

# Low Voltage Compandor SA575

The SA575 is a precision dual gain control circuit designed for low voltage applications. The SA575's channel 1 is an expandor, while channel 2 can be configured either for expandor, compressor, or automatic level controller (ALC) application.

#### Features

- Operating Voltage Range from 3.0 V to 7.0 V
- Reference Voltage of 100 mV<sub>RMS</sub> = 0 dB
- One Dedicated Summing Op Amp Per Channel and Two Extra Uncommitted Op Amps
- 600 Ω Drive Capability
- Single or Split Supply Operation
- Wide Input/Output Swing Capability
- These Devices are Pb-Free, Halogen Free/BFR Free and are RoHS Compliant

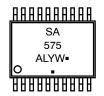
## **Applications**

- Portable Communications
- Cellular Radio
- Cordless Telephone
- Consumer Audio
- Portable Broadcast Mixers
- Wireless Microphones
- Modems
- Electric Organs
- Hearing Aids



TSSOP-20 DTB SUFFIX CASE 948E

#### **MARKING DIAGRAM**



A = Assembly Location

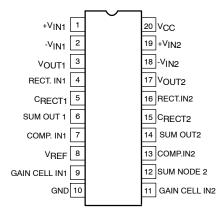
WL, L = Wafer Lot YY Y = Year

YY, Y = Year WW. W = Work Week

■ = Pb–Free Package

(Note: Microdot may be in either location)

## **PIN CONNECTIONS**



## **ORDERING INFORMATION**

See detailed ordering and shipping information in the package dimensions section on page 12 of this data sheet.

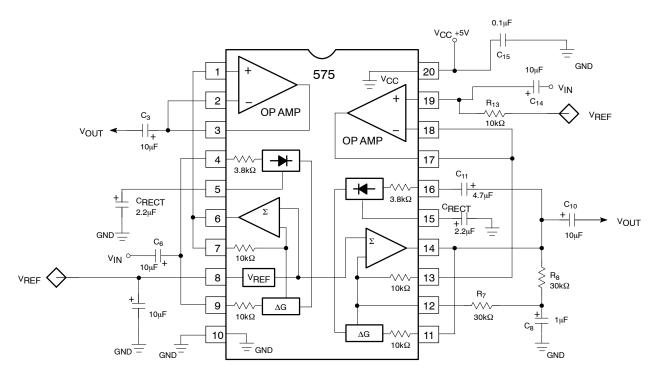


Figure 1. Block Diagram and Test Circuit

## PIN FUNCTION DESCRIPTION

Pin	Symbol	Description
1	+V <sub>IN1</sub>	Non-Inverted Input 1
2	-V <sub>IN1</sub>	Inverted Input 1
3	V <sub>OUT</sub>	Output
4	RECT. IN1	Rectifier 1 Input
5	C <sub>RECT1</sub>	External Capacitor Pinout for Rectifier 1
6	SUM OUT1	Summation Output 1
7	COMP. IN1	Compensator Pin
8	V <sub>REF</sub>	Voltage Reference
9	GAIN CELL IN1	Variable Gain Cell Input 1
10	GND	Ground
11	GAIN CELL IN2	Variable Gain Cell Input 2
12	SUM NODE 2	Summation Node 2
13	COMP. IN2	Compensator Pin
14	SUM OUT2	Summation Output 2
15	C <sub>RECT2</sub>	External Capacitor Pinout for Rectifier 2
16	RECT. IN2	Rectifier 2 Input
17	V <sub>OUT2</sub>	Output 2
18	-V <sub>IN2</sub>	Inverted Input 2
19	+V <sub>IN2</sub>	Non-Inverted Input 2
20	V <sub>CC</sub>	Positive Power Supply

#### **MAXIMUM RATINGS**

Rating	Symbol	Value	Unit
Single Supply Voltage	V <sub>CC</sub>	-0.3 to 8.0	V
Voltage Applied to Any Other Pin	V <sub>IN</sub>	-0.3 to (V <sub>CC</sub> + 0.3)	V
Operating Ambient Temperature Range	T <sub>A</sub>	-40 to +85	°C
Operating Junction Temperature	T <sub>J</sub>	150	°C
Storage Temperature Range	T <sub>STG</sub>	150	°C
Thermal Impedance	$\theta_{JA}$	124	°C/W
Maximum Power Dissipation	P <sub>D</sub>	1068	mW

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

 $\textbf{DC ELECTRICAL CHARACTERISTICS} \ \ \text{Typical values are at } T_A = 25^{\circ}\text{C}. \ \ \text{Minimum and Maximum values are for the full operating}$  $temperature\ range:\ -40\ to\ +85^{\circ}C\ for\ SA575,\ except\ SSOP\ package\ is\ tested\ at\ +25^{\circ}C\ only.\ V_{CC}=5.0\ V,\ unless\ otherwise\ stated.\ Both$ channels are tested in the Expandor mode (see Test Circuit).

Characteristic	Symbol	nbol Test Conditions		Тур	Max	Unit	
FOR COMPANDOR, INCLUDING	FOR COMPANDOR, INCLUDING SUMMING AMPLIFIER						
Supply Voltage (Note 1)	V <sub>CC</sub>	-	3.0	5.0	7.0	V	
Supply Current	Icc	No Signal	3.0	4.2	5.5	mA	
Reference Voltage (Note 2)	$V_{REF}$	V <sub>CC</sub> = 5.0 V	2.4	2.5	2.6	V	
Summing Amp Output Load	$R_L$	-	10	-	-	kΩ	
Total Harmonic Distortion	THD	1.0 kHz, 0 dB, BW = 3.5 kHz	-	0.12	1.5	%	
Output Voltage Noise	E <sub>NO</sub>	BW = 20 kHz, $R_S = 0 \Omega$	-	6.0	30	μV	
Unity Gain Level	0dB	1.0 kHz	-1.5	-	1.5	dB	
Output Voltage Offset	Vos	No Signal	-150	-	150	mV	
Output DC Shift		No Signal to 0 dB	-100	-	100	mV	
Tracking Error Relative to 0 dB		Gain Cell Input = 0 dB, 1.0 kHz Rectifier Input = 6.0 dB, 1.0 kHz	-1.0	_	1.0	dB	
		Gain Cell Input = 0 dB, 1.0 kHz Rectifier Input = -30 dB, 1.0 kHz	-1.0	_	1.0	dB	
Crosstalk		1.0 kHz, 0 dB, C <sub>REF</sub> = 220 μF	-	-80	-65	dB	
FOR OPERATIONAL AMPLIFIER	*		-		-	•	
Output Swing	Vo	$R_L = 10 \text{ k}\Omega$	V <sub>CC</sub> -0.4	V <sub>CC</sub>	_	V	
Output Load	$R_{L}$	1.0 kHz	600	-	-	Ω	
Input Common-Mode Range	CMR	-	0	-	V <sub>CC</sub>	V	
Common-Mode Rejection Ratio	CMRR	-	60	80	-	dB	
Input Bias Current	I <sub>B</sub>	V <sub>IN</sub> = 0.5 V to 4.5 V	-1.0	-	1.0	μА	
Input Offset Voltage	Vos	-	-	3.0	-	mV	
Open-Loop Gain	A <sub>VOL</sub>	$R_L = 10 \text{ k}\Omega$	-	80	-	dB	
Slew Rate	SR	Unity Gain	-	1.0	-	V/μs	
Bandwidth	GBW	Unity Gain	-	3.0	-	MHz	
Input Voltage Noise	E <sub>NI</sub>	BW = 20 kHz	-	2.5	-	μV	
Power Supply Rejection Ratio	PSRR	1.0 kHz, 250 mV	-	60	-	dB	

<sup>1.</sup> Operation down to  $V_{CC}$  = 2.0 V is possible, but performance is reduced. See curves in Figures 6 and 7. 2. Reference voltage,  $V_{REF}$  is typically at 1/2  $V_{CC}$ .

#### **Functional Description**

This section describes the basic subsystems and applications of the SA575 Compandor. More theory of operation on compandors can be found in AND8159 and AND8160. The typical applications of the SA575 low voltage compandor in an Expandor (1:2), Compressor (2:1) and Automatic Level Control (ALC) function are explained. These three circuit configurations are shown in Figures 2, 3, and 4 respectively.

The SA575 has two channels for a complete companding system. The left channel, A, can be configured as a 1:2 Expandor while the right channel, B, can be configured as either a 2:1 Compressor, a 1:2 Expandor or an ALC. Each channel consists of the basic companding building blocks of rectifier cell, variable gain cell, summing amplifier and  $V_{REF}$  cell. In addition, the SA575 has two additional high performance uncommitted op amps which can be utilized for application such as filtering, pre-emphasis/de-emphasis or buffering.

Figure 5 shows the complete schematic for the applications demo board. Channel A is configured as an expandor while channel B is configured so that it can be used either as a compressor or as an ALC circuit. The switch,  $S_1$ , toggles the circuit between compressor and ALC mode. Jumpers  $J_1$  and  $J_2$  can be used to either include the additional op amps for signal conditioning or exclude them from the signal path. Bread boarding space is provided for  $R_1$ ,  $R_2$ ,  $C_1$ ,  $C_2$ ,  $R_{10}$ ,  $R_{11}$ ,  $C_{10}$  and  $C_{11}$  so that the response can be tailored for each individual need. The components as specified are suitable for the complete audio spectrum from 20 Hz to 20 kHz.

The most common configuration is as a unity gain non-inverting buffer where  $R_1, C_1, C_2, R_{10}, C_{10}$  and  $C_{11}$  are eliminated and  $R_2$  and  $R_{11}$  are shorted. Capacitors  $C_3, C_5, C_8$ , and  $C_{12}$  are for DC blocking. In systems where the inputs and outputs are AC coupled, these capacitors and resistors can be eliminated. Capacitors  $C_4$  and  $C_9$  are for setting the attack and release time constant.

 $C_6$  is for decoupling and stabilizing the voltage reference circuit. The value of  $C_6$  should be such that it will offer a very low impedance to the lowest frequencies of interest. Too small a capacitor will allow supply ripple to modulate the audio path. The better filtered the power supply, the smaller this capacitor can be.  $R_{12}$  provides DC reference voltage to the amplifier of channel B.  $R_6$  and  $R_7$  provide a DC feedback path for the summing amp of channel B, while  $C_7$  is a short-circuit to ground for signals.  $C_{14}$  and  $C_{15}$  are for power supply decoupling.  $C_{14}$  can also be eliminated if the power supply is well regulated with very low noise and ripple.

## **Demonstrated Performance**

The applications demo board was built and tested for a frequency range of 20 Hz to 20 kHz with the component values as shown in Figure 5 and  $V_{CC} = 5.0$  V. In the expandor mode, the typical input dynamic range was from -34 dB to +12 dB where 0 dB is equal to 100 mV<sub>RMS</sub>. The typical unity gain level measured at 0 dB @ 1.0 kHz input was  $\pm 0.5$  dB and the typical tracking error was  $\pm 0.1$  dB for input range of -30 to +10 dB.

In the compressor mode, the typical input dynamic range was from -42 dB to  $\pm$  18 dB with a tracking error +0.1 dB and the typical unity gain level was  $\pm$  0.5 dB.

In the ALC mode, the typical input dynamic range was from -42 dB to +8.0 dB with typical output deviation of  $\pm 0.2$  dB about the nominal output of 0 dB. For input greater than +9.0 dB in ALC configuration, the summing amplifier sometimes exhibits high frequency oscillations. There are several solutions to this problem. The first is to lower the values of  $R_6$  and  $R_7$  to 20 k $\Omega$  each. The second is to add a current limiting resistor in series with C12 at Pin 13. The third is to add a compensating capacitor of about 22 to 30 pF between the input and output of summing amplifier (Pins 12 and 14). With any one of the above recommendations, the typical ALC mode input range increased to +18 dB yielding a dynamic range of over 60 dB.

## **Expandor**

The typical expandor configuration is shown in Figure 2. The variable gain cell and the rectifier cell are in the signal input path. The V<sub>REF</sub> is always 1/2 V<sub>CC</sub> to provide the maximum headroom without clipping. The 0 dB ref is 100 mV<sub>RMS</sub>. The input is AC coupled through C<sub>5</sub>, and the output is AC coupled through C<sub>3</sub>. If in a system the inputs and outputs are AC coupled, then C<sub>3</sub> and C<sub>5</sub> can be eliminated, thus requiring only one external component, C<sub>4</sub>. The variable gain cell and rectifier cell are DC coupled so any offset voltage between Pins 4 and 9 will cause small offset error current in the rectifier cell. This will affect the

accuracy of the gain cell. This can be improved by using an extra capacitor from the input to Pin 4 and eliminating the DC connection between Pins 4 and 9.

The expandor gain expression and the attack and release time constant is given by Equation 1 and Equation 2, respectively.

$$\mbox{Expandor gain} = \left( \frac{4 \mbox{V}_{\mbox{IN}}(\mbox{avg})}{3.8 \mbox{ k} \Omega \times 100 \mbox{ } \mu\mbox{A}} \right)^2 \mbox{ (eq. 1)}$$

where  $V_{IN}(avg) = 0.95V_{IN(RMS)}$ 

$$\tau_R = \tau_A = 10 \text{ k}\Omega \text{ x } C_{RECT} = 10 \text{ k}\Omega \text{ x } C_4 \qquad \text{ (eq. 2)}$$

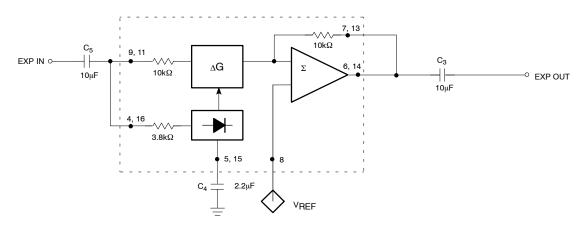


Figure 2. Typical Expandor Configuration

## Compressor

The typical compressor configuration is shown in Figure 3. In this mode, the rectifier cell and variable gain cell are in the feedback path.  $R_6$  and  $R_7$  provide the DC feedback to the summing amplifier. The input is AC coupled through  $C_{12}$  and output is AC coupled through  $C_8$ . In a system with inputs and outputs AC coupled,  $C_8$  and  $C_{12}$  could be eliminated and only  $R_6$ ,  $R_7$ ,  $C_7$ , and  $C_{13}$  would be required. If the external components  $R_6$ ,  $R_7$  and  $C_7$  are eliminated, then the output of the summing amplifier will motor-boat in absence of signals or at extremely low signals. This is because there is no DC feedback path from

the output to input. In the presence of an AC signal this phenomenon is not observed and the circuit will appear to function properly.

The compressor gain expression and the attack and release time constant is given by Equation 3 and Equation 4, respectively.

$$\begin{split} &Compressor\ gain = \left[ \frac{3.8\ k\Omega\ x\ 100\ \mu A}{4V_{IN}(avg)} \right]^{1/2} \\ &where\ \ V_{IN}(avg) = 0.95V_{IN(RMS)} \\ &\tau_R = \tau_A = 10\ k\Omega\ x\ C_{RECT} = 10\ k\Omega\ x\ C_4 \end{split} \tag{eq. 4}$$

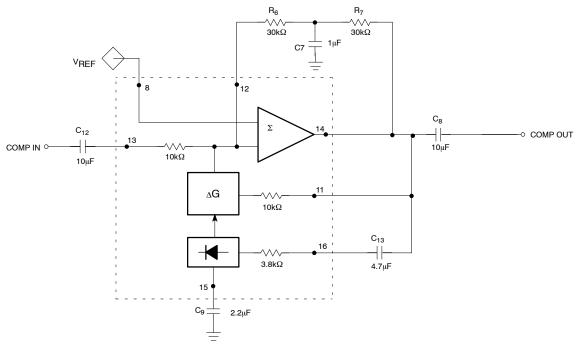


Figure 3. Typical Compressor Configuration

#### **Automatic Level Control**

The typical Automatic Level Control circuit configuration is shown in Figure 4. It can be seen that it is quite similar to the compressor schematic except that the input to the rectifier cell is from the input path and not from the feedback path. The input is AC coupled through  $C_{12}$  and  $C_{13}$  and the output is AC coupled through  $C_{8}$ . Once again, as in the previous cases, if the system input and output signals are already AC coupled, then  $C_{12}$ ,  $C_{13}$  and  $C_{8}$  could be eliminated. Concerning the compressor, removing  $R_{6}$ ,  $R_{7}$  and  $C_{7}$  will cause motor-boating in

absence of signals.  $C_{COMP}$  is necessary to stabilize the summing amplifier at higher input levels. This circuit provides an input dynamic range greater than 60 dB with the output within  $\pm 0.5$  dB typical. The necessary design expressions are given by Equation 5 and Equation 6, respectively.

ALC gain = 
$$\frac{3.8 \text{ k}\Omega \text{ x } 100 \text{ }\mu\text{A}}{4\text{V}_{\text{IN}}(\text{avg})}$$
 (eq. 5)

$$\tau_R = \tau_A = 10 \text{ k}\Omega \text{ x C}_{RECT} = 10 \text{ k}\Omega \text{ x C}_9$$
 (eq. 6)

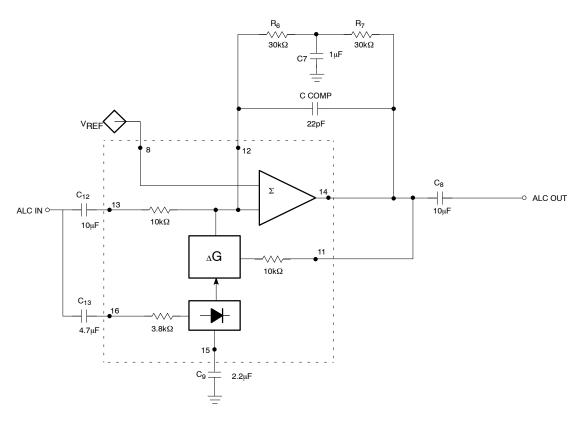


Figure 4. Typical ALC Configuration

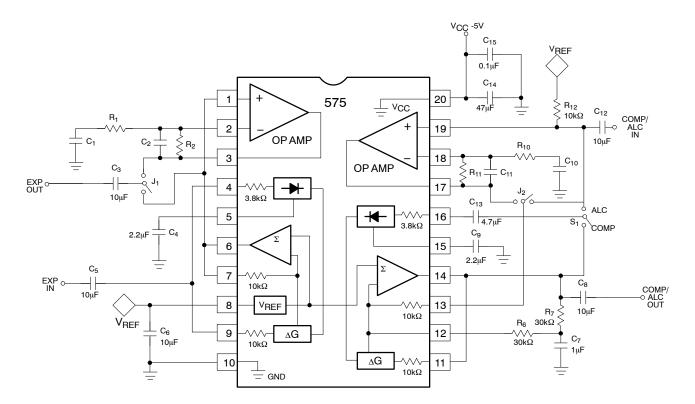


Figure 5. SA575 Low Voltage Expandor/Compressor/ALC Demo Board

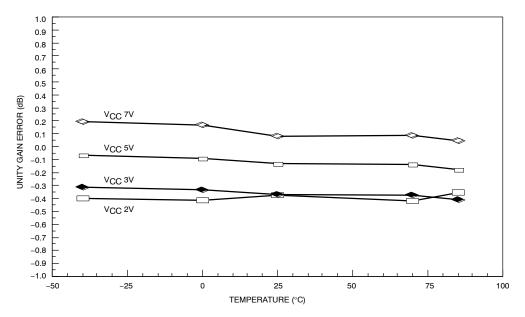


Figure 6. Unity Gain Error vs. Temperature and  $\ensuremath{V_{\text{CC}}}$ 

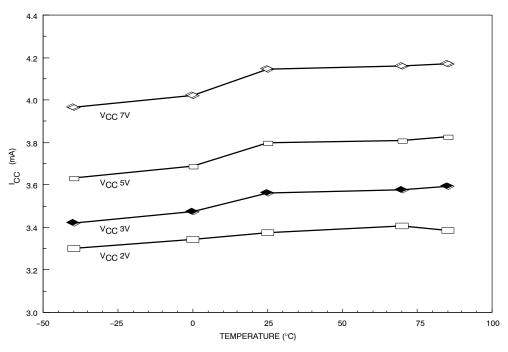


Figure 7.  $I_{\mbox{\footnotesize CC}}$  vs. Temperature and  $V_{\mbox{\footnotesize CC}}$ 

## TYPICAL PERFORMANCE CHARACTERISTICS

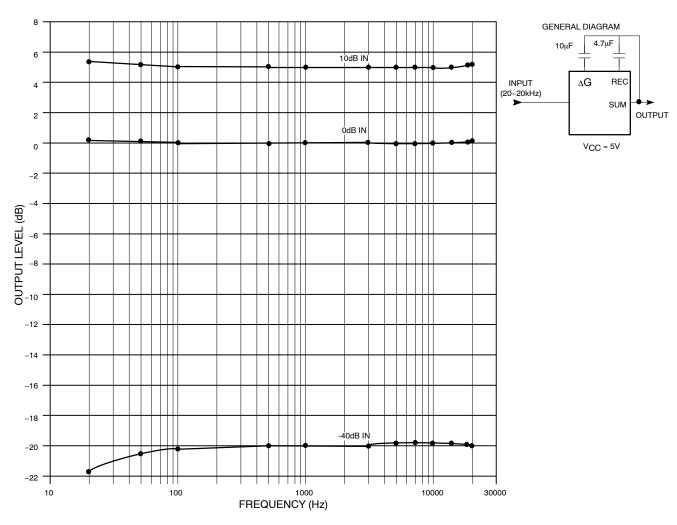


Figure 8. Compressor Output Frequency Response

## TYPICAL PERFORMANCE CHARACTERISTICS

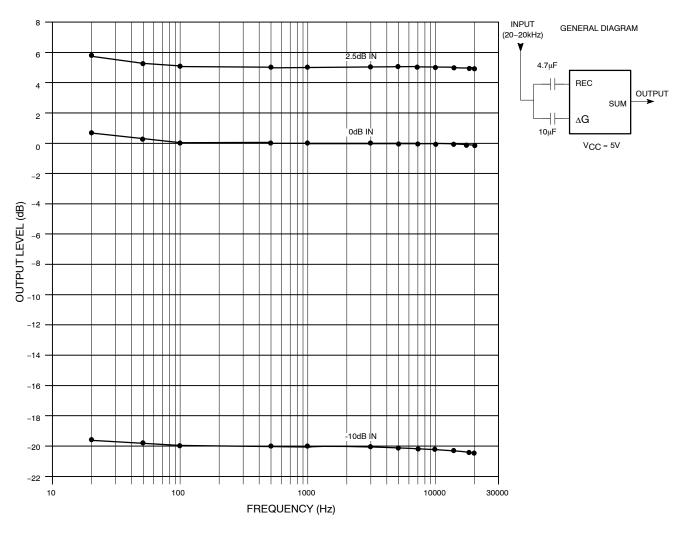


Figure 9. Expandor Output Frequency Response

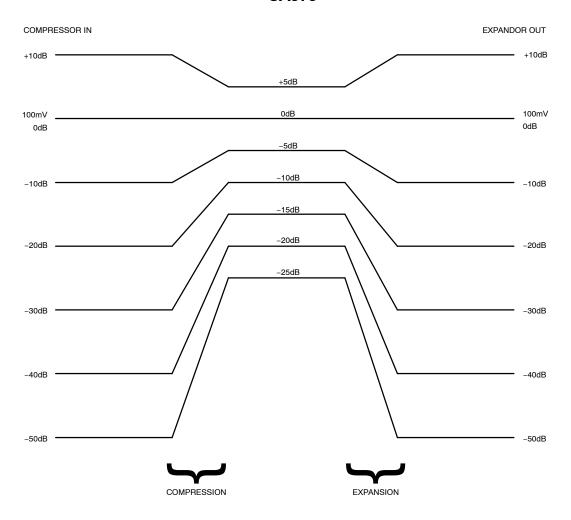


Figure 10. The Companding Function

## **ORDERING INFORMATION**

Device	Package	Temperature Range	Shipping <sup>†</sup>
SA575DTBR2G	TSSOP-20 (Pb-Free)	−40 to +85°C	2500 / Tape & Reel

<sup>†</sup>For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specification Brochure, BRD8011/D.

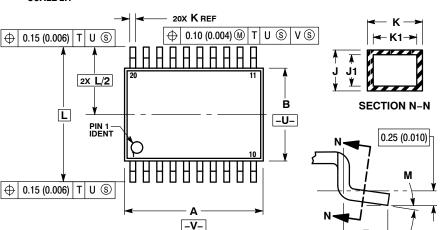
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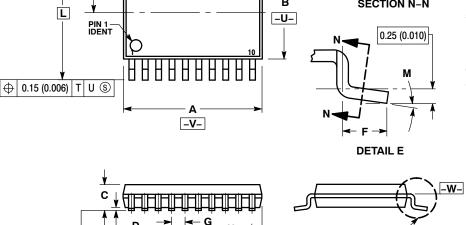
-T- SEATING



## TSSOP-20 WB CASE 948E ISSUE D

**DATE 17 FEB 2016** 





#### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: MILLIMETER.
- 3. DIMENSION A DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS.
- FLASH, PROTRUSIONS OR GATE BURRS.
  MOLD FLASH OR GATE BURRS SHALL NOT
  EXCEED 0.15 (0.006) PER SIDE.

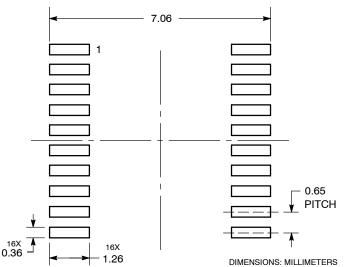
  4. DIMENSION B DOES NOT INCLUDE
  INTERLEAD FLASH OR PROTRUSION.
  INTERLEAD FLASH OR PROTRUSION
  SHALL NOT EXCEED 0.25 (0.010) PER SIDE.
  DIMENSION K DOES NOT INCLUDE
  DAMBAR PROTRUSION. ALLOWABLE
  DAMBAR PROTRUSION SHALL BE 0.08
  (0.003) TOTAL IN EXCESS OF THE K
- (0.003) TOTAL IN EXCESS OF THE K DIMENSION AT MAXIMUM MATERIAL CONDITION.
- TERMINAL NUMBERS ARE SHOWN FOR REFERENCE ONLY.

  7. DIMENSION A AND B ARE TO BE
- DETERMINED AT DATUM PLANE -W-

	MILLIN	IETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	6.40	6.60	0.252	0.260
В	4.30	4.50	0.169	0.177
С		1.20		0.047
D	0.05	0.15	0.002	0.006
F	0.50	0.75	0.020	0.030
G	0.65 BSC		0.026 BSC	
Н	0.27	0.37	0.011	0.015
J	0.09	0.20	0.004	0.008
J1	0.09	0.16	0.004	0.006
K	0.19	0.30	0.007	0.012
K1	0.19	0.25	0.007	0.010
Ĺ	6.40 BSC		0.252	BSC
M	0°	8°	0°	8°

#### **GENERIC SOLDERING FOOTPRINT MARKING DIAGRAM\***

**DETAIL E** 



	<u> </u>			
	XXXX			
	XXXX			
	ALYW <b>•</b>			
	0 •			
<u> </u>				

= Assembly Location

= Wafer Lot = Year

= Work Week

= Pb-Free Package (Note: Microdot may be in either location)

\*This information is generic. Please refer to device data sheet for actual part marking.

Pb-Free indicator, "G" or microdot " ■", may or may not be present.

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TECHNICAL SUPPORT North American Technical Support: Voice Mail: 1 800-282-9855 Toll Free USA/Canada Phone: 011 421 33 790 2910

Europe, Middle East and Africa Technical Support: Phone: 00421 33 790 2910

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