

## 512kb EEPROM – CAT25512 – Trēo™ Module

### Module Features

- On Semiconductor CAT25512
- RoHS Compliant
- Software Library
- NightShade Trēo™ Compatible
- Breakout Headers

### CAT25512 Features

(from On Semiconductor)

- 128-byte Page Write Buffer
- Additional Identification Page with Permanent Write Protection
- Self-timed Write Cycle
- Hardware and Software Protection
- Block Write Protection
  - Protect ¼, ½, or Full EEPROM Array
- Low Power CMOS Technology
- 4,000,000 Program/Erase Cycles
- 200 Year Data Retention



### Description

The CAT25512 Trēo™ Module is a 512kb EEPROM module that features On Semiconductor's CAT25512 EEPROM IC. It features 512kb of memory, an identification memory page, memory protection levels, and communication speeds up to 10MHz. This module is a part of the NightShade Treo system, patent pending.

### Applications

- Non-Volatile Data Storage
- Setting Retention
- Authentication

### Trēo™ Compatibility

#### Electrical

<b>Communication</b>	SPI
<b>Max Current, 3.3V</b>	2mA
<b>Max Current, 5V</b>	0mA

#### Mechanical

- 25mm x 25mm Outline
- 20mm x 20mm Hole Pattern
- M2.5 Mounting Holes

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## 1 Summary

The CAT25512 device is written to and read from using local memory buffers to stage a complete memory transaction. The device is initialized with the `begin()` method. A write operation is started with the `startMemoryWrite()` method. The transmit buffer is then loaded with the bytes to be written using the `write()` method. Finally, the data is written to the EEPROM by calling the `endMemoryWrite()` method. Similarly, a read operation is performed by calling the `requestMemoryRead()` method, which reads data from the EEPROM into a local receive buffer. The data is retrieved from the received buffer by using the `read()` method. The other library methods can be used to enable partial or full write protection and access the 128 byte identification page of the EEPROM.

## 2 What is Trēo™?

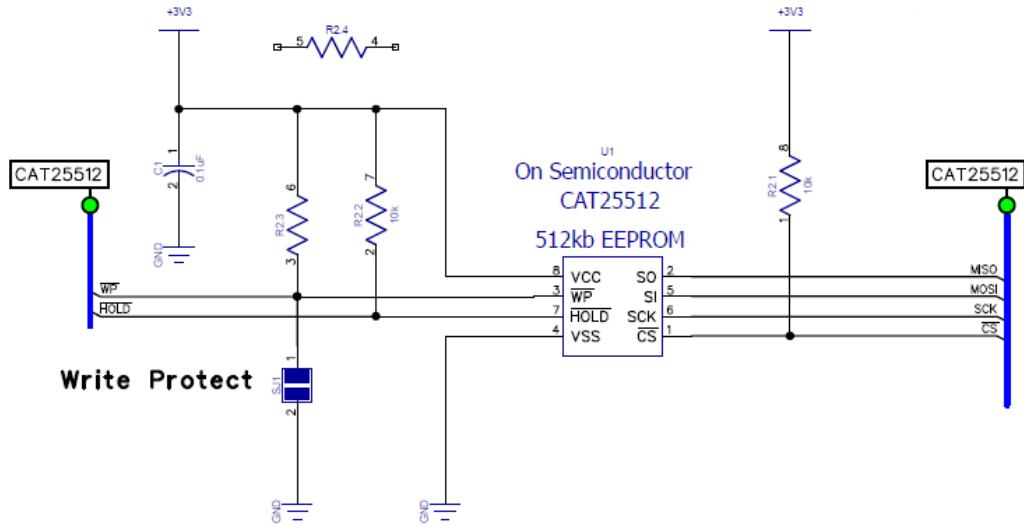
NightShade Trēo is a system of electronic modules that have standardized mechanical, electrical, and software interfaces. It provides you with a way to quickly develop electronic systems around microprocessor development boards. The grid attachment system, common connector/cabling, and extensive cross-platform software library allow you more time to focus on your application. Trēo is supported with detailed documentation and CAD models for each device.

Learn more about Trēo [here](#).

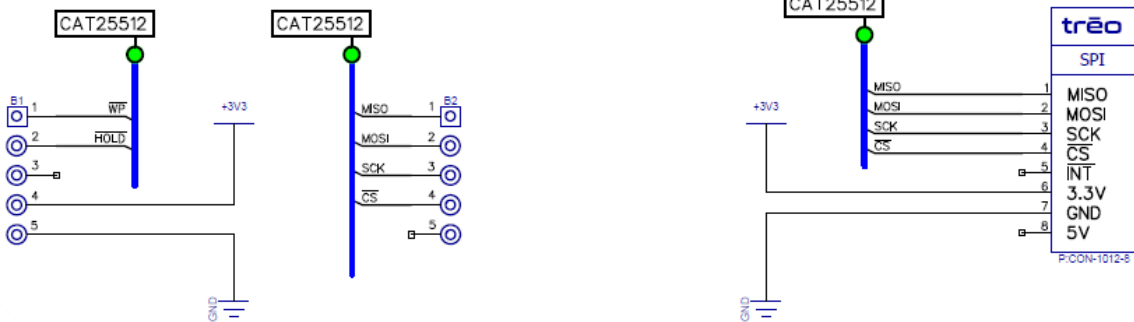
## 3 Electrical Characteristics

	Minimum	Nominal	Maximum
<b>Voltages</b>			
$V_{i/o}$ (MISO, MOSI, SCK, $\overline{CS}$ )	-0.3V	-	3.6V
$V_{3.3V}$	3.1V	3.3V	3.5V
<b>Communication</b>			
SPI Clock Speed	DC	-	10MHz
<b>Operating Temperature</b>	-25°C	-	+85°C

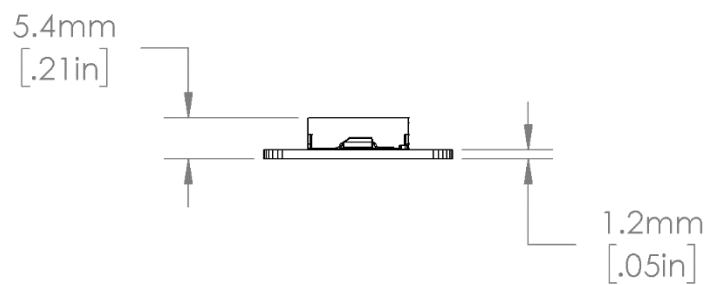
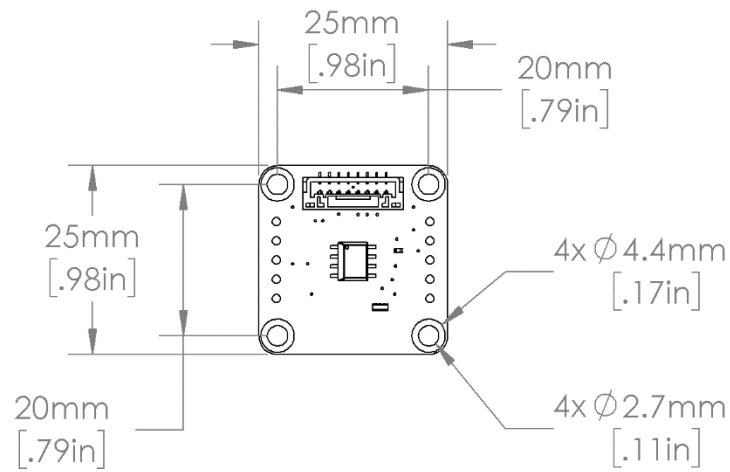
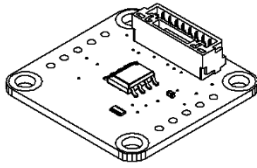
## 4 Electrical Schematic



### Breakout Headers



## 5 Mechanical Outline



## 6 Example Arduino Program

```
/******  
CAT25512_EEPROM - NightShade_Treo by NightShade Electronics  
  
This sketch demonstrates the functionality of the  
NightShade Trēo CAT25512 EEPROM module. (NSE-1138-1) It  
performs write and read cycles, playing "telephone" with  
the EEPROM.  
  
Created by Aaron D. Liebold  
on February 15, 2021  
  
Links:  
NightShade Trēo System: https://nightshade.net/treo  
Product Page: https://nightshade.net/product/treo-512kb-EEPROM-CAT25512/  
  
Distributed under the MIT license  
Copyright (C) 2021 NightShade Electronics  
https://opensource.org/licenses/MIT  
*****/  
  
#include <NightShade_Treo.h>  
  
NightShade_Treo_CAT25512 eeprom(1, 10);  
  
char buffer[128] = "Only 128 bytes can be read or written to the CAT25512 EEPROM at a  
time. This is called a page write/read.....128B";  
  
void setup() {  
  Serial.begin(115200);  
  Serial.print("Initial character string: \");  
  Serial.print(buffer);  
  Serial.println('\n');  
  eeprom.begin();  
}  
  
void loop() {  
  Serial.println("\nWriting last string to memory...");  
  eeprom.startMemoryWrite(0x00);  
  for (int x = 0; x < 128; ++x) eeprom.write(buffer[x]);  
  eeprom.endMemoryWrite();  
  Serial.println("Clearing software buffer.");  
  for (int x = 0; x < 128; ++x) buffer[x] = 0;  
  Serial.println("Buffer cleared.");  
  Serial.println("Reading memory.");  
  eeprom.requestMemoryRead(0x00, 128);  
  for (int x = 0; x < 128; ++x) buffer[x] = eeprom.read();  
  Serial.println("String read from EEPROM:");  
  for (int x = 0; x < 128; ++x) Serial.write(buffer[x]);  
  Serial.println();  
}
```



```
delay(500);  
}
```



## 7 Library Overview (C++ & Python)

### C++ Class

```
NightShade_Treo_CAT25512<classObject>();
```

### Python Module

```
<classObject> = NightShade_Treo.CAT25512()
```

### 7.1 Constructors

#### NightShade\_Treo\_CAT25512(int spiPort, chipSelectPin, uint32\_t spiClockSpeed)

Creates a CAT25512 object.

Arguments:

spiPort	Integer of the SPI port used (e.g. 0 = "/dev/spi_0")
chipSelectPin	Number of the pin connected to the chip select
spiClock	Desired clock speed for the bus

Returns:

Nothing

#### NightShade\_Treo\_CAT25512(int spiPort, int chipSelectPin)

Creates a CAT25512 object assuming the default clock speed.

Arguments:

port	Integer of the I2C port used. (e.g. 0 = "/dev/i2c_0")
------	-------------------------------------------------------

Returns:

Nothing

### 7.2 Methods

#### begin()

Initializes the CAT25512 and enables write operations.

Arguments:

None

Returns:

Error	0 = Success
-------	-------------



**startMemoryWrite(int startAddress)**

Clears the local transmit buffer to start a new write operation and enables write operations.

Arguments:

startAddress                      EEPROM write address (0 – 0xFFFF)

Returns:

Error                                0 = Success

**write(uint8\_t byte)**

Appends a byte to the local transmit buffer.

Arguments:

byte                                 byte of data to be written

Returns:

Error                                0 = Success

**txAvailable()**

Returns the number of bytes in the local transmit buffer.

Arguments:

None

Returns:

Error                                0 = Success

**endMemoryWrite()**

Writes the data in the local transmit buffer to the EEPROM at the startAddress set with the startMemoryWrite() method.

Arguments:

None

Returns:

Error                                0 = Success

**requestMemoryRead(uint16\_t startAddress, int numberOfBytes)**

Reads a block of data from the EEPROM into the local receive buffer.

Arguments:

startAddress                      first address of the memory read  
numberOfBytes                    number of bytes to read sequentially from the start address

Returns:

Error                                0 = Success







**setProtectionLevel(int protectionLevel)**

The EEPROM memory can be write protected in block with different protection levels.

Arguments:

protectionLevel	0: No Protection	
	1: Quarter Array Protection	0xC000 – 0xFFFF
	2: Half Array Protection	0x8000 – 0xFFFF
	3: Full Array Protection	0x0000 – 0xFFFF

Returns:

Error                      0 = Success

**writeStatusReg(uint8\_t regValue)**

Write the Status register value.

Arguments:

regValue                      Status register value

Returns:

Error                      0 = Success

**readStatusReg()**

Read the current value of the Status register.

Arguments:

None

Returns:

Status register value (uint8\_t)