

# CDM10V

### Flexible 0-10V Dimming Solution

### Features

- Simplest 0-10 V design on the market. CDM10V comes with default settings:
  - 5% minimum duty cycle
  - 1kHz PWM frequency
  - 200µA Dimmer/Resistor Bias current
  - Dim-To-Off disabled
- The simple one time programmable option allows setting in a wide range:
  - Minimum duty cycle: 1%, 2%, 5%, 10%
  - PWM output frequency: 200Hz, 500Hz, 1kHz, 2kHz
  - Dimmer/Resistor Bias Current: 50μA, 100μA, 200μA, 500μA
     Dim-to-Off: disabled/enabled
- Wide input V<sub>cc</sub> range from 11 to 25 V
- Transparent PWM mode (PWM Bypass Mode in DIM-TO-OFF enabled mode)
- Replaces many external components with a single chip reducing BOM and PCB space
- Minimum variation from device to device

### Applications

- LED Drivers needing 0-10 V Dimming Circuits
- Industrial and Commercial Dimmable Applications:

Luminaires, Troffers, Downlights, Sconces, Undercabinet, Office Lighting, Signage applications, Dali applications

Product Type	Package
CDM10V	SOT23-6

### Description

CDM10V is a fully integrated 0-10 V dimming interface IC and comes in a SOT-23-6 package to cover space requirements on small PCBs.

The device is targeted for various dimming applications in lighting. The IC can be used to transmit analog voltage based signals from a 0-10 V dimmer or potentiometer to the dimming or PWM input of a lighting controller IC in the form of a 5 mA current based PWM signal to drive an external opto-coupler. It replaces many components in a traditional solution and reduces BOM and PCB space significantly.

The CDM10V IC outputs a 0 - 100% PWM current signal at programmable frequency with an amplitude value of 5 mA.

The duty cycle of the PWM signal can be limited to a dedicated minimum value. Dim-to-off feature is supported as well and can be enabled on demand.

Embedded digital signal processing maintains minimum variations from device to device.



### Table of contents

### Table of contents

	Features	. 1
	Applications	.1
	Description	.1
	Table of contents	. 2
1	Block Diagram	.3
2	Pin Configuration	.3
3	Functional Description	.4
4	Electrical Characteristics and Parameters	13
5	Chip Configuration	15
6	Package Dimensions	17
7	References	19
	Revision History	19
	Trademarks	20

### CDM10V Flexible 0-10V Dimming Solution



### Block Diagram

# 1 Block Diagram

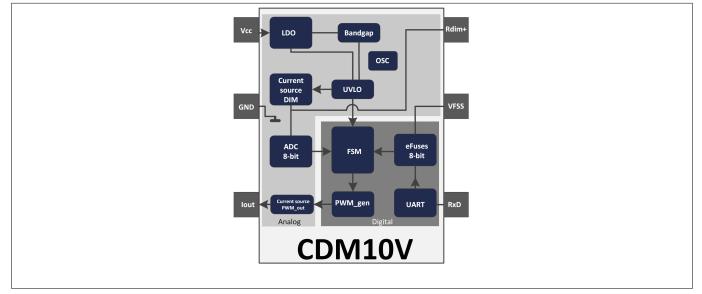


Figure 1 Block Diagram of the CDM10V

# 2 Pin Configuration

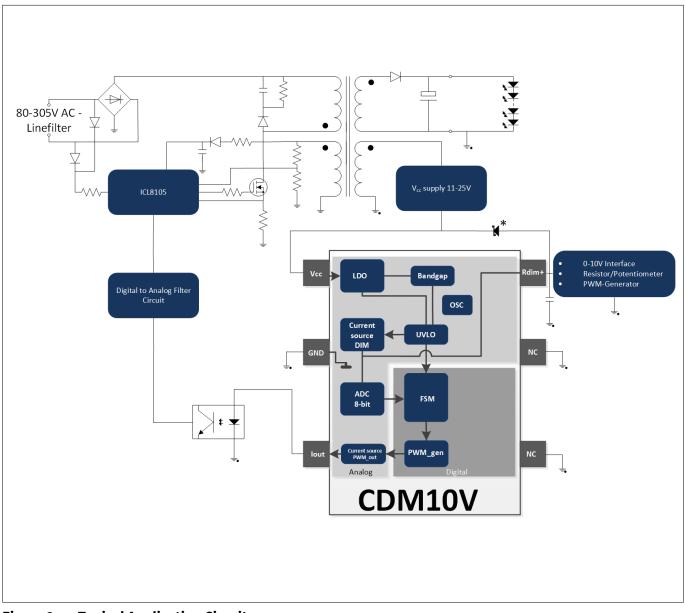
Table 1	Pin configutation
---------	-------------------

Pin	Name	Function
1	V <sub>CC</sub>	Input voltage 11V - 25V
2	GND	GND
3	I <sub>out</sub>	PWM output current 5mA
4	RxD	RxD for eFuse programming, connect to GND for normal operation
5	V <sub>FSS</sub>	Fusing voltage (4,1V) eFuse programming, connect to GND for normal operation (internal pull-down)
6	R <sub>dim+</sub>	Dimmer current output /Voltage sense



### 3 Functional Description

#### **Typical Application Circuit**

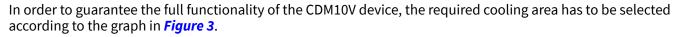


#### Figure 2 Typical Application Circuit

- Note: The Diode marked with \* is for the protection of the R<sub>dim+</sub>-Pin when active dimming is used. This is because the voltage on this Pin is not allowed to be higher than V<sub>CC</sub>+0.5V. It is advised to use a low leakage, low reverse current Schottky-Diode in order to not influence the dimming performance (e.g. MMSD301T1G).
- Note: The capacitor connected to the R<sub>dim+</sub>-Pin reduces the amount of coupled noise to the dimming signal. The size of this capacitance should be in the range of 2.2 - 10 nF (typ. 4.7 nF), where a small capacitor allows steeper edges of the dimming signal, a larger capacitor enhances the noise reduction.



### **Recommended cooling area**



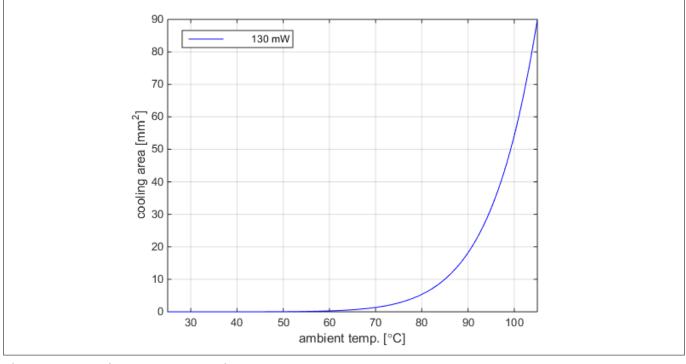


Figure 3 Cooling area over ambient temperature CDM10V



#### **Dimming Characteristic**

Table 2       PWM Output current referring to R <sub>dim+</sub> -Pin Voltage						
R <sub>dim+</sub> I <sub>out</sub>						
	<1 V	PWM @ min duty cycle or Dim-to-OFF				
	1 - 9 V	min duty cycle (@ 1V)100% (@ 9V)				
	>9V (max. applicable Voltage: V <sub>cc</sub> )	Always active				

Calculation of the lower dimming voltage boundary for entering min duty cycle:

1 V + min Duty Cycle × 8 V

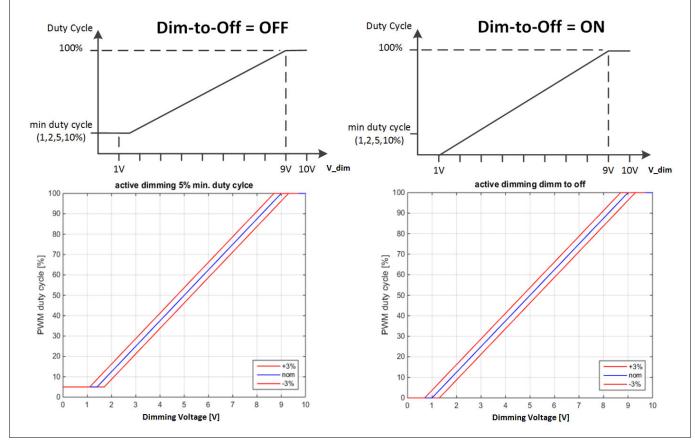


Figure 4 **Dimming Characteristic** 





#### **Transparent Mode**

CDM10V device can be configured for usage in transparent mode. In this mode the PWM signal on R<sub>dim+</sub> input will be provided directly to I<sub>out</sub>.

Pre-condition to enable the transparent mode is to fuse the DIM2OFF bit to HIGH and PWM frequency to 2 kHz, PWM minimum duty cycle is not used in this mode and can stay in default configuration.

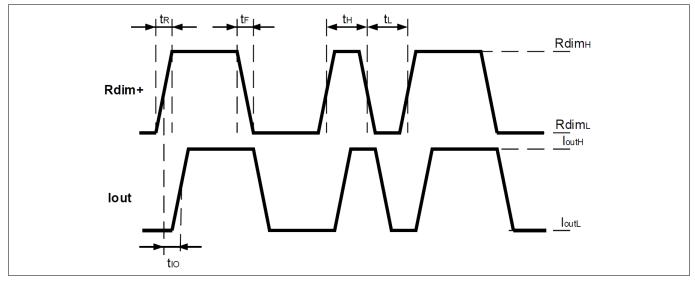


Figure 5 Transparent mode timing diagram

Table 3	Conditions for the transparent mode
---------	-------------------------------------

Condition	Name	Min	Nom	Мах
R <sub>dimH</sub>	R <sub>dim+</sub> High Value	9.3 V		V <sub>CC</sub> +0,5V
R <sub>dimL</sub>	R <sub>dim+</sub> Low Value	-0.5 V		0.5 V
I <sub>outH</sub>	I <sub>out</sub> High Value		R <sub>lout</sub> * 5mA <sup>1</sup>	
I <sub>outL</sub>	I <sub>out</sub> Low Value		0.0 V	
t <sub>IO</sub>	Propagation delay		8.8 µs	
t <sub>H</sub>	Min puls width High	2.6 µs		
tL	Min puls width Low	2.6 µs		
t <sub>R</sub>	Rising edge time			1.8 µs
t <sub>F</sub>	Falling edge time			1.8 μs

Note:  ${}^{1}R_{\text{lout}}$  is the resistance connected between the  $I_{\text{out}}$  and the GND-PIN

*Image* shows the maximum I<sub>out</sub> resolution versus the R<sub>dim+</sub> frequency. The dependency can be calculated using following formula:

 $f_{Rdim} = \frac{I_{out} \ resolution}{100 \ \times \ 2.6 \ \mu s}$ 

For 1% resolution we get:

 $f_{Rdim} = \frac{1}{100 \times 2.6 \ \mu s} \approx 3.85 \ kHz$ 

### CDM10V Flexible 0-10V Dimming Solution



### **Functional Description**

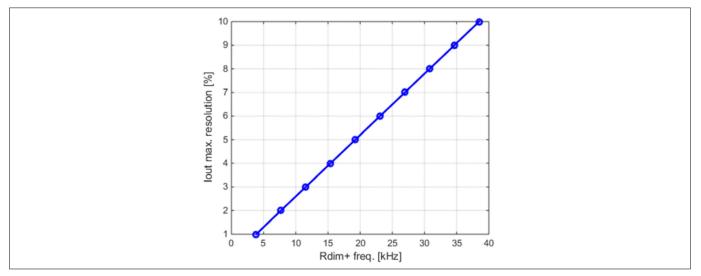


Figure 6 I<sub>out</sub> resolution versus the R<sub>dim+</sub> frequency



#### **Optocupler Selection Guide**

CDM10V converts an analog dimming signal into a PWM waveform. In the majority of applications the dimming signal needs to be isolated from the rest of the application and an optocoupler is used to implement either functional or reinforced isolation. Optocouplers are an excellent choice since they are very cost effective but nevertheless able to comply with virtually all safety standards.

The most common and cost effective optocouplers are four-pin devices consisting of a LED and a photosensitive BJT. With four pin devices only collector and emitter of the BJT are connected to pins. This limits device performance, especially switching times, as will be discussed later. Six-pin devices having the base of the BJT as well connected to a pin are seen less often. With these six-pin devices bandwidth of the transmission can be improved if necessary. Finally there are high-speed digital couplers available that are designed for very high data rates and offer a buffered output with a nearly perfect PWM signal. While offering superior performance high speed couplers are considerably more expensive than simple LED-BJT couplers.

#### Generating an Analog Signal from PWM

Although the PWM signal itself can be used, either by implementing PWM dimming or using a dedicated SMPS controller that is able to extract the dimming information directly from the PWM waveform, in many applications a DC voltage that is proportional to the desired dimming level is needed. Fortunately it is easy to create an analog signal from PWM: a low pass filter with the right corner frequency will do the job.

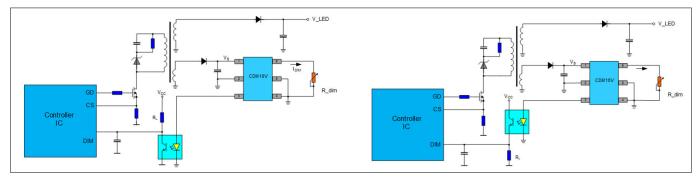
As a rule of thumb a corner frequency of  $f_{PWM}/100$  for a first order filter and  $f_{PWM}/10$  for second order filter should be used. With this selection ripple on the generated DC signal is around 150 mV<sub>pp</sub> at medium dimming levels and goes down to a few 10 mV<sub>pp</sub> at very low and high dimming levels. The first order filter will have a slower time response due to the low corner frequency. Consequently, if for some reason a  $f_{PWM}$  lower than 1 kHz has to be used, as second order filter will give the better response. With a third order filter it is possible to achieve either negligible ripple on the DC voltage or superior response time.

Since the generated DC voltage not only depends on the duty-cycle of the PWM signal but is directly proportional to its amplitude as well it is mandatory to stabilize the amplitude e.g. with a Zener-Diode.

*Image* shows a simplified schematic with second order filter. According to the design guideline given above, good starting values for  $C_1$  and  $C_2$  would be:

$$C_1 = C_2 = 150 \ nF \times \frac{1 \ kHz}{f_{PWm}}$$

*Note:* Using the ICL8105 the capacitor connected to the UART/Dim-Pin is not allowed to exceed 1nF in order to provide proper UART communication if needed.



#### Inverted / Non-Inverted Output

#### Figure 7 Simplified schematic of CDM10V with inverted (left) and non-inverted (right) output signal. Both are equivalent in terms of performance

Optocouplers are most often used in the configuration shown on the left of *Image* i.e. the output signal is derived from the collector of the BJT and thus inverted compared to the input signal. An inverted signal is not favorable at all since it will result in an inverted dimming characteristic with the majority of controllers. An additional inverter stage could be used of course, resulting in the proper dimming curve. But there is a simpler



solution as well since the four pin optocoupler can be viewed as current controlled current source if V<sub>CE</sub> of the BJT is sufficiently high. Consequently the load can be connected either to collector or emitter without significant change in parameters or performance. Therefore the configuration on the right of *Image* is favorable for most SMPS controllers.

#### **Optocoupler selection**

There are two parameters of an optocoupler that are most important for use with CDM10V: the current transfer ratio CTR and the switching times  $T_r$  and  $T_f$ .

**Image** is a typical plot of  $T_r$  and  $T_f$  vs,  $R_L$  taken from the data sheet of a widely used 4-pin optocoupler. Both parameters depend on the load resistance  $R_L$ . But while  $T_r$  doesn't vary too much and shows a moderate maximum for  $R_L$  of few hundred ohms,  $T_f$  is constantly increasing with  $R_L$ , reaching about 100 µs for  $R_L$  around 10 k $\Omega$ . These times are much longer than the minimum pulse length generated by CDM10V shown in table **Table 4**. Consequently relative low values for  $R_L$  around 100  $\Omega$  seem to be necessary in order to achieve reasonable switching times. But it's important to mention, that switching times shown in **Image** are determined with saturated BJT (this means the load resistance limits the IC to a lower value than would be determined by LED current) and with non-saturated BJT switching times can be small, even with higher load resistance.

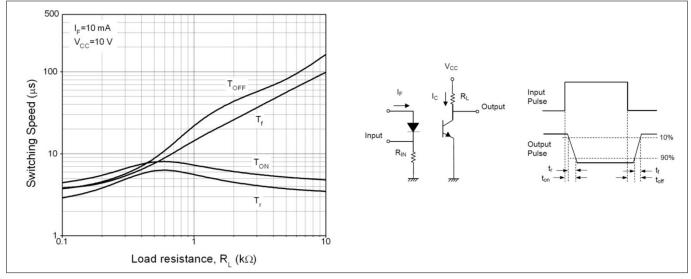


Figure 8 Typical optocoupler switching times vs. load resistance together with test circuit.

Before discussing influence of load resistance on switching performance further, the second important parameter of the coupler, CTR, needs investigation.

		-		-	
Frequency	Dim-to-off	1%	2%	5%	10%
200 Hz	1.2 μs	50 μs	100 µs	250 μs	500 μs
500 Hz	7.84 μs	20 µs	40 µs	100 µs	200 µs
1 kHz	3.92 μs	10 µs	20 µs	50 μs	100 µs
2 kHz	1.96 µs	5 µs	10 µs	25 μs	50 μs

#### Table 4 Shortest pulse length for different frequencies and minimum dimming levels of CDM10V

As the name implies, CTR is simply the ratio between the forward current I<sub>F</sub> of the LED and the resulting collector current IC of the phototransistor and usually expressed in percent. A CTR of 50% for example means that the collector current is 50% or half of the LED current. CTR is of course not constant but depends on the LED current as well as on temperature. For many optocouplers CTR is specified for a nominal current of 5mA but can have considerably higher CTR at higher currents while being much lower at currents below 5 mA. Since CDM10V drives a constant current of 5 mA it fits very well to the most common couplers on the market. For a given coupler the CTR shows wide variation from device to device, varying for example from 50% to 600% for a



widely used coupler. Therefore selections are available with a CTR variation of 1:2 ranging e.g. from 100% to 200%.

As said before, the 4-pin coupler with phototransistor can be seen as a current-controlled current source and CDM10V is driving a current of 5 mA, resulting in a collector current (= emitter current) ranging from 2.5 mA to 30 mA for a non-selected coupler. With a 100  $\Omega$  load resistor the output signal thus would vary from 250 mV to 3V. This leads to the conclusion that small load resistance is desirable for good switching behavior but leads to small output signal and this signal varies too much with CTR instead of having a constant amplitude as requested initially. A solution for achieving constant amplitude could be to make the load resistance big enough that the transistor would go into saturation. The voltage drop across a BJT in saturation is small and doesn't vary much with temperature but switching speed is very poor in this condition.

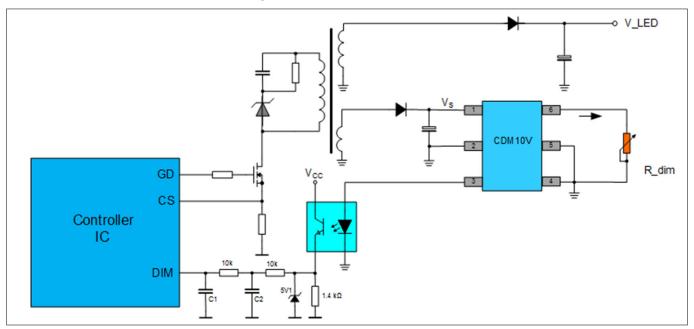


Figure 9 Simplified schematic showing second order filter and best configuration of coupler

All of the above put together results in a set of simple rules of optocoupler selection:

1. Use the lowest PWM frequency that gives reasonable dimming response.

Example: With f<sub>PWM</sub> = 1kHz a second order filter with a corner frequency of 100 Hz should be used. The response time of this filter to a step from 10% to 90% dimming level is about 10 ms and after 20 ms the final level is reached.

- **2.** Use an optocoupler with a selected CTR range like e.g. 100% to 200%.
- **3.** Use a load resistance that allows the desired output voltage even with lowest CTR over all possible operating conditions.

Example:

 $CTR_{min} = 80 \%$ ,  $V_{Out} = 5 V$ ,  $I_{LED, max} = 4.5 mA$ 

$$R_L \qquad \frac{V_{out}}{CTR_{min} \times I_{LED, min}} = \frac{5 V}{0.8 \times 4.5 mA} = 1.388 k\Omega$$

To prevent saturated switching, use a supply voltage V<sub>CC</sub> that is at least 2V higher than the desired output voltage V<sub>Out</sub>. V<sub>CC</sub> shouldn't be too high on the other hand to limit power losses.

Example:

 $V_{CC} = 15 V, CTR_{max} = 200 \%, I_{LED,max} = 5.45 mA, Dimm-Level 100 \%$  $P_{Loss,max} = 2.2 \times 5.45 mA \times 15 V = 179.85 mW$ 

Obviously with a  $V_{CC}$  of 7.5 V these losses would be halved to about 90 mW. It's important to keep in mind, that this is the maximum loss that only occurs at maximum light output. At minimum dimming level or dimto-off the loss added by the optocoupler circuit will be negligible.



5. Use a Zener diode to limit and stabilize the output voltage to the desired value. In the above example a 5.1 V Zener with 2% accuracy should be used.

A circuit that complies with all the above is shown in *Image*. An optocoupler device that complies with the above mentioned rules and has actually been tested in the application is VO617A-2 by Vishay Semiconductor. There are of course many devices available that have very similar, if not identical, technical data regarding switching times vs. load resistance and CTR selection. As an example devices as FOD817A, HCPL-817-xxAE or LTV-817A, EL817A or TLP183 GRL, to name only a few, can be used in this application. Nevertheless the desired performance has to be verified in the application in each single case.



**Electrical Characteristics and Parameters** 

### 4 Electrical Characteristics and Parameters

Pin	Name		Values	Unit	Note or Test
		Min.	Max.		Condition
1	V <sub>cc</sub>	11	25	V	
2	GND	0	0	V	Point of reference
3	l <sub>out</sub>	-0.5	3.63	V	Depending on the optocupler voltage @ 5mA
4	RxD	-0.25	0.1	V	Connect to GND during operation
5	V <sub>FSS</sub>	-0.25	0.1	V	During operation Connect to GND
6	R <sub>dim+</sub>	-0.5	V <sub>CC</sub> + 0.5	V	An applied voltage above max value leads to the destruction of the device. Also valid if V <sub>CC</sub> is 0 V.

Table 5 Absolute Maximum Ratings

Absolute maximum ratings (*Table 5*) are defined as ratings which when being exceeded may lead to destruction of the integrated circuit. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Maximum ratings are absolute ratings; exceeding only one of these values may cause irreversible damage to the integrated circuit. These values are not tested during production test.

Table 6Electrical Characteristics	<b>Electrical Cha</b>	racteristics
-----------------------------------	-----------------------	--------------

Parameter	Programmable	Symbol	Values			Unit	
			Min.	Тур.	Max.	1	Condition
Input Voltage		V <sub>in</sub>	11		25	V	Operating Voltage
Junction Temperature Range		Τ <sub>J</sub>	-40		135	°C	
Ambient Temperature Range		T <sub>A</sub>	-40		105	°C	
Power Dissipation		P <sub>tot</sub>	6.05 @ 1% duty cycle; 6.6 @ 2% duty cycle; 8.25 @ 5% duty cycle; 11 @ 10% duty cycle	83.2 @ 70% duty cycle 54 @ 50% duty	160 @ 100% PWM & 25 V <sub>in</sub>	mW	Dimmer current included
Current Consumption		I <sub>CC</sub>			1	mA	Current Consumption of the IC for self supply



#### **Electrical Characteristics and Parameters**

#### Programmable Unit Parameter Symbol Values **Note or Test** Condition Min. Тур. Max. **Output Current for** 50/100/<u>200</u>/500 Current flow -10% +10% μA yes Idim Dimmer out of R<sub>dim+</sub>-Pin Output Current for -10% 5 +10% I<sub>out</sub> mΑ Optocoupler PWM frequency -6% 200/500/ +6% Ηz yes f<sub>PWM</sub> <u>1000</u>/2000 Min. duty cycle % Percentage of $PW_{PWM}$ -0.2 1/2/5/10 +0.2 yes the pulse width With active **Dimming accuracy** -3 +3 % dimming incl. all variations Fusing Voltage 4.0 4.1 4.2 V For eFuse $V_{FSS}$ programming, connect to GND for normal operation Wake-up Time 40 Time from V<sub>CC</sub> tw μs = 11 V to first output current V ESD capability HBM 1500 according to $V_{HAB}$ ANSI/ESDA/ JEDEC JS-001 according to ESD capability CDM 500 V<sub>CDM</sub> JESD22 C101

#### Table 6 Electrical Characteristics (continued)



**Chip Configuration** 

## 5 Chip Configuration

#### **Typical eFuse programming Circuit**

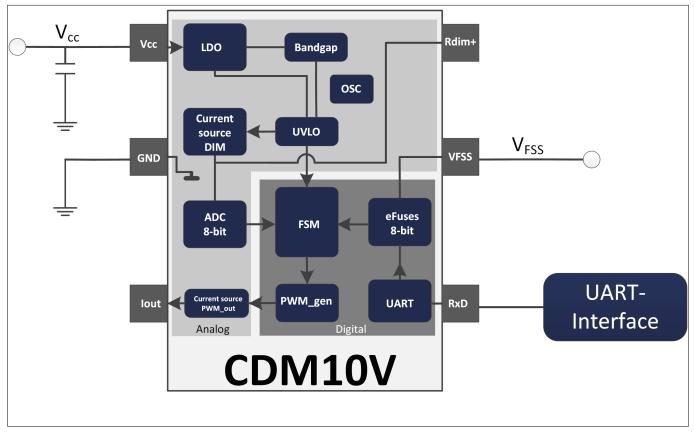


Figure 10 Typical eFuse programming Circuit

#### **Serial Port**

The serial port enables a <u>one time reconfiguration</u> of parameters for device function.

Characteristics of the communication: Baudrate: 9600Bd; one stop bit; no parity bit

Timing diagram:

	Data frame		
Startbit	8 Data bits	Stopbit	

Figure 11 Timing diagram for the serial communication



### **Chip Configuration**

Data frame format:

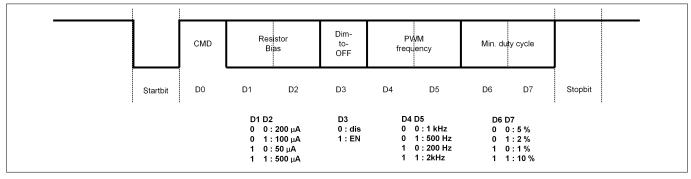




Table 7	Bit setting for the one time reconfiguration
---------	--

Bit group	Value	Meaning	Comment
CMD	1	Always high	reserved
Dimmer/Resistor Bias	00	200 µA	Default
	01	100 µA	
	10	50 µA	
_	11	500 μΑ	
Dim-to-Off	0	NOT ENABLED	Default
_	1	Enable	
PWM Frequency	00	1 kHz	Default
	01	500 Hz	
	10	200 Hz	
	11	2 kHz	
Minimum duty cycle	00	5 %	Default
_	01	2 %	
	10	1%	
_	11	10 %	



#### Package Dimensions

# 6 Package Dimensions

All dimensions in mm.

#### **Package Drawings**

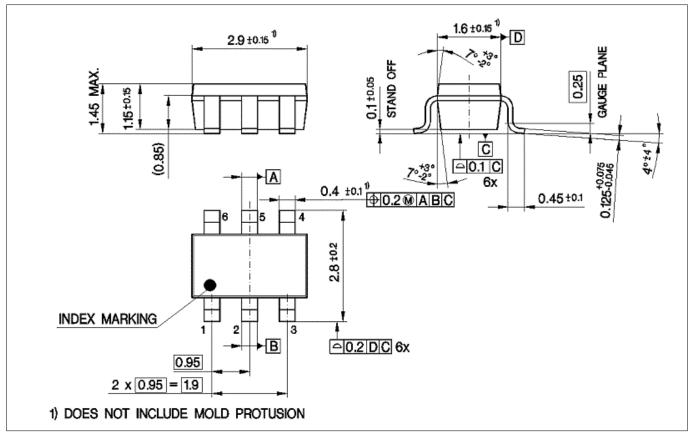


Figure 13 Package Drawings

### Package Dimensions

#### Footprint

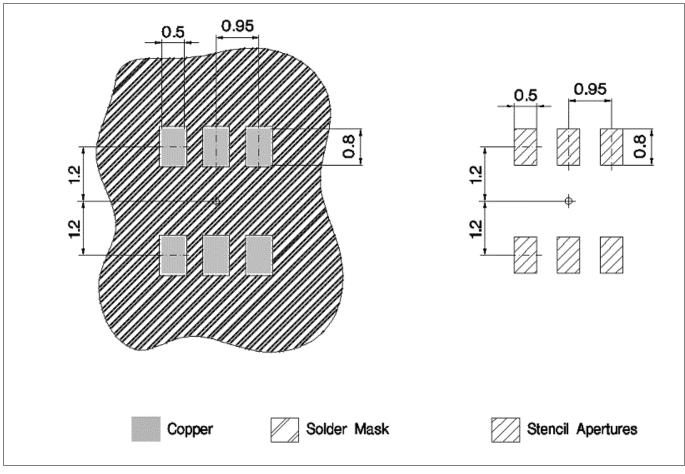


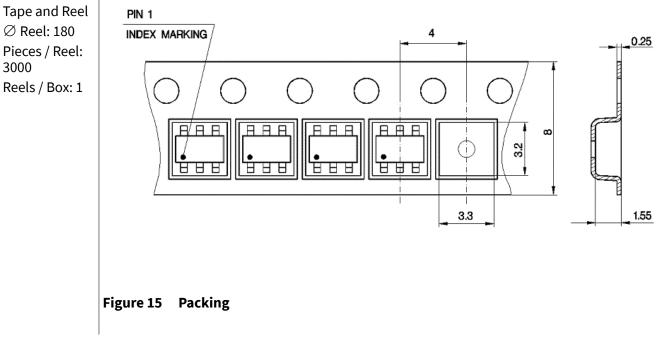
Figure 14 Footprint



#### References

#### **Packing Description**

#### **Packing Type**



### 7 References

Additional support material can be found under the following link. **Related information** 

http://www.infineon.com/CDM10V

### **Revision History**

Major changes since previous revision

Revision History			
Reference	Description		
v1.0	Initial Version		
v1.1	Typos, added <i>Table 5</i>		
v1.2	Туроѕ р 12, р 13		
v1.3	Additional information about the max rating of Rdim-Pin ( <i>Image</i> , <i>Table 5</i> )		



#### **Trademarks of Infineon Technologies AG**

μΗVIC<sup>®</sup>, μΙΡΜ<sup>®</sup>, μΡFC<sup>®</sup>, AU-ConvertIR<sup>®</sup>, AURIX<sup>®</sup>, C166<sup>®</sup>, CanPAK<sup>®</sup>, CIPOS<sup>®</sup>, CIPURSE<sup>®</sup>, CoolDP<sup>®</sup>, CoolGaN<sup>®</sup>, COOLIR<sup>®</sup>, CoolSOS<sup>®</sup>, CoolSET<sup>®</sup>, CoolSiC<sup>®</sup>, DAVE<sup>®</sup>, DI-POL<sup>®</sup>, DirectFET<sup>®</sup>, DrBlade<sup>®</sup>, EasyPIM<sup>®</sup>, EconoBRIDGE<sup>®</sup>, EconoDUAL<sup>®</sup>, EconoPACK<sup>®</sup>, EconoPIM<sup>®</sup>, EiceDRIVER<sup>®</sup>, eupec<sup>®</sup>, FCOS<sup>®</sup>, GaNpowIR<sup>®</sup>, HEXFET<sup>®</sup>, HITFET<sup>®</sup>, HybridPACK<sup>®</sup>, iMOTION<sup>®</sup>, IRAM<sup>®</sup>, ISOFACE<sup>®</sup>, IsoPACK<sup>®</sup>, LEDrivIR<sup>®</sup>, LITIX<sup>®</sup>, MIPAQ<sup>®</sup>, ModSTACK<sup>®</sup>, my-d<sup>®</sup>, NovalithIC<sup>®</sup>, OPTIGA<sup>®</sup>, OptiMOS<sup>®</sup>, ORIGA<sup>®</sup>, PowIRaudio<sup>®</sup>, PowIRStage<sup>®</sup>, PrimePACK<sup>®</sup>, PrimeSTACK<sup>®</sup>, PROFET<sup>®</sup>, PRO-SIL<sup>®</sup>, RASIC<sup>®</sup>, REAL3<sup>®</sup>, SmartLEWIS<sup>®</sup>, SOLID FLASH<sup>®</sup>, SPOC<sup>®</sup>, StrongIRFET<sup>®</sup>, SupIRBuck<sup>®</sup>, TEMPFET<sup>®</sup>, TRENCHSTOP<sup>®</sup>, TriCore<sup>®</sup>, UHVIC<sup>®</sup>, XHP<sup>®</sup>, XMC<sup>®</sup>.

Trademarks Update 2015-12-22

#### **Other Trademarks**

All referenced product or service names and trademarks are the property of their respective owners.

Edition 2017-01-27 Published by Infineon Technologies AG 81726 Munich, Germany

© 2017 Infineon Technologies AG All Rights Reserved.

Do you have a question about any aspect of this document? Email: erratum@infineon.com

Document reference IFX-len1448356374413

#### **IMPORTANT NOTICE**

The information given in this document shall in no event be regarded as a guarantee of conditions or characteristics ("Beschaffenheitsgarantie").

With respect to any examples, hints or any typical values stated herein and/or any information regarding the application of the product, Infineon Technologies hereby disclaims any and all warranties and liabilities of any kind, including without limitation warranties of non-infringement of intellectual property rights of any third party.

In addition, any information given in this document is subject to customer's compliance with its obligations stated in this document and any applicable legal requirements, norms and standards concerning customer's products and any use of the product of Infineon Technologies in customer's applications.

The data contained in this document is exclusively intended for technically trained staff. It is the responsibility of customer's technical departments to evaluate the suitability of the product for the intended application and the completeness of the product information given in this document with respect to such application.

#### WARNINGS

Due to technical requirements products may contain dangerous substances. For information on the types in question please contact your nearest Infineon Technologies office.

Except as otherwise explicitly approved by Infineon Technologies in a written document signed by authorized representatives of Infineon Technologies, Infineon Technologies' products may not be used in any applications where a failure of the product or any consequences of the use thereof can reasonably be expected to result in personal injury