabled.
18	D <sub>OUT4-</sub>	Inverted Differential Output 4.
19	D <sub>OUT4+</sub>	Noninverted Differential Output 4.
20	D <sub>OUT3</sub> -	Inverted Differential Output 3.
21	D <sub>OUT3+</sub>	Noninverted Differential Output 3.
22	D <sub>OUT2</sub> -	Inverted Differential Output 2.
23	D <sub>OUT2+</sub>	Noninverted Differential Output 2.
24	D <sub>OUT1</sub> -	Inverted Differential Output 1.
25	D <sub>OUT1+</sub>	Noninverted Differential Output 1.

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### PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

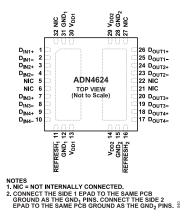


Figure 5. Pin Configuration, LFCSP

Table 19. LFCSP Pin Function Descriptions

Pin No.	Mnemonic	Description	
1	D <sub>IN1+</sub>	Noninverted Differential Input 1.	
2	D <sub>IN1</sub> -	Inverted Differential Input 1.	
3	D <sub>IN2+</sub>	Noninverted Differential Input 2.	
4	D <sub>IN2</sub> -	Inverted Differential Input 2.	
5, 6, 21, 22, 27, 32	NIC	Not Internally Connected. This pin is not internally connected.	
7	D <sub>IN3+</sub>	Noninverted Differential Input 3.	
8	D <sub>IN3</sub> -	Inverted Differential Input 3.	
9	D <sub>IN4+</sub>	Noninverted Differential Input 4.	
10	D <sub>IN4-</sub>	Inverted Differential Input 4.	
11	REFRESH <sub>1</sub>	Active Low Enable for Side 1 Refresh Function. Short to GND <sub>1</sub> for normal operation with refresh enabled, or short to V <sub>DD1</sub> for lower power, lower jitter, and quieter operation with refresh disabled.	
12, 31	GND <sub>1</sub>	Ground, Side 1.	
13, 30	V <sub>DD1</sub>	1.8 V Power Supply for Side 1. Connect both pins externally and bypass to GND <sub>1</sub> with 0.1 μF capacitors.	
14, 29	V <sub>DD2</sub>	1.8 V Power Supply for Side 2. Connect both pins externally and bypass to $\text{GND}_2$ with 0.1 $\mu\text{F}$ capacitors.	
15, 28	GND <sub>2</sub>	Ground, Side 2.	
16	REFRESH <sub>2</sub>	Active Low Enable for Side 1 Refresh Function. Short to GND <sub>2</sub> for normal operation with refresh enabled, or short to V <sub>DD2</sub> for lower power, lower jitter, and quieter operation with refresh disabled.	
17	D <sub>OUT4-</sub>	Inverted Differential Output 4.	
18	D <sub>OUT4+</sub>	Noninverted Differential Output 4.	
19	D <sub>OUT3-</sub>	Inverted Differential Output 3.	
20	D <sub>OUT3+</sub>	Noninverted Differential Output 3.	
23	D <sub>OUT2</sub>	Inverted Differential Output 2.	
24	D <sub>OUT2+</sub>	Noninverted Differential Output 2.	
25	D <sub>OUT1-</sub>	Inverted Differential Output 1.	
26	D <sub>OUT1+</sub>	Noninverted Differential Output 1.	
	EPAD	Exposed Pad. Connect the Side 1 EPAD to the same PCB ground as the GND <sub>1</sub> pins. Connect the Side 2 EPAD to the same PCB ground as the GND <sub>2</sub> pins.	

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### TYPICAL PERFORMANCE CHARACTERISTICS

 $V_{DD1} = V_{DD2} = 1.8 \text{ V}, T_A = 25^{\circ}\text{C}, \overline{\text{REFRESH}_1} = \text{GND}_1, \overline{\text{REFRESH}_2} = \text{GND}_2, R_L = 100 \ \Omega, 1.25 \ \text{GHz} \ \text{clock input with} \ |V_{ID}| = 200 \ \text{mV}, V_{IC} = 1.2 \ \text{V}, \text{ and } t_R \text{ and } t_F < 0.05 \ \text{ns}, \text{ unless otherwise noted}.$ 

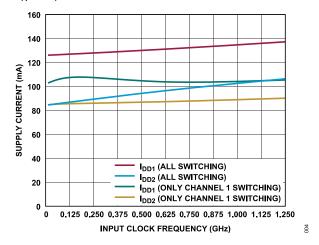


Figure 6. Supply Current vs. Input Clock Frequency

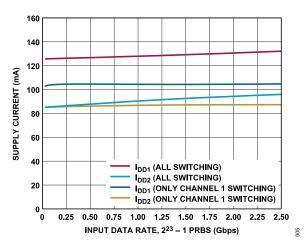


Figure 7. Supply Current vs. Input Data Rate, 223 - 1 PRBS

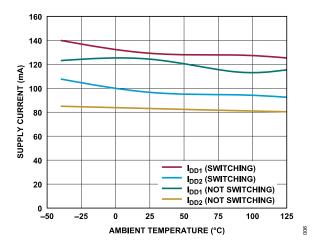


Figure 8. Supply Current vs. Ambient Temperature

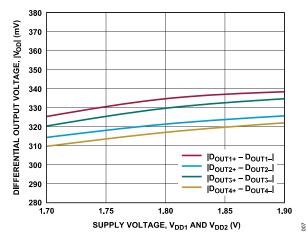


Figure 9. Differential Output Voltage,  $|V_{OD}|$  vs. Supply Voltage,  $V_{DD1}$  and  $V_{DD2}$ 

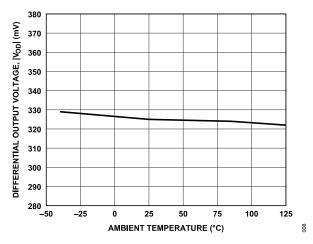


Figure 10. Differential Output Voltage,  $|V_{OD}|$  vs. Ambient Temperature

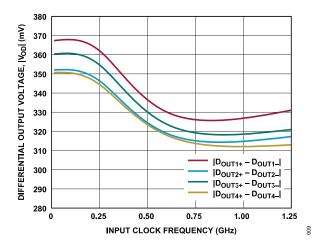


Figure 11. Differential Output Voltage, |VoD| vs. Input Clock Frequency

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### TYPICAL PERFORMANCE CHARACTERISTICS

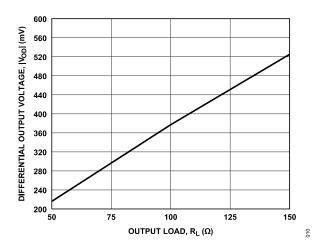


Figure 12. Differential Output Voltage,  $|V_{OD}|$  vs. Output Load,  $R_L$  (DC Input)

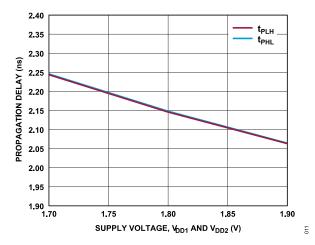


Figure 13. Propagation Delay vs. Supply Voltage,  $V_{DD1}$  and  $V_{DD2}$ 

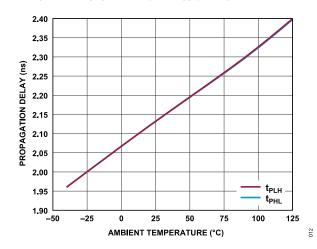


Figure 14. Propagation Delay vs. Ambient Temperature

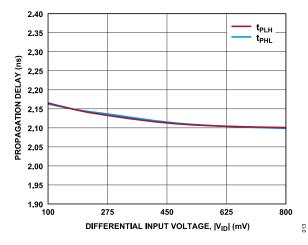


Figure 15. Propagation Delay vs. Differential Input Voltage,  $|V_{ID}|$ 

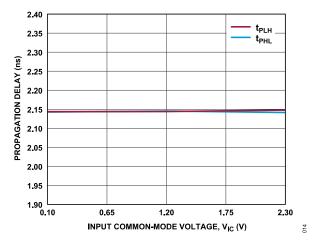


Figure 16. Propagation Delay vs. Input Common-Mode Voltage, V<sub>IC</sub>

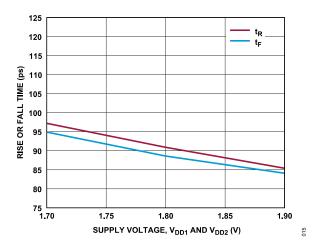


Figure 17. Rise or Fall Time vs. Supply Voltage,  $V_{DD1}$  and  $V_{DD2}$ 

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### TYPICAL PERFORMANCE CHARACTERISTICS

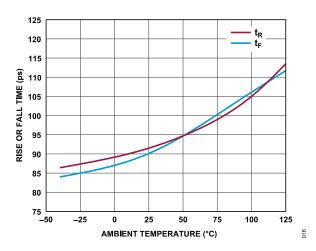


Figure 18. Rise or Fall Time vs. Ambient Temperature

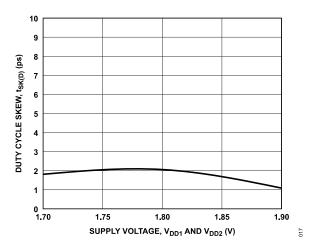


Figure 19. Duty Cycle Skew,  $t_{SK(D)}$  vs. Supply Voltage,  $V_{DD1}$  and  $V_{DD2}$ 

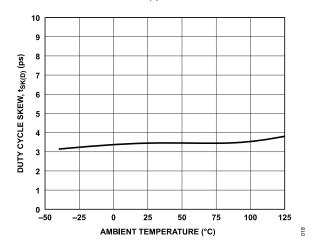


Figure 20. Duty Cycle Skew,  $t_{SK(D)}$  vs. Ambient Temperature

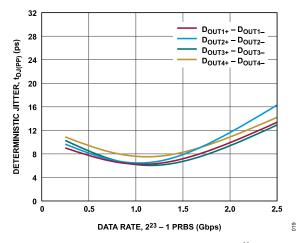


Figure 21. Deterministic Jitter,  $t_{DJ(PP)}$  vs. Data Rate,  $2^{23}$  – 1 PRBS

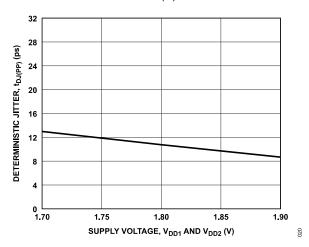


Figure 22. Deterministic Jitter,  $t_{\rm DJ(PP)}$  vs. Supply Voltage,  $V_{\rm DD1}$  and  $V_{\rm DD2}$ 

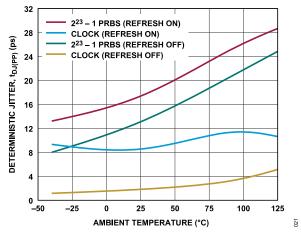


Figure 23. Deterministic Jitter,  $t_{\mathrm{DJ(PP)}}$  vs. Ambient Temperature

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### **TYPICAL PERFORMANCE CHARACTERISTICS**

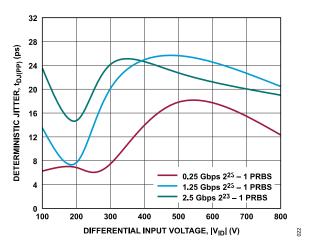


Figure 24. Deterministic Jitter,  $t_{DJ(PP)}$  vs. Differential Input Voltage,  $|V_{ID}|$ 

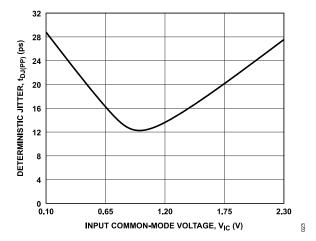


Figure 25. Deterministic Jitter,  $t_{\text{DJ(PP)}}$  vs. Input Common-Mode Voltage,  $V_{\text{IC}}$ 

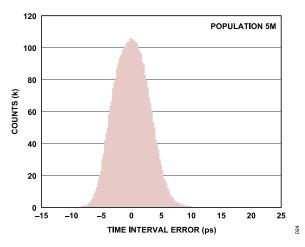


Figure 26. Time Interval Error (TIE) Histogram for D<sub>OUT1±</sub> at 1.25 GHz

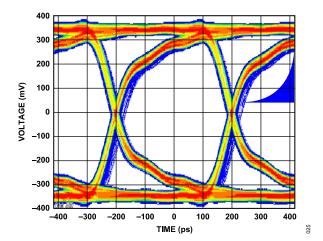


Figure 27. Eye Diagram for  $D_{OUT1\pm}$  at 1.25 GHz

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### **TEST CIRCUITS AND SWITCHING CHARACTERISTICS**

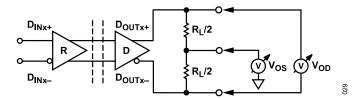


Figure 28. Driver Test Circuit

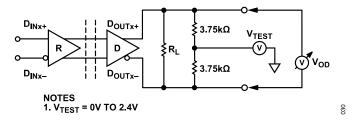


Figure 29. Driver Test Circuit (Full Load Across Common-Mode Range)

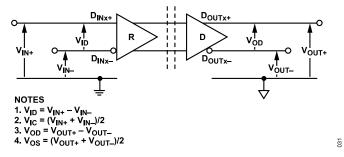


Figure 30. Voltage Definitions

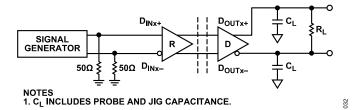


Figure 31. Timing Test Circuit

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#### THEORY OF OPERATION

The ADN4624 is a high speed differential signal isolator capable of switching up to 2.5 Gbps with signal levels compliant to TIA/ EIA-644-A. The device couples differential signals applied to the LVDS receiver inputs across the isolation barrier to the outputs on the other side and re-transmits the bit stream or clock as LVDS. This integration allows drop-in isolation of LVDS signal chains and isolation of other signals such as CML.

The LVDS receiver detects the differential voltage present across a termination resistor on an LVDS input. An integrated digital isolator transmits the input state across the isolation barrier, and an LVDS driver outputs the same state as the input.

When there is a positive differential voltage of  $\geq 100$  mV across a termination resistor between any  $D_{INX+}$  pin and a corresponding  $D_{INX-}$  pin, the corresponding  $D_{OUTX+}$  pin sources current. This current flows across the connected transmission line and termination at the receiver at the far end of the bus, while  $D_{OUTX-}$  sinks the return current. When there is a negative differential voltage of  $\leq -100$  mV across any  $D_{INX\pm}$  pin, the corresponding  $D_{OUTX+}$  pin sinks current with the  $D_{OUTX-}$  pin sourcing the current. Table 20 shows these input and output combinations.

The output drive current is between  $\pm 2.5$  mA and  $\pm 4.5$  mA (typically  $\pm 3.1$  mA), developing between  $\pm 250$  mV and  $\pm 450$  mV across a 100  $\Omega$  termination resistor (R<sub>T</sub>). The received voltage is centered around 1.2 V. Because the differential voltage (V<sub>ID</sub>) reverses polarity, the peak-to-peak voltage swing across R<sub>T</sub> is twice the differential voltage magnitude (|V<sub>ID</sub>|).

#### ISOLATION AND REFRESH

In response to any change in the input state detected by the integrated LVDS receiver, an encoder circuit sends narrow (~1 ns) pulses to a decoder circuit using integrated transformer coils. The decoder is bistable and is, therefore, either set or reset by the pulses that indicate input transitions. The decoder state determines the LVDS driver output state in normal operation, which reflects the isolated LVDS buffer input state.

For normal operation of the ADN4624, the active low enable pins,  $\overline{REFRESH_1}$  and  $\overline{REFRESH_2}$ , are shorted to  $GND_1$  and  $GND_2$ , respectively, to enable a refresh function. When enabled, this function means that in the absence of input transitions for more than approximately 1  $\mu s$ , a periodic set of refresh pulses, indicative of the correct input state, ensures dc correctness at the output (including the fail-safe output state, if applicable).

On power-up, the output state may initially be in the incorrect dc state if there are no input transitions. The output state is corrected within 1  $\mu$ s by the refresh pulses.

If the decoder receives no internal pulses for more than approximately 1  $\mu$ s, the device assumes that the input side is unpowered or nonfunctional, in which case, the output is set to a positive differential voltage (logic high).

For clocks, constant bit streams, or protocols with error correction, the refresh functionality may not be required. If REFRESH<sub>1</sub> and REFRESH<sub>2</sub> are shorted to VDD1 and VDD2, respectively, the refresh functionality is disabled, allowing for lower power operation with no internal clock-like signals (potentially reducing conducted or radiated emissions). In this mode of operation, a new data transition at the input may be required to correct the output state, either after power-up or after a common-mode transient event beyond the guaranteed common-mode transient immunity specification.

#### **TRUTH TABLE**

The LVDS standard, TIA/EIA-644-A, defines normal receiver operation under two conditions: an input differential voltage of ≥+100 mV corresponding to one logic state, and a voltage of ≤-100 mV for the other logic state. Between these thresholds, the standard LVDS receiver operation is undefined (the LVDS receiver can detect either state), as shown in Table 20.

Table 20. Input and Output Operation

Input (D <sub>INx±</sub> )			Output (D <sub>OUTx±</sub> )		
Powered On	V <sub>ID</sub> (mV)	Logic	Powered On	V <sub>OD</sub> (mV)	Logic
Yes	≥100	High	Yes	≥250	High
Yes	≤−100	Low	Yes	≤-250	Low
Yes	-100 < V <sub>ID</sub> < +100	Indeterminate	Yes	Indeterminate	Indeterminate
No	Don't care	Don't care	Yes	≥250	High

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#### **APPLICATIONS INFORMATION**

#### **PCB LAYOUT**

The ADN4624 can operate with high speed LVDS signals up to 1.25 GHz clock, or 2.5 Gbps nonreturn to zero (NRZ) data. When operating with such high frequencies, apply best practices for the LVDS trace layout and termination. Place a 100  $\Omega$  termination resistor as close as possible to the receiver, across the  $D_{\text{INx+}}$  and  $D_{\text{INx-}}$  pins.

Controlled impedance traces (100  $\Omega$  differential) are needed on LVDS signal lines for full signal integrity, reduced system jitter, and for minimizing electromagnetic interference (EMI) from the PCB. Trace widths, lateral distance within each pair, and distance to the ground plane underneath all must be chosen appropriately. Via fencing to the PCB ground between pairs is also a best practice to minimize crosstalk between adjacent pairs.

The ADN4624 pass EN 55032 Class B emissions limits without extra considerations required for the isolator when operating with up to 2 Gbps PRBS data. When isolating at higher data rates or for high speed clocks, specific PCB layout measures may be required to reduce dipole antenna effects from the isolation gap and provide sufficient margin below Class B emissions limits.

The best practice for high speed PCB design avoids emissions from traces with high speed LVDS signals. Special care is recommended for off board connections, where switching transients from high speed LVDS signals (and clocks in particular) may conduct onto cabling, resulting in radiated emissions. Use common-mode chokes, ferrites, or other filters as appropriate at LVDS connectors and power supplies, as well as cable shield or PCB ground connections to earth or chassis.

The ADN4624 requires appropriate decoupling of the V<sub>DDx</sub> pins with 100 nF capacitors. Power supplies must also have appropriate filtering to avoid possible radiated emissions due to high frequency switching noise.

#### **APPLICATION EXAMPLES**

High speed LVDS interfaces for the analog front-end (AFE), processor to processor serial communication, or video and imaging

data can be isolated using the ADN4624 between components, between boards, or at a cable interface.

The ADN4624 provides the galvanic isolation required for robust external ports, and the low jitter and high drive strength of the device allow communication along short cable runs of a few meters. High common-mode immunity ensures communication integrity even in harsh, noisy environments, and isolation can protect against electromagnetic compatibility (EMC) transients up to ±8 kV<sub>PEAK</sub>, such as ESD, electrical fast transient (EFT), and surge.

Standard LVDS inputs and outputs allow simple integration into high speed signal chains using field-programmable gate arrays (FPGAs), redrivers, or coupling networks to interface to CML and other physical layers. The ADN4624 can isolate a range of video and imaging protocols, including protocols that use CML rather than LVDS for the physical layer.

One example is High-Definition Multimedia Interface (HDMI), where ac coupling and biasing and termination resistor networks are used, as shown in Figure 32 to convert between CML (used by the transition minimized differential signaling (TMDS) data and clock lanes) and the LVDS levels required by the ADN4624. Additional Analog Devices isolator components, such as the ADuM2250 and ADuM2251 I<sup>2</sup>C isolators, can be used to isolate control signals and power (ADuM6421A and ADuM6028 *iso*Power integrated, isolated dc-to-dc converter). This circuit supports resolutions up to 1080p.

Other coupling networks, processing nodes, and translation circuits can use the ADN4624 as part of an overall signal chain to isolate MIPI CSI-2, DisplayPort, and LVDS-based protocols such as FPD-Link. Use of an FPGA or an application-specific integrated circuit (ASIC) serializer/deserializer (SERDES) expands bandwidth through multiple ADN4624 devices to support 1080p or 4K video resolutions, providing an alternative to short reach fiber links.

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### **APPLICATIONS INFORMATION**

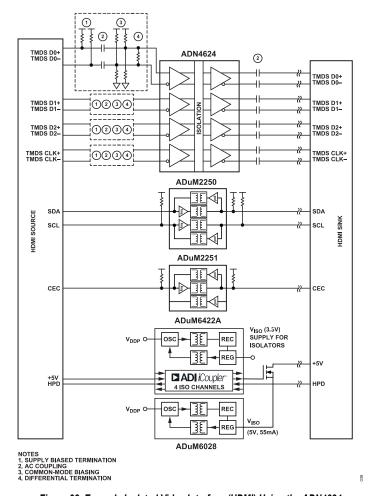


Figure 32. Example Isolated Video Interface (HDMI) Using the ADN4624

#### **MAGNETIC FIELD IMMUNITY**

The limitation on the magnetic field immunity of the device is set by the condition in which the induced voltage in the transformer receiving coil is sufficiently large, either to falsely set or reset the decoder. The following analysis defines such conditions. The ADN4624 is examined in a 1.7 V operating condition because this operating condition represents the most susceptible mode of operation for these products.

The pulses at the transformer output have an amplitude greater than 0.35 V. The decoder has a sensing threshold of about 0.11 V, therefore establishing a 0.24 V margin in which induced voltages are tolerated.

The voltage (V) induced across the receiving coil is given by

$$V = (-d\beta/dt) \sum_{n} \pi r_n^2; n = 1, 2, ..., N$$
 (1)

where:

 $d\beta$  is the change in magnetic flux density.

dt is the change in time.

 $r_n$  is the radius of the  $n^{th}$  turn in the receiving coil.

*N* is the number of turns in the receiving coil.

Given the geometry of the receiving coil in the ADN4624 and an imposed requirement that the induced voltage be, at most, 50% of the 0.11 V threshold at the decoder, a maximum allowable external magnetic flux density is calculated as shown in Figure 33.

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#### **APPLICATIONS INFORMATION**

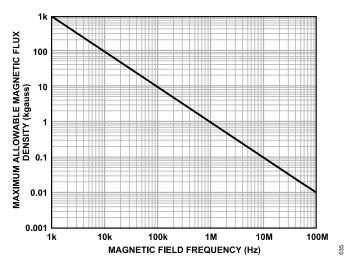


Figure 33. Maximum Allowable External Magnetic Flux Density

For example, at a magnetic field frequency of 1 MHz, the maximum allowable magnetic field of 1.06 kgauss induces a voltage of 0.055 V at the receiving coil. This voltage is about 50% of the sensing threshold and does not cause a faulty output transition. If such an event occurs with the worst case polarity during a transmitted pulse, the applied magnetic field reduces the received pulse from >0.35 V to 0.295 V. This voltage is still higher than the 0.11 V sensing threshold of the decoder.

The preceding magnetic flux density values correspond to specific current magnitudes at given distances from the ADN4624 transformers. Figure 34 expresses these allowable current magnitudes as a function of frequency for selected distances. The ADN4624 is insensitive to external fields. Only extremely large, high frequency currents that are close to the component can potentially be a concern. For the 1 MHz example noted, a 2.64 kA current must be placed 5 mm from the ADN4624 to affect component operation.

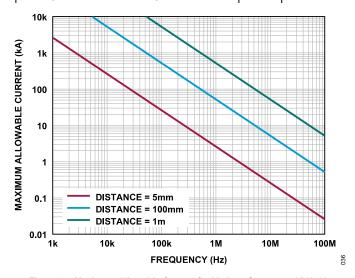


Figure 34. Maximum Allowable Current for Various Current to ADN4624 Spacings

In combinations of strong magnetic field and high frequency, any loops formed by PCB traces can induce sufficiently large error voltages to trigger the thresholds of succeeding circuitry. Avoid PCB structures that form loops.

#### **INSULATION LIFETIME**

All insulation structures eventually break down when subjected to voltage stress over a sufficiently long period. The rate of insulation degradation is dependent on the characteristics of the voltage waveform applied across the insulation as well as on the materials and material interfaces.

The two types of insulation degradation of primary interest are breakdown along surfaces exposed to the air and insulation wear out. Surface breakdown is the phenomenon of surface tracking and the primary determinant of surface creepage requirements in system level standards. Insulation wear out is the phenomenon where charge injection or displacement currents inside the insulation material cause long-term insulation degradation.

### **Surface Tracking**

Surface tracking is addressed in electrical safety standards by setting a minimum surface creepage based on the working voltage, the environmental conditions, and the properties of the insulation material. Safety agencies perform characterization testing on the surface insulation of components, which allows the components to be categorized in different material groups. Lower material group ratings are more resistant to surface tracking and, therefore, can provide adequate lifetime with smaller creepage. The minimum creepage for a given working voltage and material group is in each system level standard and is based on the total rms voltage across the isolation barrier, pollution degree, and material group. The material group and creepage for ADN4624 are detailed in Table 5.

### **Insulation Wear Out**

The lifetime of insulation caused by wear out is determined by the thickness of the insulation, material properties, and the voltage stress applied. It is important to verify that the product lifetime is adequate at the application working voltage. The working voltage supported by an isolator for wear out may not be the same as the working voltage supported for tracking. The working voltage applicable to tracking is specified in most standards.

Testing and modeling show that the primary driver of long-term degradation is displacement current in the polyimide insulation causing incremental damage. The stress on the insulation can be broken down into broad categories, such as dc stress, which causes little wear out because there is no displacement current, and an ac component time varying voltage stress, which causes wear out.

The ratings in certification documents are usually based on 60 Hz sinusoidal stress because this type of waveform reflects isolation from line voltage. However, many practical applications have com-

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### **APPLICATIONS INFORMATION**

binations of 60 Hz ac and dc across the isolation barrier, as shown in Equation 1. Because only the ac portion of the stress causes wear out, the equation can be rearranged to solve for the ac rms voltage, as shown in Equation 2. For insulation wear out with the polyimide materials used in this product, the ac rms voltage determines the product lifetime.

$$V_{RMS} = \sqrt{V_{AC RMS}^2 + V_{DC}^2}$$
 (1)

or

$$V_{AC\ RMS} = \sqrt{V_{RMS}^2 - V_{DC}^2}$$
 (2)

where

 $V_{RMS}$  is the total rms working voltage.

 $V_{AC\ RMS}$  is the time varying portion of the working voltage.

 $V_{DC}$  is the dc offset of the working voltage.

### **Calculation and Use of Parameters Example**

The following example frequently arises in power conversion applications. Assume that the line voltage on one side of the isolation is 240 V ac rms and a 400 V dc bus voltage is present on the other side of the isolation barrier. The isolator material is polyimide. To establish the critical voltages in determining the creepage, clearance, and lifetime of a device, see Figure 35 and the following equations.

The working voltage across the barrier from Equation 1 is

$$V_{RMS} = \sqrt{V_{AC RMS}^2 + V_{DC}^2} \tag{2}$$

$$V_{RMS} = \sqrt{240^2 + 400^2} \tag{3}$$

$$V_{RMS} = 466 \text{ V}$$

This  $V_{RMS}$  value is the working voltage used together with the material group and pollution degree when looking up the creepage required by a system standard.

To determine if the lifetime is adequate, obtain the time varying portion of the working voltage. To obtain the ac rms voltage, use Equation 2.

$$V_{AC\ RMS} = \sqrt{V_{RMS}^2 - V_{DC}^2} \tag{4}$$

$$V_{AC\ RMS} = \sqrt{466^2 - 400^2} \tag{5}$$

 $V_{AC\ RMS}$  = 240 V rms

In this case, the ac rms voltage is simply the line voltage of 240 V rms. This calculation is more relevant when the waveform is not sinusoidal. Table 14 compares the value to the limits for the working voltage for the expected lifetime. Note that the dc working voltage limit in Table 14 is set by the creepage of the package as specified in IEC 60664-1. This value can differ for specific system level standards.

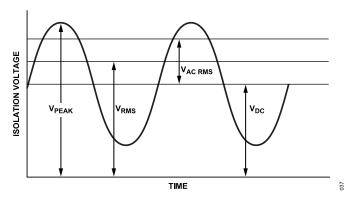


Figure 35. Critical Voltage Example

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### **OUTLINE DIMENSIONS**

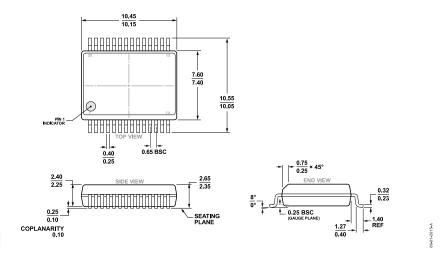


Figure 36. 28-Lead Standard Small Outline, Wide Body, with Finer Pitch [SOIC\_W\_FP]
(RN-28-1)
Dimensions shown in millimeters

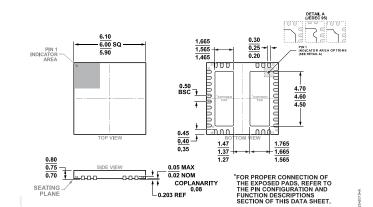


Figure 37. 32-Lead Lead Frame Chip Scale Package [LFCSP] 6 mm × 6 mm Body and 0.75 mm Package Height (CP-32-32)

Dimensions shown in millimeters

### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Packing Quantity	Package Option
ADN4624BRNZ	-40°C to +125°C	28-Lead SOIC (Wide, Finer Pitch)	Tube, 46	RN-28-1
ADN4624BRNZ-RL	-40°C to +125°C	28-Lead SOIC (Wide, Finer Pitch)	Reel, 1000	RN-28-1
ADN4624BCPZ	-40°C to +125°C	32-Lead LFCSP (6 mm x 6 mm)	Tray, 490	CP-32-32
ADN4624BCPZ-RL	-40°C to +125°C	32-Lead LFCSP (6 mm x 6 mm)	Reel, 2500	CP-32-32

<sup>&</sup>lt;sup>1</sup> Z = RoHS Compliant Part.

### **EVALUATION BOARDS**

Model <sup>1</sup>	Description
EVAL-ADN4624EB1Z	ADN4624 SOIC_W_FP Evaluation Board

<sup>&</sup>lt;sup>1</sup> Z = RoHS Compliant Part.



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